

Une piscine de fluide non-newtonien...



*Voilà, un fluide vraiment difficile à modéliser !
C'est autre chose qu'un simple écoulement de fluide newtonien*

*C'est l'objet du cours de rhéologie...
Les fluides : ce n'est pas que l'aéronautique !
L'océan, c'est aussi un fluide !*

WHY
1D ?



TO AVOID
TECHNICALITIES !

SIMPLEST FLUID MODEL :

"THE NEWTONIAN VISCOUS MODEL"

$$\left\{ \begin{array}{l} \gamma \frac{D\rho}{Dt} - \beta \frac{DT}{Dt} + \nabla \cdot \underline{x} = 0 \\ \rho \frac{D\underline{x}}{Dt} = -\nabla p + \nabla (\alpha \underline{\underline{S}} : \underline{\underline{d}}) + \nabla \cdot (2\mu \underline{\underline{d}}^d) + \rho \underline{g} \\ \rho c_p \frac{DT}{Dt} - \beta T \frac{D\rho}{Dt} = \alpha (\underline{\underline{S}} : \underline{\underline{d}})^2 + 2\mu (\underline{\underline{d}}^d : \underline{\underline{d}}^d) \\ \quad + r + \nabla \cdot (k \nabla T) \end{array} \right.$$

INCOMPRESSIBLE
FLOW

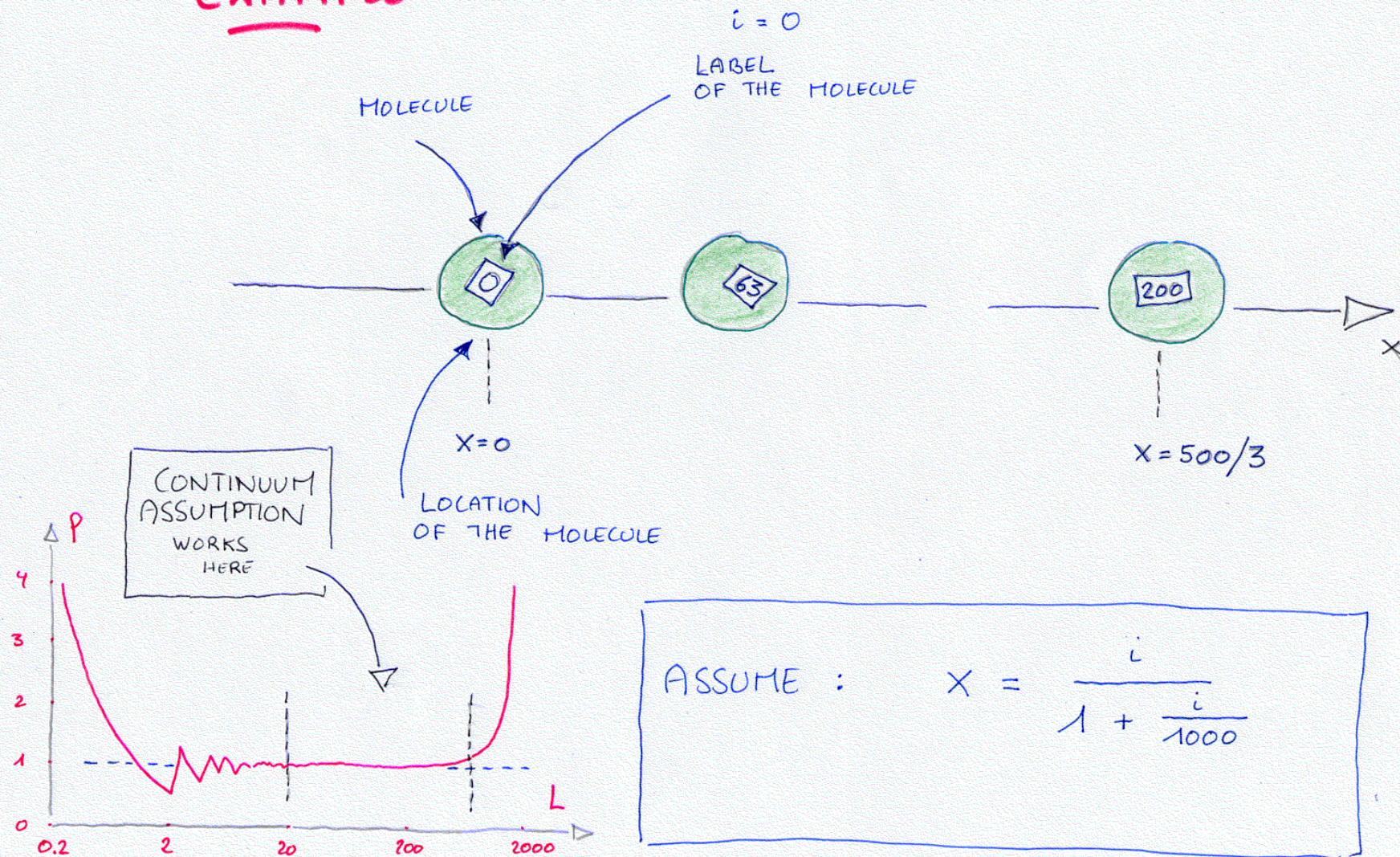


$$\nabla \cdot \underline{x} = 0$$

$$\rho \frac{D\underline{x}}{Dt} = -\nabla p + \nabla \cdot (2\mu \underline{\underline{d}}) + \rho \underline{g}$$

$$\rho c_p \frac{DT}{Dt} = 2\mu (\underline{\underline{d}} : \underline{\underline{d}}) + r + \nabla \cdot (k \nabla T)$$

STUPID EXAMPLE



SOLIDS
LIQUIDS
GASES

SEPARATION OF LENGTH SCALES

10^5	LINEAR	1D
10^{15}	VOLUME	3D

AVERAGED MASS
OF THE CONTINUUM

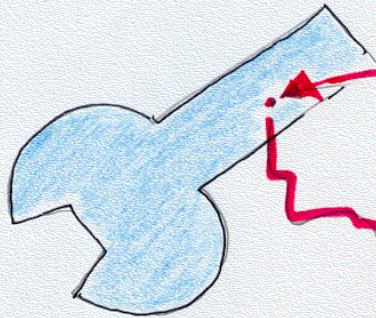
CONTINUUM
ASSUMPTION

$p(x, t)$ DENSITY
OF THE CONTINUUM

FORM OF
UNCERTAINTY
PRINCIPLE

ACCURACY
OF THE CONTINUUM HYPOTHESIS IS
DIRECTLY DEPENDENT UPON THE SEPARATION
OF THE LENGTH SCALES OF MOLECULAR FLUCTUATIONS
AND THE LENGTH SCALES OF MACROSCOPIC VARIATIONS

