

On a Particular Case of the Bisymmetric Equation for Quasigroups

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Abstract

We characterize the solutions of the equation

$$D(G(x, y), G(u, v)) = G(D(x, u), T(y, v)), \quad (1)$$

where D , G and T are quasigroups. We also discuss the particular case when $D = T$.

1 Introduction and Notations

A *quasigroup* on a set Q is an operation $(\cdot) : Q \times Q \rightarrow Q$ such that for any $a, b \in Q$, there are unique x, y such that $a \cdot x = b$ and $y \cdot a = b$. In this paper, we use small letters for elements of Q and capital letters for quasigroups. We use greek letters for permutations on Q . If $x \in Q$ and α is a permutation on Q , we write $\alpha(x)$ for the image of x by α . We write $\beta\alpha$ for the composition of α and β , where α is applied first.

Two quasigroups \oplus and \otimes on a same set Q are *isotopic* if there exist three permutations α, β, γ of Q such that for any $x, y \in Q$, we have $x \otimes y = (x\alpha \oplus y\beta)\gamma^{-1}$. When $(Q, +)$ is an Abelian group and α is a permutation on Q , we say that α is *additive* for $+$ if for any $x, y \in Q$, we have $\alpha(x + y) = \alpha(x) + \alpha(y)$. When α and β are two permutations on the same set Q , we say that α and β commute if for all $x \in Q$, we have $\alpha\beta(x) = \beta\alpha(x)$.

Functional equations on quasigroups have been previously considered in [1, 2, 3]. In [1], Aczél, Belousov and Hosszú studied various quasigroup equations, including the generalized bisymmetry equation:

$$A(B(x, y), C(u, v)) = D(E(x, u), F(y, v)).$$

They showed that for any solution of this equation, all the quasigroups A, B, C, D, E, F are isotopic to the same Abelian group. Here, we show that the additional constraints $B = C = D$, $A = E$ imply some additivity and commutativity properties.

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2 Our Results

Let G, D, T satisfying (1). From Theorem 3 in Aczél, Belousov, Hosszú [1], there exist an Abelian group $+$ and 6 permutations $\psi, \epsilon, \delta, \varphi, \beta, \gamma$ such that:

$$G(x, y) = \psi(x) + \epsilon(y), \quad D(x, y) = \delta(x) + \varphi(y), \quad T(x, y) = \epsilon^{-1}(\beta(x) + \gamma(y)). \quad (2)$$

Let $-$ be such that $x + y = z \Leftrightarrow x = z - y$, and let e be the neutral element of $+$.

Proposition 1 *Let G, D, T be three quasigroups. These quasigroups satisfy*

$$D(G(x, y), G(u, v)) = G(D(x, u), T(y, v))$$

if and only if there exist an Abelian group $+$, two constants k_1, k_2 and four permutations $\hat{\psi}, \hat{\delta}, \hat{\varphi}, \epsilon$ such that the three permutations $\hat{\psi}, \hat{\delta}$ and $\hat{\varphi}$ are additive for $+$, the permutation $\hat{\psi}$ commutes with both $\hat{\delta}$ and $\hat{\varphi}$, and:

$$\begin{aligned} G(x, y) &= \hat{\psi}(x) + \epsilon(y) + k_1, \\ D(x, y) &= \hat{\delta}(x) + \hat{\varphi}(y) + k_2, \\ T(x, y) &= \epsilon^{-1} \left(\hat{\delta}\epsilon(x) + \hat{\varphi}\epsilon(y) + k_3 \right), \end{aligned}$$

where $k_3 := \hat{\delta}(k_1) + \hat{\varphi}(k_1) - k_1 + k_2 - \hat{\psi}(k_2)$.

