A FAST ALGORITHM FOR COMPUTING A MINIMAL DECOMPOSITION OF A METABOLIC FLUX VECTOR IN TERMS OF ELEMENTARY FLUX VECTORS

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Abstract. The concept of elementary flux vector is valuable in a number of applications of metabolic engineering. For instance, in metabolic flux analysis, each admissible flux vector can be expressed as a non-negative linear combination of a small number of elementary flux vectors. However a critical issue concerns the number of elementary flux vectors which may be huge because it combinatorially increases with the size of the metabolic network. In this paper we present a fast algorithm that randomly computes admissible flux vectors having a minimal decomposition without explicitly enumerating all the elementary flux vectors of the network. The method is illustrated with an experimental case-study on CHO cells where the network has 65329 elementary flux vectors while the admissible flux distributions are expressed as a combination of 22 elementary vectors only.

1 Metabolic networks and elementary flux vectors

The intracellular metabolism of living cells is usually represented by a metabolic network under the form of a directed hypergraph that encodes a set of biochemical reactions taking place within the cell. In this hypergraph, the nodes represent the metabolites and the edges represent the metabolic fluxes.

According to the quasi steady-state paradigm of metabolic flux analysis (MFA) (e.g. [10]), it is assumed that the fluxes are balanced at each internal node. This means that the net sum of production and consumption fluxes, weighted by their stoichiometric coefficients, is zero for each internal metabolite of the network. This is expressed by the algebraic relation:

$$\mathbf{N}\mathbf{v} = \mathbf{0} \qquad \mathbf{v} \geqslant \mathbf{0} \tag{1}$$

where $\mathbf{v} = (v_1, v_2, \dots, v_m)^T$ is the *m*-dimensional column vector of fluxes and $\mathbf{N} = [n_{ij}]$ is the $n \times m$ stoichiometric matrix of the metabolic network (*m* is the number of fluxes and *n* the number of internal nodes of the network). More precisely, a flux v_j denotes the rate of reaction *j* and a non-zero n_{ij} is the stoichiometric coefficient of the metabolite *i* in reaction *j*.

For a given metabolic network, the set *S* of possible flux distributions is the set of vectors **v** that satisfy the linear system (1). This set *S* is the pointed polyhedral cone resulting from the intersection of the kernel of **N** with the nonnegative orthant. This implies that there exists a set of elementary flux vectors \mathbf{e}_i ([11]) which are the edges (or extremal rays) of the polyhedral cone and such that any flux distribution **v** can be expressed as a non-negative linear combination of the vectors \mathbf{e}_i which form therefore a *unique* convex basis (see e.g. [12]) of the flux space *S*:

$$\mathbf{v} = w_1 \mathbf{e}_1 + w_2 \mathbf{e}_2 + \dots + w_a \mathbf{e}_a \quad w_i \ge 0.$$

The $m \times q$ non-negative matrix **E** with column vectors \mathbf{e}_i obviously satisfies $\mathbf{NE} = 0$ and (2) can be written in matrix form as

$$\mathbf{v} = \mathbf{E}\mathbf{w} \text{ with } \mathbf{w} \triangleq (w_1, w_2, \dots, w_q)^T.$$
 (3)

2 Metabolic flux analysis

Metabolic flux analysis (MFA) is the exercise of calculating the admissible flux distributions v that satisfy the steady state balance equation Nv = 0 together with an additional set of linear constraints added by using experimental measurements. Here we consider the case where the measurements are collected in a vector v_m which is a linear function of the unknown flux distribution v and is expressed as

$$\mathbf{v}_m = \mathbf{P}\mathbf{v} \tag{4}$$

where **P** is a given $p \times m$ full-rank matrix. In addition, it is assumed that $\mathbf{Pe}_i \neq 0 \forall i$ or, in other terms, that the elementary flux vectors \mathbf{e}_i do not belong to the kernel of the matrix **P**. Then, from equations (1)-(4), we have the following fundamental equation of metabolic flux analysis

$$\Sigma\begin{pmatrix}\mathbf{v}\\1\end{pmatrix} = \mathbf{0} \text{ with } \Sigma \triangleq \begin{pmatrix}\mathbf{N} & \mathbf{0}\\\mathbf{P} & -\mathbf{v}_m\end{pmatrix} \text{ and } \mathbf{v} \ge \mathbf{0}.$$
 (5)

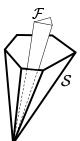


Figure 1: Illustration of the flux spaces *S* and \mathscr{F} .