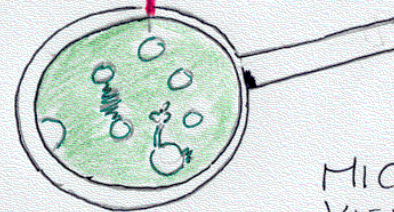
MACROSCOPIC
VIEW



PARTICLE
≡ VERY SMALL SECTION
OF A CONTINUUM MATERIAL



**MOLECULES
OR ELEMENTS**

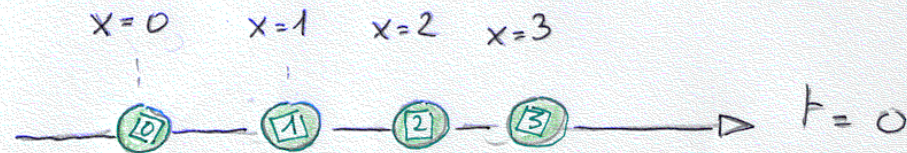


MICROSCOPIC
VIEW

**DESCRIBING THE MOTION
USING AVERAGED CONTINUOUS QUANTITIES**

LIKE HOUSE NUMBERING ALONG A STREET

REFERENCE
CONFIGURATION



EULERIAN
OR SPATIAL
COORDINATES



$$v^E(x)$$

EULERIAN
DESCRIPTION

$$v^L(\xi)$$

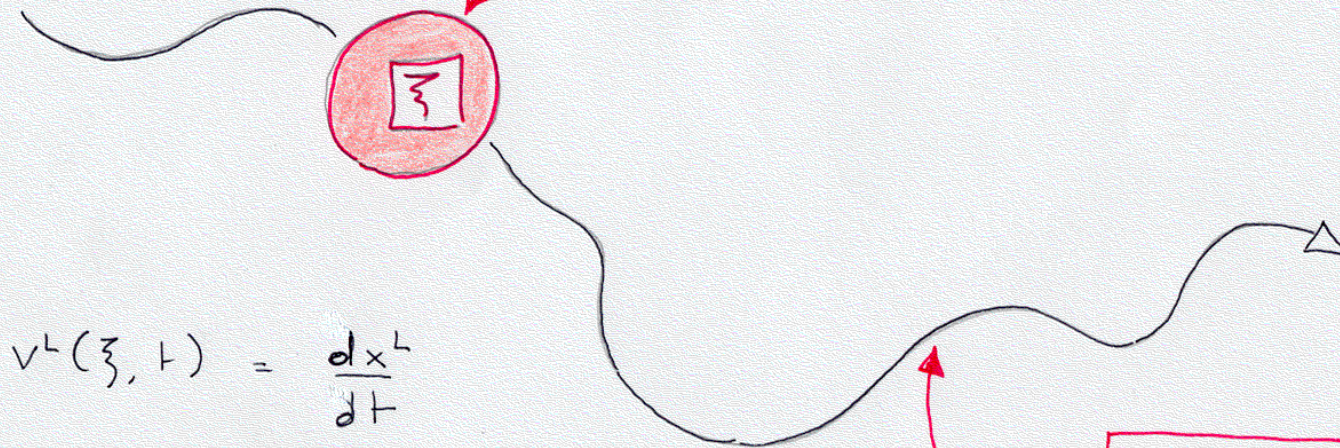
LAGRANGIAN
DESCRIPTION

LAGRANGIAN
OR MATERIAL COORDINATES

(IT IS IN FACT A "CONTINUOUS" NUMBERING !)

LAGRANGIAN DESCRIPTION

PARTICLE (\neq MOLECULE !)