When we additionally impose $T = D$, we get:

Proposition 2 *Let G, D be two quasigroups. These quasigroups satisfy:*

$$D(G(x, y), G(u, v)) = G(D(x, u), D(y, v)) \quad (3)$$

if and only if there exist an Abelian group $+$, two constants k_1, k_2 and four permutations $\hat{\psi}, \hat{\delta}, \hat{\varphi}, \hat{\epsilon}$, all of them additive for $+$, such that both $\hat{\psi}$ and $\hat{\epsilon}$ commute with both $\hat{\delta}$ and $\hat{\varphi}$:

$$\hat{\delta}(k_1) + \hat{\varphi}(k_1) + k_2 = \hat{\psi}(k_2) + \hat{\epsilon}(k_2) + k_1,$$

and:

$$\begin{aligned} G(x, y) &= \hat{\psi}(x) + \hat{\epsilon}(y) + k_1, \\ D(x, y) &= \hat{\delta}(x) + \hat{\varphi}(y) + k_2. \end{aligned}$$

3 Proof of Proposition 1

Proving that any G, D, T defined as in Proposition 1 satisfy Equation (1) is a straightforward check. We now prove that any solution of Equation (1) is as in Proposition 1.

From Equations (1) and (2), we get:

$$\delta(\psi(x) + \epsilon(y)) + \varphi(\psi(u) + \epsilon(v)) = \psi(\delta(x) + \varphi(u)) + \beta(y) + \gamma(v). \quad (4)$$

When $x = \psi^{-1}(e)$, Equation (4) gives:

$$\delta\epsilon(y) - \beta(y) = \psi(\delta\psi^{-1}(e) + \varphi(u)) + \gamma(v) - \varphi(\psi(u) + \epsilon(v)).$$

Since this equation must be satisfied for any y, u, v , the left and right terms must be equal to a constant value c_1 . We deduce:

$$\delta\epsilon(y) - \beta(y) = c_1. \quad (5)$$

Taking $y = \beta^{-1}(e)$, we get:

$$c_1 = \delta\epsilon\beta^{-1}(e).$$

Similarly when $u = \psi^{-1}(e)$, Equation (4) gives:

$$\varphi\epsilon(v) - \gamma(v) = \psi(\delta(x) + \varphi\psi^{-1}(e)) + \beta(y) - \delta(\psi(x) + \epsilon(y)),$$

hence:

$$\varphi\epsilon(v) - \gamma(v) = c_2, \quad (6)$$

where:

$$c_2 = \varphi\epsilon\gamma^{-1}(e).$$

Substituting Equations (5) and (6) in Equation (4), we get:

$$\delta(\psi(x) + \epsilon(y)) + \varphi(\psi(u) + \epsilon(v)) = \psi(\delta(x) + \varphi(u)) + \delta\epsilon(y) - c_1 + \varphi\epsilon(v) - c_2.$$

We deduce the following functional equation in δ, ψ and φ only:

$$\delta(\psi(x) + y) + \varphi(\psi(u) + v) = \psi(\delta(x) + \varphi(u)) + \delta(y) + \varphi(v) - c_1 - c_2. \quad (7)$$

Taking $v = e$ and $x = \delta^{-1}(e)$, we get:

$$\psi\varphi(u) - \varphi\psi(u) = \delta(\psi\delta^{-1}(e) + y) - \delta(y) - \varphi(e) + c_1 + c_2,$$

which implies:

$$\psi\varphi(u) - \varphi\psi(u) = c_3, \quad (8)$$

where:

$$c_3 = \psi\varphi\psi^{-1}\varphi^{-1}(e).$$

Similarly substituting $y = e$ and $u = \varphi^{-1}(e)$ in Equation (7), we get:

$$\psi\delta(x) - \delta\psi(x) = \varphi(\psi\varphi^{-1}(e) + v) - \delta(e) - \varphi(v) + c_1 + c_2,$$

which implies:

$$\psi\delta(x) - \delta\psi(x) = c_4, \quad (9)$$

where:

$$c_4 = \psi\delta\psi^{-1}\delta^{-1}(e).$$

Equation (7) may be re-written as:

$$\delta(\delta^{-1}(x) + \delta^{-1}(y)) + \varphi(\varphi^{-1}(u) + \varphi^{-1}(v)) = \psi(\delta\psi^{-1}\delta^{-1}(x) + \varphi\psi^{-1}\varphi^{-1}(u)) + y + v - c_1 - c_2.$$

Using Equations (8) and (9), this leads to:

$$\delta(\delta^{-1}(x) + \delta^{-1}(y)) + \varphi(\varphi^{-1}(u) + \varphi^{-1}(v)) = \psi(\psi^{-1}(x + c_4) + \psi^{-1}(u + c_3)) + y + v - c_1 - c_2. \quad (10)$$