For a given metabolic network and a given set of measurements, the solution of the MFA problem is defined as the set \mathscr{F} of admissible flux distributions i.e. the set of non-negative vectors **v** that satisfy the homogeneous linear system (5). Each admissible **v** must be such that the non-negative vector $(\mathbf{v}^T 1)^T$ belongs to the kernel of the matrix Σ . Hence, as emphasized in [7, Chapter 4]-[8], the set \mathscr{F} is a polytope in the positive orthant \mathbb{R}^m_+ . This means that any admissible flux distribution **v** can be expressed as a convex combination of a set of non-negative basis vectors **f**_i which are the vertices of this polytope and form therefore a *unique* convex basis of the flux space \mathscr{F} . In other words, the solution of the MFA problem is the *admissible flux space* \mathscr{F} defined as

$$\mathscr{F} \triangleq \big\{ \mathbf{v} : \mathbf{v} = \sum_{i} \alpha_{i} \mathbf{f}_{i}, \ \alpha_{i} \ge 0, \ \sum_{i} \alpha_{i} = 1 \big\}.$$
(6)

The admissible flux space \mathscr{F} is a subset of the possible flux space *S*. In geometric terms, the polytope \mathscr{F} defines a subcone of the pointed cone *S* as illustrated in Fig.1.

3 Minimal decomposition of $\mathbf{v} \in \mathscr{F}$ in terms of elementary vectors \mathbf{e}_i

For any admissible flux vector **v** in the polytope \mathscr{F} satisfying equation (5), it must be emphasized that the decomposition of **v** in the convex basis $\{\mathbf{e}_i\}$ is **not** unique. Our aim is to determine minimal decompositions which can be useful in pratical applications of MFA. Using (3), system (5) is equivalent to the system:

$$\begin{pmatrix} \mathbf{NE} \\ \mathbf{PE} \end{pmatrix} \mathbf{w} = \begin{pmatrix} \mathbf{0} \\ \mathbf{v}_m \end{pmatrix} \quad \mathbf{w} \ge \mathbf{0}.$$
(7)

We observe that the first equation NEw = 0 is trivially satisfied independently of w since by definition NE = 0. Hence, system (7) may be reduced to the second equation:

$$\mathbf{PEw} = \mathbf{v}_m \quad \mathbf{w} \ge \mathbf{0}$$

or equivalently:

$$\begin{pmatrix} \mathbf{PE} & -\mathbf{v}_m \end{pmatrix} \begin{pmatrix} \mathbf{w} \\ 1 \end{pmatrix} = 0 \quad \mathbf{w} \ge \mathbf{0}.$$
 (8)

In this form, it is clear that the set of admissible weighting vectors **w** that satisfy (8) again constitutes a convex polytope that we denote \mathcal{H} . Therefore there exists a set of appropriate edge vectors \mathbf{h}_i such that any arbitrary convex combination of the form:

$$\mathbf{w} = \sum_{i} \beta_{i} \mathbf{h}_{i} \quad \beta_{i} \ge 0 \quad \sum_{i} \beta_{i} = 1$$
(9)

is necessarily an admissible **w** satisfying (8). The convex basis vectors \mathbf{h}_i have a critical property : the number of non-zero entries is equal to the size p of the vector \mathbf{v}_m i.e. the number of measurements (see [3] and Section 3.5 in [7]). From a metabolic viewpoint, each vector \mathbf{h}_i is a particular solution **w** of (8) corresponding to an admissible flux distribution **v**:

$$\mathbf{v} = \mathbf{E}\mathbf{h}_i \quad \mathbf{v} \in \mathscr{F} \tag{10}$$

In this expression, the non-zero entries of the vector \mathbf{h}_i are interpreted as the weights of the respective contributions of the corresponding elementary flux vectors \mathbf{e}_i in the computation of the flux distribution \mathbf{v} .

An important issue concerns the number of distinct extremal rays or vertices that are generated when computing the cone S or the polytopes \mathscr{F} and \mathscr{H} . This number may become very large because it combinatorially increases with the size of the underlying metabolic network. The Double Description (DD) method ([6]) is the simplest known algorithm for enumerating the extremal rays of a polyhedral cone (see [3] for a review). In the context of metabolic networks it has received various dedicated improvements that are documented in the literature (see e.g. [9], [4] and [5]). In practical applications of MFA, the enumeration of all extremal rays is not necessarily a

critical objective. In many applications it is sufficient to know only one minimal decomposition of some vectors $\mathbf{v} \in \mathscr{F}$ in terms of elementary vectors \mathbf{e}_i . It clearly follows from our analysis that such a minimal decomposition involves ℓ terms with $p \leq \ell \leq (m-n)$. Furthermore, according to (10) there necessarily exist admissible \mathbf{v} having a decomposition that involves only p terms. Computing this decomposition may be very expensive at first sight since the dimension of \mathbf{E} is not bounded by a polynomial in the sizes of \mathbf{N} and \mathbf{P} .

In this paper we present a fast algorithm that randomly computes vectors $\mathbf{v} \in \mathscr{F}$ having such a minimal decomposition from the sole knowledge of the stoichiometric matrices \mathbf{N} , \mathbf{P} and the measurement vector \mathbf{v}_m but without explicitly enumerating the extremal rays of the cone *S* (i.e. the columns of the huge matrix \mathbf{E}) and therefore without solving the system (8).

4 The algorithm

Let us first consider the following simple problem: We are given a vector \mathbf{v} that belongs to a cone S, and we would like to express this vector as a linear combination of a few extremal rays of S.