$$v^L(\xi, t) = \frac{dx^L}{dt}$$

$$a^L(\xi, t) = \frac{d^2 x^L}{dt^2}$$

LAGRANGIAN
DESCRIPTION OF THE VELOCITY
AND THE ACCELERATION

PARTICLE
PATH

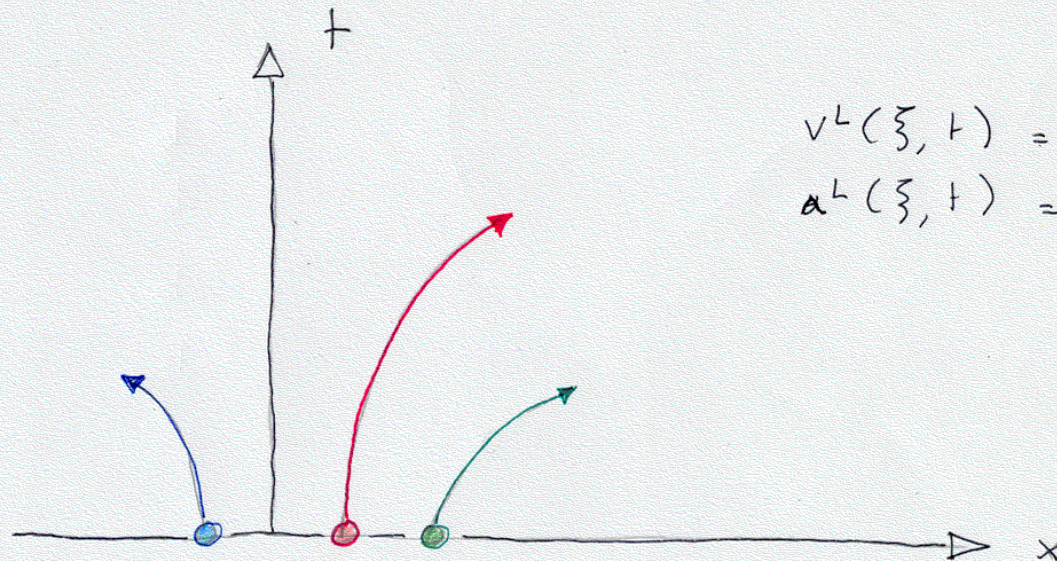
$$x^L(\xi, t)$$

$$\frac{d}{dt} = \frac{\partial}{\partial t} \quad \text{BECAUSE } \xi \text{ DOES NOT DEPEND OF } t!$$

EXAMPLE 2 :

$$x = x^L(\xi, t) = \xi + \xi t^2$$

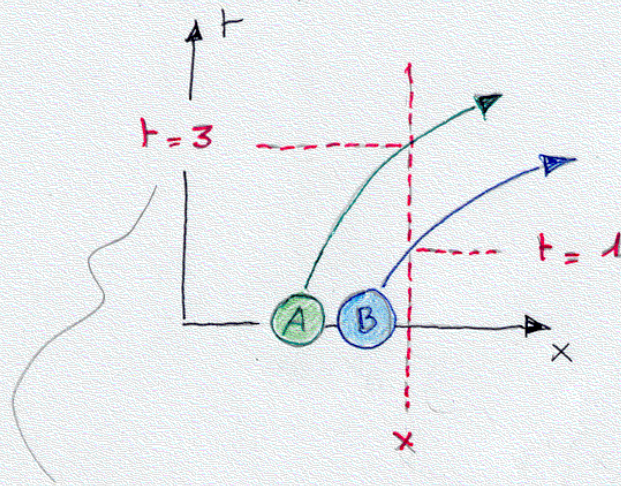
ASSUME THAT PARTICLES
OF CONTINUUM MOVE ACCORDING TO SUCH A RULE



$$v^L(\xi, t) = 2\xi t$$

$$a^L(\xi, t) = 2\xi$$

EULERIAN DESCRIPTION



EULERIAN
DESCRIPTION
OF THE
VELOCITY

$$v^E(x, t=1) = v^L(\underbrace{\xi = B, t=1}_{\text{LAGRANGIAN DESCRIPTION OF THE VELOCITY}})$$

LAGRANGIAN
DESCRIPTION
OF THE
VELOCITY

$$v^E(x, t=3) = v^L(\underbrace{\xi = A, t=3}_{\text{LAGRANGIAN DESCRIPTION OF THE VELOCITY}})$$

THE USUAL DESCRIPTION TO USE
IS THE EULERIAN DESCRIPTION

BUT, HOW TO FIND v_E ?