Since $+$ is Abelian, we can swap x and y or u and v without changing the left-hand term of Equation (10). We therefore obtain the following functional equation in ψ only:

$$\psi(\psi^{-1}(x \oplus c_4) + \psi^{-1}(u \oplus c_3)) + y + v = \psi(\psi^{-1}(y \oplus c_4) + \psi^{-1}(v \oplus c_3)) + x + u.$$

Replacing x by $\psi(x) - c_4$, u by $\psi(u) - c_3$, y by $\psi(y) - c_4$ and v by $\psi(v) - c_3$, we get:

$$\psi(x + u) - \psi(x) - \psi(u) = \psi(y + v) - \psi(y) - \psi(v),$$

hence:

$$\psi(x \oplus u) - \psi(x) - \psi(u) = c_5, \quad (11)$$

for a constant c_5 such that:

$$c_5 = \psi(e + e) - \psi(e) - \psi(e) = e - \psi(e).$$

Using Equation (11), Equation (10) becomes:

$$\delta(\delta^{-1}(x) + \delta^{-1}(y)) + \varphi(\varphi^{-1}(u) + \varphi^{-1}(v)) = x + y + u + v + c_4 + c_3 - \psi(e) - c_1 - c_2,$$

or:

$$\delta(x + y) - \delta(x) - \delta(y) = \varphi(u) + \varphi(v) - \varphi(u + v) + c_4 + c_3 - \psi(e) - c_1 - c_2. \quad (12)$$

This implies:

$$\delta(x + y) - \delta(x) - \delta(y) = c_6, \quad (13)$$

where $c_6 = e \ominus \delta(e)$. On the other hand, Equation (12) also implies:

$$\varphi(u) + \varphi(v) - \varphi(u + v) = c_7, \quad (14)$$

where $c_7 = \varphi(e)$. Let now:

$$\hat{\psi} := \psi - \psi(e).$$

Equation (11) implies

$$\hat{\psi}(x \oplus u) = \psi(x \oplus u) - \psi(e) = \psi(x) + \psi(u) - 2\psi(e) = \hat{\psi}(x) + \hat{\psi}(u), \quad (15)$$

in other words $\hat{\psi}$ is additive for $+$. Similarly, Equations (13) and (14) imply that $\hat{\delta} := \delta - \delta(e)$ and $\hat{\varphi} := \varphi - \varphi(e)$ are additive. Equation (8) and the additivity of $\hat{\varphi}$ and $\hat{\psi}$ now imply:

$$\hat{\psi}\hat{\varphi}(u) + \hat{\psi}\varphi(e) + \psi(e) = \hat{\varphi}\hat{\psi}(u) + \hat{\varphi}\psi(e) + \varphi(e) + c_3.$$

For $u = e$, it follows that:

$$\hat{\psi}\varphi(e) + \psi(e) = \hat{\varphi}\psi(e) + \varphi(e) + c_3$$

hence Equation (8) eventually implies that:

$$\hat{\psi}\hat{\varphi}(u) = \hat{\varphi}\hat{\psi}(u),$$

in other words $\hat{\psi}$ and $\hat{\varphi}$ commute. Similarly, Equation (9) implies that $\hat{\psi}$ and $\hat{\delta}$ commute. By Equations (5) and (6), we have:

$$\beta(x) + \gamma(y) = \delta\epsilon(x) - c_1 + \varphi\epsilon(y) - c_2 = \hat{\delta}\epsilon(x) + \hat{\varphi}\epsilon(y) + \delta(e) + \varphi(e) - c_1 - c_2.$$

Defining $k_1 := \psi(e)$, $k_2 := \delta(e) + \varphi(e)$ and $k_3 := \delta(e) + \varphi(e) - c_1 - c_2$, we deduce from Equation (2) that:

$$\begin{aligned} G(x, y) &= \hat{\psi}(x) + \epsilon(y) + k_1, \\ D(x, y) &= \hat{\delta}(x) + \hat{\varphi}(y) + k_2, \\ T(x, y) &= \epsilon^{-1} \left(\hat{\delta}\epsilon(x) + \hat{\varphi}\epsilon(y) + k_3 \right), \end{aligned}$$