Let us denote $a = \mathbf{u}^T \mathbf{v}$ the sum of the entries in \mathbf{v} (\mathbf{u} denotes the vector whose all entries are equal to one). In the following we will consider without loss of generality the slightly different problem where we are looking for extremal rays \mathbf{e}_i such that $\mathbf{u}^T \mathbf{e}_i = a$. Geometrically speaking, we cut the cone with a plane passing through \mathbf{v} such that the intersection is a bounded polytope whose vertices correspond to extremal rays of the initial cone *S*. We are thus given a (bounded) polytope, and a vector \mathbf{v} in this polytope and we want to express this vector \mathbf{v} as a convex combination of vertices of the polytope.

The algorithm essentially relies on two observations: first, we do not need to know all the extremal rays, what we only need is a (small) subset, to express v as a convex combination of them. Second, all the constraints defining the different cones are linear, and so we can make use of Linear Programming (e.g. [2]). More precisely, the problem of finding a vertex of the polytope defined by the equations

$$\mathbf{M}\mathbf{x} = \mathbf{0}, \quad \mathbf{u}^T \mathbf{x} = a, \quad \mathbf{x} \ge \mathbf{0}$$

can be done in time polynomial in the number of constraints and the dimension. Indeed, consider the following linear program :

min
$$\mathbf{d}^T \mathbf{x}$$

s.t.
 $\mathbf{M}\mathbf{x} = \mathbf{0},$ (11)
 $\mathbf{x} \ge \mathbf{0},$
 $\mathbf{u}^T \mathbf{x} = a.$

If \mathbf{d} is not parallel to a constraint of the program (11), then, the solution is a vertex of the corresponding polytope (see for instance [2]). So in practice, if \mathbf{d} is a random direction, an extremal ray is found with probability one.

Let us now present our algorithm which proceeds iteratively by projecting v on faces \mathcal{P}_i of the polytope \mathcal{P} described by the constraints of the program (11). Since the dimension of the faces \mathcal{P}_i strictly decreases at each step, the algorithm takes at most k - 1 steps, where k is the dimension of the cone S.

Take any extremal ray \mathbf{e}_1 of the cone *S* (for instance by solving the linear program (11)); then the vector \mathbf{v} can be written as the convex combination of \mathbf{e}_1 and of a vector \mathbf{v}_1 , which belongs to a face \mathscr{P}_1 of *S*: $\mathbf{v} = \gamma_1 \mathbf{e}_1 + (1 - \gamma_1)\mathbf{v}_1$. These quantities \mathbf{v}_i, γ_i are easy to compute, as \mathbf{v}_1 is the solution \mathbf{x}^* of the Linear Program

$$\max \mu$$

s.t.
$$\mathbf{M}\mathbf{x} = \mathbf{0}, \qquad (12)$$
$$\mathbf{x} \ge \mathbf{0}, \qquad \mathbf{u}^{T}\mathbf{x} = a, \qquad \mathbf{v} + \mu(\mathbf{v} - \mathbf{e}_{1}) = \mathbf{x}.$$

The geometric meaning of this linear program is as follows: starting fom the vector \mathbf{v} one tries to find a point \mathbf{x} which is diametrically opposite to \mathbf{e}_1 and as far as possible from \mathbf{v} . Clearly this point will be on a face of the polytope (because if it is not, it is possible to go further). Here μ represents the distance from \mathbf{v} to \mathbf{x} .

Now \mathscr{P}_i is a new polyhedron, and we still can express \mathbf{v}_i as a convex combination of a vertex of \mathscr{P}_i (which is also a vertex of S) and a point \mathbf{v}_{i+1} that belongs to a face \mathscr{P}_{i+1} of \mathscr{P}_i (which is also a face of S, but of dimension

strictly smaller than dim \mathcal{P}_i). Thus, after $k' \leq k-1$ steps, the dimension of $\mathcal{P}_{k'}$ is equal to 0, which means that $\mathbf{v}_{k'}$ is actually a vertex of \mathcal{P} which we denote $\mathbf{e}_{k'+1}$. Thus, $\mathbf{v}_{k'-1} = \gamma_{k'} \mathbf{e}_{k'} + (1 - \gamma_{k'}) \mathbf{e}_{k'+1}$. Finally we can write:

$$\begin{aligned} \mathbf{v} &= \mathbf{v}_{0} \\ &= \gamma_{1} \mathbf{e}_{1} + (1 - \gamma_{1})(\gamma_{2} \mathbf{e}_{2} + (1 - \gamma_{2})(\dots(\gamma_{k'} \mathbf{e}_{k'} + (1 - \gamma_{k'})\mathbf{e}_{k'+1}))) \\ &= \sum_{1}^{k'+1} w_{i} \mathbf{e}_{i}, \end{aligned}$$

with $\sum w_i = 1$. Finally, as the dimension of the cone *S* is equal to k = m - n, we obtain at most m - n extremal vectors \mathbf{e}_i . We have thus found the decomposition in polynomial time, which is a dramatic improvement compared to the naive brute force approach that requires the enumeration of all vectors \mathbf{e}_i .