QUANTITY
OF IMPORTANCE

$$\xi^E(x, t)$$

↓
LABEL
OF PARTICLE
WHICH IS AT POSITION x
AT TIME t

$$\begin{aligned}\xi^E(x^L(\xi, t), t) &= \xi \\ x^L(\xi^E(x, t), t) &= x\end{aligned}$$

* SUBSCRIPTS E AND L
ARE IN FACT USELESS
AS $\xi^L = \xi$ AND $x^E = x$!
(BUT FOR SOME
NOTATIONAL SYMETRY,
THE AUTHOR LIKES THEM)

INVERSE *
FUNCTION
OF $x^L(\xi, t)$

↓
POSITION
OF PARTICLE ξ AT TIME t



$$v = U$$

$$x = \underbrace{\xi}_{x^L(\xi, t)} + \underbrace{Ut}$$

$$\rightarrow \xi = \underbrace{x - Ut}_{\xi^E(x, t)}$$



* FOR A GIVEN TIME
OF COURSE !

EXAMPLE 2
REVISITED

$$x = \underbrace{\xi} + \underbrace{\xi t^2}_{x^L(\xi, t)}$$

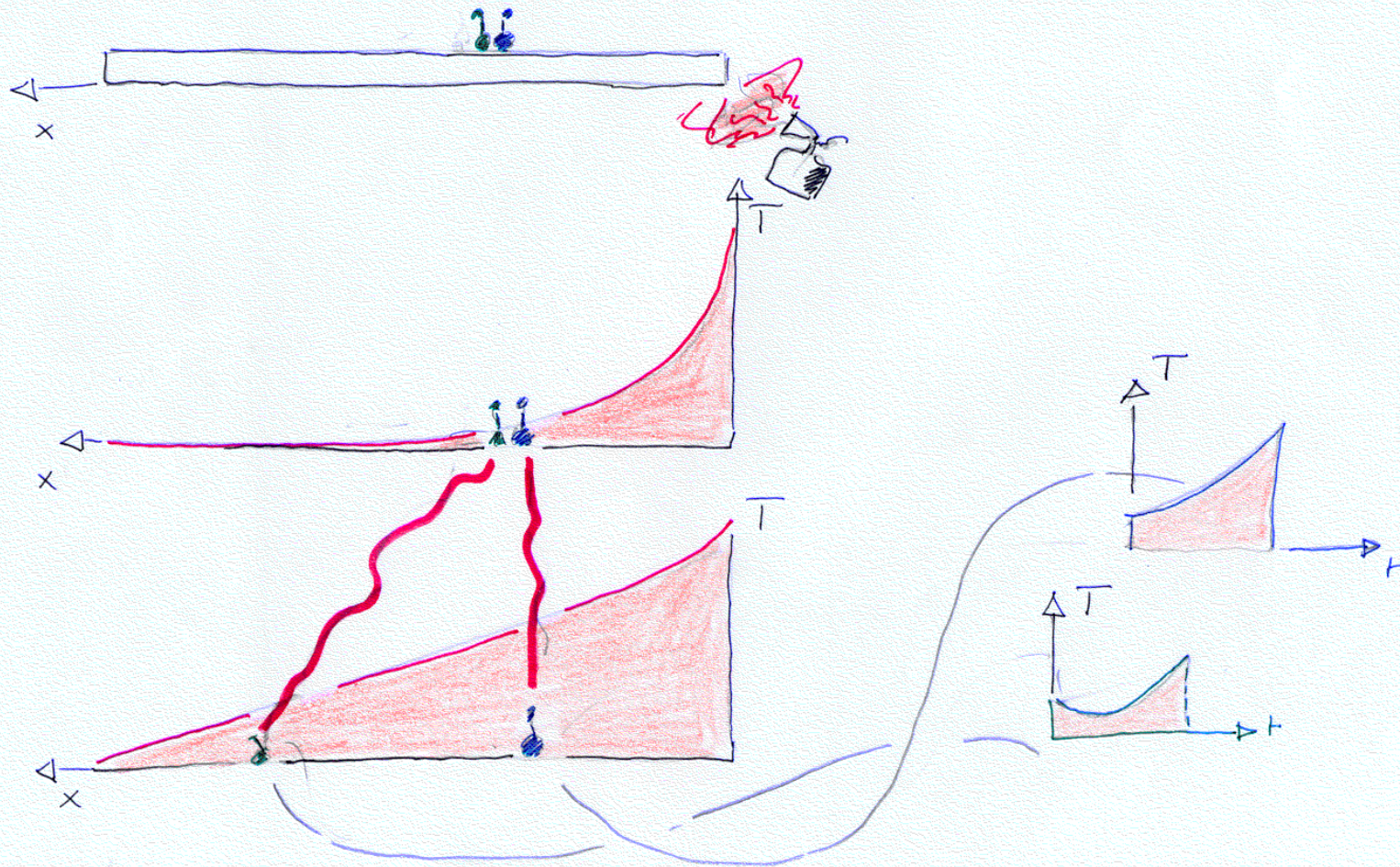
$$\rightarrow \xi (1 + t^2) = x$$

$$\xi = \frac{x}{\underbrace{1 + t^2}_{\xi^E(x, t)}}$$

$$\begin{aligned} v^E(x, t) &= \underbrace{v^L(\underbrace{\xi^E(x, t), t})}_{= 2\xi t} = 2 \frac{x}{1+t^2} t = \frac{2xt}{1+t^2} \\ &= 2\xi t \end{aligned}$$

$$a^E(x, t) = \frac{2x}{1+t^2}$$

DIFFERENCE BETWEEN WHAT A STATIONARY OBSERVER AND A MOVING PARTICLE EXPERIENCE !



MATERIAL DERIVATIVE

$$f = f^L(\vec{x}, t) = f^E(\overbrace{x^L(\vec{x}, t)}^x, t)$$

