

Labor market dynamics when effort depends on wage growth comparisons*

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Abstract. We present an efficiency wage model in which workers' disutility of effort depends on the level and on the growth rate of their wage relative to an alternative wage. Using data for four countries (US, UK, FR, GY), the implications of the model are examined and are found to be in accordance with the information in the non-stationary data. The restrictions implied by the model dynamics are not rejected by the data and the structural parameters are found to be constant through time. One interesting result is that the workers' disutility of effort depends less on relative wages growth and more on relative wage levels in the US than in the three European countries analyzed.

Key words: Efficiency wages, partial gift exchange, effort function, cointegration, GMM.

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1. Introduction

The contrast between the US pattern of the labor market and its European counterpart has attracted wide attention (see e.g. Card, Kramarz and Lemieux (1996)). Indeed, in the last two decades, the US labor market was characterized by constant or even declining real wages and rising employment,

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while the European labor market experienced steadily rising real wages and falling employment, and a substantial and persistent high level of unemployment.

There are many reasons for doubting that the time series properties of wages and employment can be understood in terms of the outcome of a competitive labor market. Indeed, dynamic models with perfect competition systematically fail to reflect the low response of wages to shocks and the high response of employment. Attempts to tackle this failure within the Walrasian paradigm are proposed in Christiano and Eichenbaum (1992), Burnside, Eichenbaum and Rebelo (1993) and Fairise and Langot (1994) and further evaluated using European data by Fève and Langot (1994).

Departures from the Walrasian framework account for some of these facts (An exploratory computable model is proposed by Bénassy (1995)). Among the various ways to improve modelling the labor market, efficiency wage theories seem a very promising one. In these models, the firm chooses the wage so as to motivate its employees, to reduce its turnover costs or to attract a larger share of skilled workers to its work basin. As stressed in the recent survey of MacLeod and Malcomson (1995), these models are able to explain why wages may not respond to some shocks and/or display asymmetric behavior over the business cycle and why employment varies so much.

In this paper, we develop an efficiency wage model in the spirit of the partial gift exchange of Akerlof (1982). In this framework, workers are ready to increase their effort in exchange of getting a fair wage from the firm. The fair wage depends on a comparison between the current wage and a norm which includes the wages received by other workers, the level of unemployment and unemployment benefits, and the actual wage of the individual in previous periods. This last element has been omitted in the subsequent analyses since the majority of them were performed in static frameworks. The optimal response of the firm to this behavior is to offer a wage above the market-clearing wage in exchange of which workers will provide a higher level of effort.

The idea that the wage growth comparisons are important in the determination of the fair wage is supported by various studies which tend to show that, in addition to the usual comparison of the level of firm's wages with outside wages, workers also compare their current situation with that in the past. For instance Lord and Hohenfeld (1979) compared the performance records of 23 major league baseball players who, for contract reasons, were paid less one season than they were the previous season. Thus, using their own salaries for the previous year as a basis of comparison, they were expected to have felt underpaid. The study shows that these players lowered their performance; in particular, they had lower batting averages, hit fewer home runs, and had fewer runs-batted-in. (from Greenberg and Ornstein (1984)).

A micro-econometric study of Wadhwani and Wall (1991) goes in the same direction. The authors use a panel on U.K. manufacturing enterprises to estimate their production function (including thus the effort function). They allow the wage norm to depend on past wages and show that there is some

¹ There exists two other strands of literature dealing with efficiency wages: the shirking approach (see e.g. Shapiro and Stiglitz (1984)) and the turnover costs approach (see e.g. Salop (1979)).

evidence in favor of this dependence. Additional inference on the role of past wages on effort can be done by analyzing job satisfaction studies. Using a panel data on British employees, Clark (1996) provides evidence that job satisfaction is strongly positively correlated with the change in the worker's pay between the two waves of the panel. Notice that when past situations are used as a benchmark to evaluate current outcomes, workers are interested in rising wage profiles, as shown in Loewenstein and Sicherman (1991) and Frank and Hutchens (1993). The same idea was applied to unions by Kotowitz and Portes (1974) and de la Croix, Palm and Pfann (1996).

