# Local Network Identifiability: Path Conditions

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## **1** Introduction

We consider the identifiability of a network matrix G(q), where the network is made up of *n* node signals stacked in the vector  $w(t) = [w_1(t) \quad w_2(t) \cdots w_n(t)]^\top$ , known external excitation signals r(t), measured node signals y(t) and unmeasured noise v(t) related to each other by:

$$w(t) = G(q)w(t) + Br(t) + v(t)$$
  

$$y(t) = Cw(t),$$
(1)

where matrices *B* and *C* are binary selections indicating respectively the  $n_B$  excited nodes and  $n_C$  measured nodes, forming sets  $\mathscr{B}$  and  $\mathscr{C}$  respectively.

The nonzero entries of the transfer matrix G(q) define the network topology:  $G_{ij}(q)$  is the transfer function from node j to node i, represented by an edge (j,i) in the graph. Some of those transfer functions are known and collected in matrix  $G^{\bullet}(q)$ , and the others are unknown, collected in matrix  $G^{\circ}(q)$ , such that  $G(q) = G^{\bullet}(q) + G^{\circ}(q)$ .

We assume that *the input-output relations between the excitations r and measurements y have been identified*, and that the network topology is known. From this knowledge, we aim at recovering an entry of  $G^{\circ}(q)$ , or a subset of them.



A first line of work extends the classical closed-loop identification techniques to identify a single module, see e.g. [1]. A recent approach employs graph-theoretical tools to derive identifiability conditions on the graph of the network. Using this approach, [2] addresses the particular case where all nodes are excited/measured. In the general case of partial measurement *and* excitation, [3] introduces a local version of identifiability and derives algebraic necessary and sufficient conditions. In this work, we consider local identifiability with partial excitation and measurement. From the conditions of [3], we derive a path conditions which generalize the results of [2] when not all nodes are excited/measured. \* Work supported by the "RevealFlight" ARC at UCLouvain, and by the MIS grant "Learning from Pairwise Data" of the F.R.S.-FNRS.

### 2 Problem reformulation

Starting from the definition of a network system in (1), we first define  $T(q) \triangleq (I - G(q))^{-1}$ , which is assumed to be proper and stable. The input-output model of (1) is:

$$y(t) = C T(q) B r(t) + \tilde{v}(t)$$

where  $\tilde{v}(t) \triangleq CT(q)v(t)$ . We assume that r(t) is sufficiently rich so that, for any *B* and *C*, CT(q)B can be consistently estimated from  $\{y(t), r(t)\}$  data. From the knowledge of CT(q)B, the aim is to identify  $G^{\circ}(q)$ . This motivates the following definition, which restricts the usual generic identifiability from [2] to non-discrete sets of solutions.

**Definition 1.** The module  $G_{ij}$  is locally identifiable at G from excitations  $\mathcal{B}$  and measurements  $\mathcal{C}$  if there exists  $\varepsilon > 0$  such that for any  $\tilde{G}$  with same zero and known entries  $G^{\bullet}$  as G satisfying  $||\tilde{G} - G|| < \varepsilon$ , there holds

$$C\tilde{T}(q)B = CT(q)B \Rightarrow \tilde{G}_{ij} = G_{ij},$$
 (2)

where  $\tilde{T}(q) = (I - \tilde{G})^{-1}$ .  $G_{ij}$  is generically locally identifiable *if it is locally identifiable at* almost all *G*.

#### **3** Results

In [3], a linearization of (2) yields a necessary and sufficient condition for generic local identifiability, based on the generic rank of a matrix K constructed from B, C and T.

In this work, we show how the generic rank of K relies on the generic rank of certain particular transfer matrices. Besides, we know from [2] that the generic rank of a transfer matrix can be characterized as paths in the network graph.

Combining those results allows to derive a necessary condition and a sufficient one for generic local identifiability in terms of paths in the network, which will pave the way for further developments in the subject.

#### References

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