↓

$$\frac{df}{dt} = \frac{\partial f^L}{\partial t} = \frac{\partial f^E}{\partial t} + \frac{\partial f^E}{\partial x} \underbrace{\frac{\partial x^L}{\partial t}}_{v^L = v^E}$$

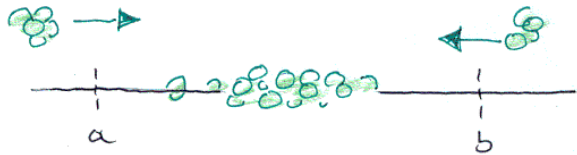
$$= \underbrace{\frac{\partial f^E}{\partial t}}_{\text{Rate of change of } f \text{ at fixed position}} + \underbrace{v^E \frac{\partial f^E}{\partial x}}_{\text{Rate of change of } f \text{ that a particle can "see" because it moves through a spatially non-uniform field of } f}$$

RATE
OF CHANGE
OF f AT FIXED
POSITION

$$\frac{Df^E}{Dt}(x, t)$$

RATE OF CHANGE
OF f THAT A
PARTICLE CAN "SEE"
BECAUSE IT MOVES
THROUGH A SPATIALLY
NON-UNIFORM
FIELD OF f

MASS CONSERVATION



RATE OF MASS INCREASE
IN THE INTERVAL

= RATE OF MASS INFLUX
ACROSS THE ENDS

✓ INTERVALS !

$$\frac{\partial}{\partial t} \int_a^b \rho \, dx = \rho_a v_a - \rho_b v_b$$

$$\int_a^b \frac{\partial \rho}{\partial t} \, dx + [\rho v]_a^b = 0$$

$$\int_a^b \left(\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x} (\rho v) \right) dx = 0$$

✓ $a < b$

IF ρ CONTINUOUS !!