with $\hat{\psi}$, $\hat{\delta}$ and $\hat{\varphi}$ with the properties required. Using the additivity of $\hat{\delta}$, $\hat{\varphi}$ and $\hat{\psi}$, we compute:

$$\begin{aligned} D(G(x, y), G(u, v)) &= \hat{\delta} \left(\hat{\psi}(x) + \epsilon(y) + k_1 \right) + \hat{\varphi} \left(\hat{\psi}(u) + \epsilon(v) + k_1 \right) + k_2, \\ &= \hat{\delta}\hat{\psi}(x) + \hat{\delta}\epsilon(y) + \hat{\delta}(k_1) + \hat{\varphi}\hat{\psi}(u) + \hat{\varphi}\epsilon(v) + \hat{\varphi}(k_1) + k_2, \end{aligned}$$

and:

$$\begin{aligned} G(D(x, u), T(y, v)) &= \hat{\psi} \left(\hat{\delta}(x) + \hat{\varphi}(u) + k_2 \right) + (\hat{\delta}\epsilon(y) + \hat{\varphi}\epsilon(v) + k_3) + k_1, \\ &= \hat{\psi}\hat{\delta}(x) + \hat{\psi}\hat{\varphi}(u) + \hat{\psi}(k_2) + \hat{\delta}\epsilon(y) + \hat{\varphi}\epsilon(v) + k_3 + k_1. \end{aligned}$$

Since $\hat{\psi}$ commutes with both $\hat{\varphi}$ and $\hat{\delta}$, we deduce:

$$\begin{aligned} G(D(x, u), T(y, v)) &= \hat{\delta}\hat{\psi}(x) + \hat{\varphi}\hat{\psi}(u) + \hat{\psi}(k_2) + \hat{\delta}\epsilon(y) + \hat{\varphi}\epsilon(v) + k_3 + k_1, \\ &= D(G(x, y), G(u, v)) + \hat{\psi}(k_2) + k_3 + k_1 - \hat{\delta}(k_1) - \hat{\varphi}(k_1) - k_2. \end{aligned}$$

Equation (1) then implies:

$$k_3 = \hat{\delta}(k_1) + \hat{\varphi}(k_1) - k_1 + k_2 - \hat{\psi}(k_2).$$

This concludes the proof of Proposition 1.

4 Proof of Proposition 2

Proving that any G, D, T defined as in Proposition 2 satisfy Equation (3) is a straightforward check. We now prove that any solution of Equation (3) is as in Proposition 2. By Proposition 1, we have:

$$G(x, y) = \hat{\psi}(x) + \hat{\epsilon}(y) + k_1, \quad D(x, y) = \hat{\delta}(x) + \hat{\varphi}(y) + k_2$$

for permutations $\hat{\psi}, \hat{\delta}, \hat{\varphi}, \hat{\epsilon}$ such that $\hat{\psi}, \hat{\delta}$ and $\hat{\varphi}$ are additive for $+$, and moreover $\hat{\psi}$ commutes with both $\hat{\delta}$ and $\hat{\varphi}$. By symmetry of D and G in Equation (3), $\hat{\epsilon}$ must also be distributive for $+$ and it must commute with both $\hat{\delta}$ and $\hat{\varphi}$. As in the proof of Proposition 1, we compute:

$$D(G(x, y), G(u, v)) = \hat{\delta}\hat{\psi}(x) + \hat{\delta}\hat{\epsilon}(y) + \hat{\delta}(k_1) + \hat{\varphi}\hat{\psi}(u) + \hat{\varphi}\hat{\epsilon}(v) + \hat{\varphi}(k_1) + k_2.$$

Similarly, we have:

$$G(D(x, y), D(u, v)) = \hat{\psi}\hat{\delta}(x) + \hat{\psi}\hat{\varphi}(u) + \hat{\varphi}(k_2) + \hat{\epsilon}\hat{\delta}(y) + \hat{\epsilon}\hat{\varphi}(v) + \hat{\epsilon}(k_2) + k_1.$$

Equation (3) then leads to:

$$\hat{\delta}(k_1) + \hat{\varphi}(k_1) + k_2 = \hat{\psi}(k_2) + \hat{\epsilon}(k_2) + k_1.$$

This concludes the proof of Proposition 2.

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