We now would like to express a vector \mathbf{v} in \mathscr{F} (that is a vector compatible with the measurements in \mathbf{v}_m) as a linear combination of extremal rays of S. Moreover we would like to minimize the number of extremal rays in this expression. Equation (9) and the remark below ensure us that there is such a vector \mathbf{v} that can be expressed as a combination of only p extremal rays \mathbf{e}_i of S. To see this, consider the expression (8) of the polytope \mathscr{H} , which describes the set of admissible values of \mathbf{w} . It can be defined by only p equalities, so that $dim(\mathbf{w}) - p$ inequality constraints can be activated to define an extremal ray \mathbf{h}_i of \mathscr{H} . In conclusion, there are admissible vectors \mathbf{w} (the extremal rays of \mathscr{H}), that only contain at most p nonzero values. However, if one does not want to compute the matrix \mathbf{E} of extremal rays of S, this is not an easy task a priori to find such a minimal representation. Indeed, the dimension of \mathbf{w} is exponential in the size of the problem.

In order to compute such a "good" vector **v** and its corresponding decomposition, we introduce yet another cone $\mathscr{K} \subset \mathbb{R}^p$. This cone is the projection of *S* by the matrix **P**:

$$\mathscr{K} = \{ \mathbf{y} = \mathbf{P}\mathbf{v} : \mathbf{v} \ge \mathbf{0}, \mathbf{N}\mathbf{v} = \mathbf{0} \}.$$

The idea of the algorithm is as follows: We know that the vector \mathbf{v}_m is in \mathcal{H} , and we will express this vector as a convex combination of p vectors, which are the projection of extremal rays \mathbf{e}_i under the matrix \mathbf{P} . We start from an extremal ray \mathbf{e}_1 of the cone \mathscr{F} (for instance by applying the Linear Program (11)); then the vector $\mathbf{v}_m = \mathbf{y}_0$ can be written as the convex combination of \mathbf{Pe}_1 and a vector \mathbf{y}_1 , which belongs to a face \mathbf{P}_1 of \mathscr{H} : $\mathbf{v}_m = \alpha_1 \mathbf{Pe}_1 + (1 - \alpha_1)\mathbf{y}_1$. This vector \mathbf{v}_1 is easy to find with a line search in the cone \mathscr{H} as in Program (12). Now, at each step, find an extremal ray \mathbf{e}_i of \mathscr{H} which is mapped to a face \mathbf{P}_{i-1} of \mathscr{H} . Then \mathbf{y}_{i-1} can be expressed as a convex combination of \mathbf{Pe}_i and a vector \mathbf{y}_i that belongs to a face \mathbf{P}_i of \mathbf{P}_{i-1} . Since the dimension of \mathbf{P}_i strictly decreases at each step, after $t \leq p$ steps the point \mathbf{y}_t is actually an extremal ray of \mathscr{H} , and is thus the projection of an extremal ray $\mathbf{e}_{(t+1)}$ of S. Finally we have the relations:

$$\mathbf{v}_m = \sum_{1}^{t} \lambda_i \mathbf{P} \mathbf{e}_i = \mathbf{P}(\sum_{1}^{t} \lambda_i \mathbf{e}_i), \tag{13}$$

and thus the vector

$$\mathbf{v} = \sum_{1}^{t} \lambda_i \mathbf{e}_i$$

is a convex combination of at most p extremal vectors of S that satisfies (5).

5 Case study

As a matter of illustration and motivation to the methodology presented above, we consider the example of chinese hamster ovary (CHO) cells cultivated in batch mode in stirred flasks in a serum-free medium ([1]). During the growth phase, we assume that the cell metabolism is described by the metabolic network presented in Appendix A. The network involves the Glycolysis pathway, the Pentose-Phosphate pathway, the Krebs cycle, the amino-acid metabolism, the urea cycle as well as the nucleotide, protein and lipid synthesis (see [13] for further motivation and details).

For this network we have m = 82 fluxes and n = 53 internal metabolites, and there are 65329 elementary flux vectors \mathbf{e}_i (i.e the polyhedral cone *S* has 65329 edges).

Moreover, there are p = 22 extra-cellular species whose degradation or accumulation rates in the culture medium are measured and collected in the vector \mathbf{v}_m given in Table 1.

The algorithm of Section 4 is then implemented with these data. We present a trial where the resulting admissible flux vector \mathbf{v} is given in Table 2. It can be checked to satisfy (5) and to be is fully consistent with the experimental

Glucose	-0,187130	Glutamine	-0,050246
Threonine	-0,001184	Lysine	-0,002125
Valine	-0,001956	Isoleucine	-0,001528
Leucine	-0,002601	Phenylalanine	-0,000998
Methionine	-0,000724	Asparagine	-0,001278
Arginine	-0,002142	Proline	-0,002142
Histidine	-0,003298	Tyrosine	-0,007610
Aspartate	-0,000318	Cysteine	-0,000923
Glycine	0,002230	Serine	-0,000923
Glutamate	-0,009548	Ammonia	0,045712
Lactate	0,344510	Alanine	0,008808

Table 1: Vector of measurements \mathbf{v}_m (mM/(h × 10⁹ cells)), with a "-" sign for degradation and a "+" sign for accumulation.

data of Table 1. Furthermore, the algorithm provides the minimal decomposition of \mathbf{v} as a non-negative linear combination of the 22 elementary flux vectors \mathbf{e}_i given in Tables 3 and 4.