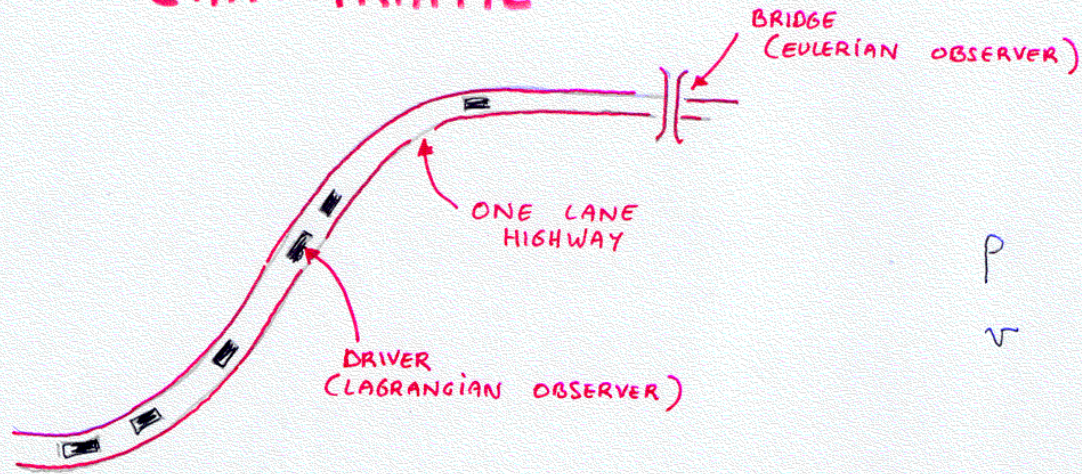
$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x} (\rho v) = 0$$

CONTINUITY
EQUATION

ALSO

$$\frac{D\rho}{Dt} + \rho \frac{\partial v}{\partial x} = 0$$

CAR TRAFFIC



ρ DENSITY OF CARS [CARS / Km]
 v VELOCITY OF CARS [Km / h]

CONTINUITY EQUATION

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x} (\rho v) = 0$$

+

STATE
OR
CONSTITUTIVE
EQUATION

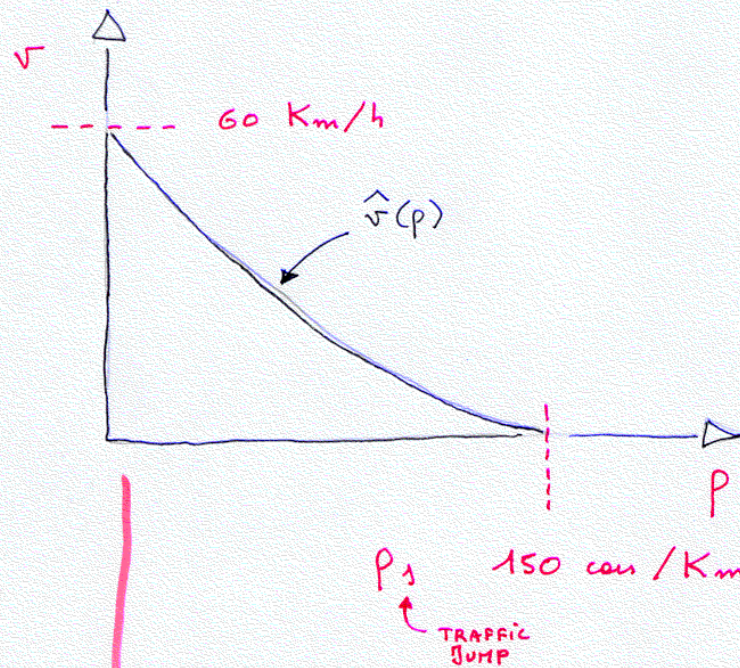
$$v = \hat{v}(\rho)$$

REASONABLE
 = MODEL
 OF THE DRIVER BEHAVIOUR

LIGHT TRAFFIC \rightarrow SPEED LIMIT !
 HEAVY TRAFFIC \rightarrow SLOW DOWN !