Let us insist that the obtained vector \mathbf{v} is obviously just one possible solution among many others with a minimal decomposition. If the algorithm is re-run with the same initial data, it will find other solutions with a minimal decomposition because it makes use of random searching directions. Complementary results on the metabolic flux analysis of CHO cells can be found in the companion paper [13].

6 References

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Appendix A. Metabolic network.

Glycolisis v1: Glu + ATP \rightarrow G6P + ADP v2: $G6P + ATP \rightarrow DHAP + G3P + ADP$ v3: DHAP \rightarrow G3P v4: G3P + OxP + P_i + ADP \rightarrow (3)PG + RdP + ATP v5: (3)PG + ADP \rightarrow Pyr + ATP Krebs Cycle v6:Pyr + OxP \rightarrow AcCoA + CO₂ + RdP v7:AcCoA + Oxal \rightarrow Cit v8:Cit + OxP $\rightarrow \alpha KG$ + CO₂ + RdP $v9:\alpha KG + OxP \rightarrow SucCoA + CO_2 + RdP$ v10:SucCoA + ADP + $P_i \rightarrow$ Succ + ATP v11:Succ \rightarrow Fum $v12{:}Fum \rightarrow Mal$ v13:Mal + OxP \rightarrow Oxal + RdP Pyruvate Fates v14:Pyr + RdP \rightarrow Lact + OxP v15:Pyr + Glu \rightarrow Ala + α KG Pentose Phosphate Pathway v16: G6P+ 2 OxP \rightarrow R5P+ 2 RdP+CO₂ v17: 3 R5P \rightarrow 2.5 G6P+ 0.5 P_i Anaplerotic Reaction v18: Mal+ OxP \rightarrow Pyr+ CO₂+RdP Amino Acid Metabolism v19:Glu + OxP $\rightarrow \alpha KG + NH_4^+ + RdP$ v20:Oxal + Glu \rightarrow Asp + α KG v21: Gln \rightarrow Glu + NH₄⁺ v22: Thr+OxP \rightarrow Gly+AcCoA+RdP v23: Gly+ OxP \rightarrow CO₂ + NH₄⁺ +RdP v24: (3)PG + OxP + Glu \rightarrow Ser + α KG + RdP + P_i v25: Ser \rightarrow Gly v26: Ser \rightarrow Pyr + NH₄⁺ v27: Thr $\rightarrow \alpha Kb + NH_4^+$ v28: α Kb + OxP \rightarrow PropCoA + RdP +CO₂ v29: PropCoA + CO₂ +ATP \rightarrow SucCoA +ADP + P_i v30: Lys + 2 α KG + OxP $\rightarrow \alpha$ Ka + 2 Glu +RdP v31: α Ka + 2 OxP \rightarrow AcetoAcCoA + 2 RdP + 2 CO₂ v32: AcetoAcCoA \rightarrow 2 AcCoA v33: Val + $\alpha KG \rightarrow \alpha Kv$ + Glu v34: $\alpha Kv + 3 OxP \rightarrow PropCoA + 2 CO_2 + 3 RdP$ v35: Ile + $\alpha KG \rightarrow (3)$ Methyl(2)oxovalerate+Glu v36: (3)Methyl(2)oxovalerate+ 2 $OxP \rightarrow AcCoA + PropCoA + CO_2 + 2 RdP$ v37: Leu + $\alpha KG \rightarrow \alpha Ki$ + Glu v38: α Ki + OxP + ATP \rightarrow AcCoA + AcetoAc + RdP + ADP + P_i v39: AcetoAc + SucCoA \rightarrow AcetoAcCoA + Succ v40: Phe + RdP \rightarrow Tyr + OxP v41: Tyr + α KG \rightarrow Fum + Glu + AcetoAc +CO₂ v42: Met + ATP \rightarrow HomoCys + AMP + P_i v43: HomoCys + Ser $\rightarrow \alpha$ Kb + Cys + NH₄⁺ v44: Cys \rightarrow Pyr + NH₄⁺ v45: Asn \rightarrow Asp + NH₄⁺ v46: Arg \rightarrow Ornitine + Urea v47: Ornitine + $\alpha KG \rightarrow Glu\gamma SA + Glu$ v48: Pro \rightarrow Glu γ SA v49: $Glu\gamma SA + OxP \rightarrow Glu + RdP$ v50: His \rightarrow Glu + NH₄⁺ v51: Asp_{ext} \rightarrow Asp v52: $Cys_{ext} \rightarrow Cys$

v53: Gly \rightarrow Gly_{ext} v54: Ser_{ext} \rightarrow Ser v55: $Glu_{ext} \rightarrow Glu$ v56: Tyr_{ext} \rightarrow Tyr v57: Ala \rightarrow Ala_{ext}

Protein Synthesis

v10

v11

v12

v13

v14

v15

v16 v17

v18

0.06109

0.07202

0.09943

0.02953

0.34451

0.00894

0.10879

0.02823

0.06988

v30

v31

v32

v33

v34

v35

v36

v37

v38

0.00202

0.00202

0.01145

0.00184

0.00184

0.00144

0.00144

0.00244

0.00244

v50

v51

v52

v53

v54

v55

v56

v57

v58

0.00326

0.00023

0.00089

0.00235

0.00013

0.00944

0.00755

0.00881

0.00173

v70

v71

v72

v73

v74

v75

v76

v77

v78

0.00518

0.02411

0.00129

0.00129

0.00129

0.00046

0.00096

0.00013

0.00013

v58:0.023 His +0.053Ile +0.091 Leu + 0.059 Lys + 0.023Met + 0.039Phe + 0.059Thr + 0.014Trp + 0.066Val + 0.051Arg + 0.019 Cys + 0.042 Gln+ 0.072 Gly+ 0.052 Pro+ 0.032Tyr+ 0.78Ala +0.043 Asn + 0.053 Asp +0.063 Glu + 0.068 Ser + 3 ATP \rightarrow Protein + AMP + Pp_i + 2 ADP + 2P_i Nucleotide Synthesis v59: R5P + ATP \rightarrow PRPP + AMP v60: PRPP+ 2 Gln +Asp +Gly +4 ATP+ CO₂ \rightarrow IMP + 2 Glu + Fum + 4 ADP+4 P_i+ Pp_i v61: IMP +Asp + 3ATP \rightarrow ATP_{RN} +Fum + 3ADP + P_i v62: IMP +Gln + 3ATP + OxP \rightarrow GTP_{RN} + Glu + 2ADP + AMP + Pp_i + RdP v63: $CO_2 + NH_4^+ + Asp + 2 ATP + OxP \rightarrow Orotate + RdP + 2ADP + 2P_i$ v64: Orotate + PRPP + ATP \rightarrow UTP_{RN} +CO₂ + 2ADP + Ppi v65: UTP_{RN} + Gln + ATP \rightarrow CTP_{RN} + Glu + ADP + P_i v66: 0.285 ATP_{RN} + 0.285 UTP_{RN} + 0.215 GTP_{RN} + 0.215 CTP_{RN} \rightarrow RNA v67: ATP_{RN} \rightarrow dATP v68: $\text{GTP}_{RN} \rightarrow \text{dGTP}$ v69: UTP_{RN} \rightarrow dTTP v70: $CTP_{RN} \rightarrow dCTP$ v71: 0.285 dATP + 0.285 dTTP + 0.215 dGTP + 0.215 dCTP \rightarrow DNA Lipid Synthesis v72: DHAP +RdP \rightarrow Glyc3P + OxP v73: Glyc3P + 18 AcCoA + 21 ATP + 33 RdP \rightarrow PA + 16 (ADP +P_i) + 33 OxP + 5 (AMP + P_i) v74: PA \rightarrow (1,2)DG +P_i v75: Eth + (1,2)DG + 2 ATP \rightarrow PE + ADP+ P_i + AMP + Pp_i v76: Chol + 1,2)DG + 2 ATP \rightarrow PC + ADP+ P_i + AMP + Pp_i v77: PE + Ser \rightarrow PS + Eth v78: 8 AcCoA + 8 ATP + 15 RdP + Ser \rightarrow Sphg + 7(ADP + P_i) + 15 OxP + CO₂ + AMP + Pp_i v79: Sphg + 8 AcCoA + 8 ATP + 14 RdP \rightarrow Cer + 7(ADP + P_i) + 14 OxP + AMP + Pp_i v80: Cer + PC \rightarrow SM + (1,2)DG v81: 6 AcetoAcCoA + 6 AcCoA + 18 ATP+ 14 RdP \rightarrow Cholesterol + 14 OxP+ 18 ADP + 4 Pp_i $+ 6P_i + 6 CO_2$ v82: 0.5 PC + 0.2 PE + 0.075 PS + 0.075 SM+0.15 Cholesterol \rightarrow Membrane Lipid 0.18713 v21 0.01570 v41 0.00849 v61 0.00687 v81 0.00025 v1 0.14891 0.00068 0.00518 0.00167 v2 v22 0.00000 v42 v62 v82 v3 0.14762 v23 0.00000 v43 0.00068 v63 0.01205 v4 0.29653 v24 0.04879 v44 0.00157 v64 0.01205 v5 0.24774 v25 0.01440 v45 0.00120 v65 0.00518 0.03426 0.00000 0.00205 v6 v26 v46 v66 0.00000 v7 0.00000 v27 0.00108 v47 0.00205 v67 0.00687 0.00000 v28 0.00176 v48 0.00205 v68 v8 0.00518 v29 v49 v9 0.06698 0.00504 0.00410 v69 0.00687

v19 0.00000 v39 0.01093 v59 0.02411 v79 0.00013 v20 v40 0.02955 0.00093 v60 0.01205 v80 0.00013 Table 2: A vector v of admissible metabolic flux rates ($mM/(h \times 10^9 \text{ cells})$) consistent with the metabolic network and the experimental data of Table 1.