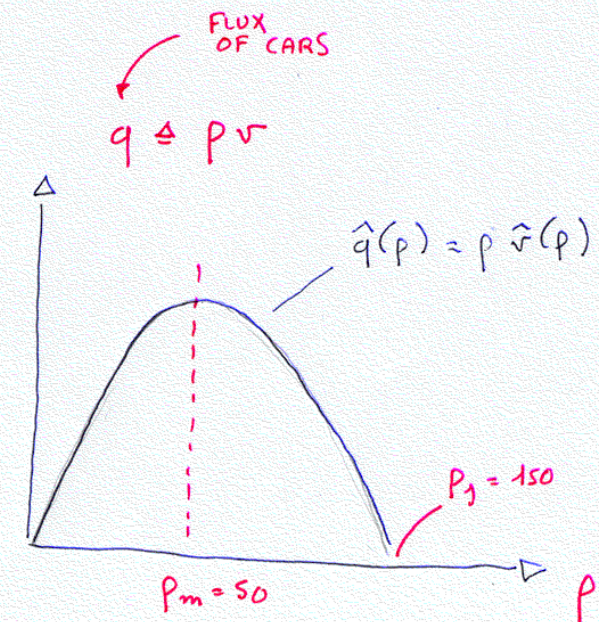
CONSTITUTIVE MODEL IS NEEDED TO CLOSE THE PROBLEM

STATE EQUATION FOR CAR TRAFFIC



IN AGREEMENT WITH EXPERIMENTAL EVIDENCES

[LINCOLN TUNNEL
NEW YORK ...]



SOLVING THE CAR TRAFFIC PROBLEM

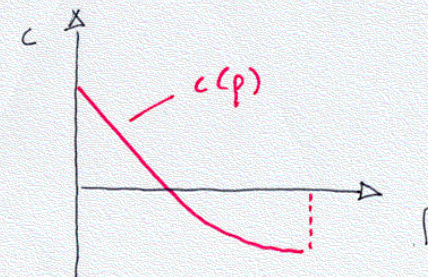
$$\frac{\partial p}{\partial t} + \frac{\partial}{\partial x}(\underbrace{p v}_{= \hat{q}(p)}) = 0$$

$$\frac{\partial p}{\partial t} + \frac{\partial}{\partial x}(\hat{q}(p)) = 0$$

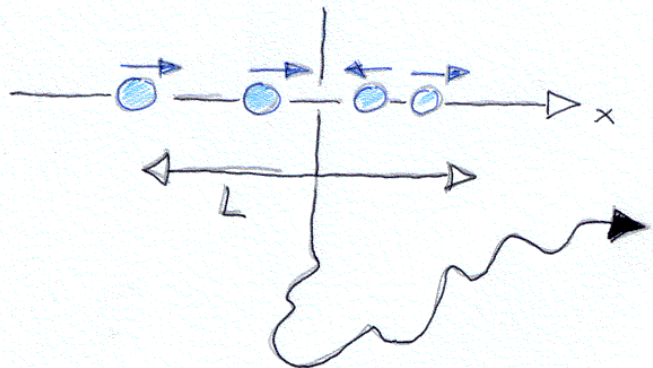
$$\frac{\partial p}{\partial t} + \underbrace{\hat{q}'(p)}_{\triangleq c(p)} \frac{\partial p}{\partial x} = 0$$

VELOCITY
AT WHICH FLUCTUATIONS
IN TRAFFIC DENSITY PROGRESS.

SINGLE
NON-LINEAR
HYPERBOLIC
DIFFERENTIAL
EQUATION



MOMENTUM DENSITY

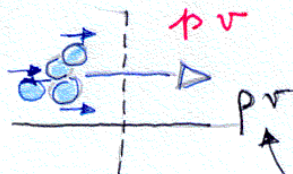


MOMENTUM DENSITY

$$\rho(x, t) \triangleq \underbrace{\rho(x, t)}_{\text{MASS DENSITY}} v(x, t)$$

THIS IS IN FACT THE DEFINITION OF THE CONTINUOUS VELOCITY, THE MOMENTUM AND THE MASS DENSITY BEING DEFINED BY THE AVERAGING PROCESS !

MOMENTUM FLUX



MASS FLUX