e22	23.93	9.98	9.98	19.95	0	0	0	0	19.95	19.95	19.95	30.91	0	43.88	0	13.95	0	30.91	0	0	0	0	0	19.95	6.98	12.98	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
e21	m	e	e	9	0	0	0	0	9	9	9	9	0	12	0	0	0	9	0	0	0	0		9																0	0
e20	m	ю	e	9	0	0	0	0	9	9	9	9	0	12	0	0	0	9	0	0	9	0	0	9	0	9	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
e19	m	e	ŝ	9	0	0	0	0	0	9	9	9	0	12	0	0	0	9	0	0	0	0	0	9	0	9	0	0	9	0	0	0	9	9	0	0	0	0	0	0	0
e18	354.5	354.5	323.5	678	0	0	0	0	0	606	642	678	0	1350	0	0	0	678	0	0	0	0	0	678	0	672	0	0	642	0	0	0	0	0	642	642	0	0	36	36	36
e17	23.93	9.98	9.98	19.95	0	0	0	0	19.95	19.95	19.95	30.91	0	43.88	0	13.95	0	30.91	0	0	0	0	0	19.95	6.98	12.98	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
e16	17.44	3.49	3.49	6.98	0	0	0	0	24.91	24.91	24.91	35.86	17.93	17.93	0	13.95	0	17.93	0	17.93	4.95	0	0	6.98	6.98	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
e15	m	ε	ε	9	0	0	0	0	9	9	9	9	0	12	0	0	0	9	0	0	0	0	0	9	0	9	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
e14	1254.42	265.68	234.68	500.37	0	0	0	0	1413.89	1056.89	1413.89	2547.04	1270.52	1276.52	0	988.73	0	1276.52	0	1270.52	0	0	0	500.37	494.37	0	0	0	0	0	0	321	0	0	0	0	0	0	357	357	357
e13	253.5	253.5	222.5	476	0	0	0	0	238	0	238	238	0	708	0	0	0	238	0	0	0	0	0	476	0	470	0	0	0	0	0	202	0	0	0	0	238	238	238	0	0
e12	461.75	212.1	181.1	393.2	0	0	0	0	357	0	357	909.98	320.8	851.55	0	249.65	0	589.17	0	320.8	0	0	0	393.2	124.83	262.37	0	0	0	0	0	321	0	0	0	0	0	0	357	0	357
e11	372.5	372.5	341.5	714	0	0	0	0	0	0	0	0	0	708	0	0	0	0	0	0	0	0	0	714	0	708	0	0	0	357	357	321	0	0	0	0	0	0	0	0	0
e10	134.5	134.5	103.5	238	0	0	0	0	0	0	238	238	0	470	0	0	0	238	0	0	0	0	0	238	0	232	238	238	238	0	0	202	0	0	0	0	238	238	238	0	0
eo	372.5	372.5	341.5	714	0	0	0	0	357	0	357	714	0	1422	0	0	0	714	0	0	0	0	0	714	0	708	0	0	0	0	0	321	0	0	0	0	0	0	357	0	357
e ₈	551	551	520	1071	0	0	0	0	357	0	357	714	0	1779	0	0	0	714	0	0	0	0	0	1071	0	1065	0	0	0	0	0	321	0	0	0	0	0	0	357	0	357
еŢ	ŝ	e	e	9	0	0	0	0	9	9	9	9	0	9	0	0	0	9	0	0	0	0	0	9	9	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
e6	ε	Э	Э	9	9	0	0	0	0	0	0	0	0	9	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
es	134.5	134.5	103.5	238	0	0	0	0	0	0	238	238	0	476	0	0	0	238	0	0	0	0	0	238	232	0	0	238	238	0	0	202	0	0	0	0	238	238	238	0	0
e4	0	0	0	0	0	0	0	0	0	0	0	0	0	e	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
e3	0	0	0	0	0	0	0	0	С	С	e	З	0	0	ŝ	0	0	ŝ	0	0	ŝ	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
e2	m	0	0	0	0	0	0	0	0	0	0	0	0	0	0	18	9	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
e1	31	31	0	31	31	0	0	0	0	0	0	0	0	0	714	0	0	0	0	0	0	0	0	0	0	683	0	0	0	357	357	321	0	0	0	0	0	0	0	0	0
	v1	v2	v3	44	v5	v6	٢٧	v8	6v	v10	v11	v12	v13	v14	v15	v16	v17	v18	v19	v20	v21	v22	v23	v24	v25	v26	v27	v28	v29	v30	v31	v32	v33	v34	v35	v36	v37	v38	v39	v40	v41

Table 3: Elementary vectors \mathbf{e}_i (first 41 entries) of the minimal decomposition of the flux vector \mathbf{v} of Table 2. The integer entries are exact stoichiometric coefficients. The other entries are truncated to the 2nd decimal.

	e1	•	e3	e4	es	e6	е7	e8	69	e10	e11	e12	e13	e14	e15	e16	e17	e18	elo	e20	e21	e22
v42	0		0	0	238	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
v43	0		0	0	238	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
v44	0		0	С	238	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
v45	0		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17.93
v46	0		0	0	0	0	0	357	0	0	0	0	0	0	0	0	0	0	0	0	0	0
v47	0		0	0	0	0	0	357	0	0	0	0	0	0	0	0	0	0	0	0	0	0
v48	0		0	0	0	0	9	0	357	0	0	0	0	0	0	0	0	0	0	0	0	0
v49	0		0	0	0	0	9	357	357	0	0	0	0	0	0	0	0	0	0	0	0	0
v50	0		0	0	0	0	0	0	0	0	0	0	238	0	0	0	0	0	0	0	9	0
v51	0		0	0	0	0	0	0	0	0	0	0	0	0	0	0	17.93	0	0	0	0	0
v52	0		0	С	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
v53	0		0	0	232	0	9	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
v54	689		0	0	0	0	0	0	0	0		0	0	0	0	0	0	0	0	0	0	0
v55	0		0	0	0	0	0	0	0	0		0	0	0	9	0	0	0	0	0	0	0
v56	0		0	0	0	0	0	357	357	0		357	0	0	0	0	0	0	0	0	0	0
v57	0		e	0	0	0	0	0	0	0		0	0	0	0	0	0	0		0	0	0
v58	9153.85		0	0	0	0	0	0	0	0		0	0	0	0	0	0	0		0	0	0
v59	0		0	0	0	0	0	0	0	0		249.65	0	988.73	0	13.95	13.95	0		0	0	13.95
v60	0		0	0	0	0	0	0	0	0		124.83	0	494.37	0	6.98	6.98	0		0	0	6.98
v61	0		0	0	0	0	0	0	0	0		71.15	0	281.79	0	3.98	3.98	0		0	0	3.98
v62	0		0	0	0	0	0	0	0	0		53.67	0	212.58	0	ю	e	0		0	0	С
v63	0		0	0	0	0	0	0	0	0		124.83	0	494.37	0	6.98	6.98	0		0	0	6.98
v64	0		0	0	0	0	0	0	0	0		124.83	0	494.37	0	6.98	6.98	0		0	0	6.98
v65	0		0	0	0	0	0	0	0	0		53.67	0	212.58	0	б	ŝ	0		0	0	С
v66	0		0	0	0	0	0	0	0	0		0	0	0	0	0	0	0		0	0	0
v67	0		0	0	0	0	0	0	0	0		71.15	0	281.79	0	3.98	3.98	0		0	0	3.98
v68	0		0	0	0	0	0	0	0	0		53.67	0	212.58	0	Э	Э	0		0	0	С
v69	0		0	0	0	0	0	0	0	0		71.15	0	281.79	0	3.98	3.98	0	0	0	0	3.98
v70	0		0	0	0	0	0	0	0	0		53.67	0	212.58	0	m	n	0	0	0	0	n
v71	0		0	0	0	0	0	0	0	0		249.65	0	988.73	0	13.95	13.95	0	0	0	0	13.95
v72	31		0	0	31	0	0	31	31	31		31	31	31	0	0	0	31	0	0	0	0
v73	31		0	0	31	0	0	31	31	31		31	31	31	0	0	0	31	0	0	0	0
v74	31		0	0	31	0	0	31	31	31		31	31	31	0	0	0	31	0	0	0	0
v75	11		0	0	11	0	0	11	11	11		11	11	11	0	0	0	11	0	0	0	0
v76	23		0	0	23	0	0	23	23	23		23	23	23	0	0	0	23	0	0	0	0
LLV	с		0	0	m	0	0	с	ε	с		б	e	ŝ	0	0	0	ε	0	0	0	0
v78	с		0	0	e	0	0	с	с	ŝ		e	ω	С	0	0	0	e	0	0	0	0
v79	e		0	0	с	0	0	б	с	с		С	Э	e	0	0	0	Э	0	0	0	0
v80	m		0	0	Э	0	0	Э	Э	e		б	б	б	0	0	0	С	0	0	0	0
v81	9	0	0	0	9	0	0	9	9	9	9	9	9	9	0	0	0	9	0	0	0	0
v82	40		0	0	40	0	0	40	40	40		40	40	40	0	0	0	40	0	0	0	0

Table 4: Elementary vectors \mathbf{e}_i (last 41 entries) of the minimal decomposition of the flux vector \mathbf{v} of Table 2. The integer entries are exact stoichiometric coefficients. The other entries are truncated to the 2nd decimal.