Very recently the survey undertaken by Bewley (1998) brings interesting insights into modelling wage behavior. He interviewed 300 business people, labor leaders and counselors of unemployed people in the US to understand why wages were almost never declining. A first result is that "resistance to pay reduction came primarily from employers, not from workers or their representatives, though employers opposed pay cutting because of anticipated negative employee reactions." This suggests strongly that efficiency wage models better describe the key issues in the US than unions models. Second, firms dislike pay cuts because they hurt morale. Good morale promotes high productivity, less turnover, and a good company reputation that helps recruiting. Pay cuts hurt morale because of discomfort from reduced living standards and because of an insult effect – workers associate pay increases with approbation and reward. A key point of the survey is that morale depends on the level of wages, but most importantly, on wage changes. Bewley (1998) concludes that the theory of Akerlof (1982) is correct in emphasizing morale, and errs only if importance is attached to wage levels rather than to changes in them.

Accordingly we propose a dynamic model in which a representative firm chooses employment and a wage level designed to motivate its employees. The effort of these employees depends both on the level and on the growth rates of wages compared to those of the alternative wages (i.e. in the rest of their sector). With the aim to understand wage and employment dynamics, the implications of this model are confronted with data for manufacturing sectors in US, Germany, Great-Britain and France. Using the information contained in the observed stochastic and deterministic trends, a cointegration (Engle and Granger, 1987) restriction is derived from the theoretical model and used to estimate a first set of parameters. If cointegration is not rejected, the remaining parameters are obtained from the estimation of the Euler equations by the Generalized Method of Moments (Hansen, 1982). If cointegration is rejected, the adequate unit root is imposed, and the set of parameters is estimated in one step by GMM. We also analyze systematically the issue of parameter constancy, both at the level of the cointegration restriction and at the level of the GMM estimation. Keeping in mind that a large number of empirical studies find that many macroeconomic and sectoral time series contain a unit root and that the unemployment rates display a high degree of persistence, the empirical analysis shows that our model is broadly consistent with the presence of non-stationarity in the time series related to output, employment and wages and with a high degree of unemployment persistence.

The paper is organized as follows. In section 2, the theoretical model is presented. Section 3 describes the data and some summary statistics. In Section 4, results of the empirical analysis are presented. Section 5 contains some concluding remarks.

2. The model

The production function is

$$y_t = f(a_t, \tilde{l}_t, k_t), \tag{1}$$

where y_t is production and k_t the capital stock. The stochastic variable a_t is a productivity shock. \tilde{l}_t represents efficient hours of work which are given by

$$\tilde{l}_t = e^{\mu t} h_t l_t,$$

where l_t denotes hours input and h_t effort per hour. The parameter μ measures the growth rate of deterministic labor-saving technical progress. The production function is supposed to have a CES form:

$$f(.) = \psi e^{a_t} [(1 - \alpha)(e^{\mu t} h_t l_t)^{(\sigma - 1)/\sigma} + \alpha (k_t)^{(\sigma - 1)/\sigma}]^{\sigma/(\sigma - 1)}.$$
(2)

The parameter $\sigma > 0$ is the elasticity of substitution between efficient hours and capital. $\alpha \in]0,1[$ and $\psi > 0$. Two kinds of popular specifications for the technical progress are allowed for: (a) a deterministic labor saving technical progress (i.e. Harrod neutral) growing at a rate μ , (b) a stochastic technical progress a_t affecting total factor productivity and generated by the following scheme:

$$a_t = \phi a_{t-1} + z_t, \tag{3}$$

where z_t is assumed to be i.i.d. with $E\{z_t\} = 0$. The empirical analysis will be designed to evaluate the importance of both types of technical progress and to test whether a_t contains a unit root, i.e. $\phi = 1$.

As usually assumed in efficiency wage models, the representative firm chooses its wage level in order to increase the effort of its employees. The effort function has been introduced by Solow (1979) and used since then by many others, see e.g. Danthine and Donaldson (1990). The derivation of the effort function is obtained by using a utility function in which the disutility of labor has been replaced by the disutility of effort. We assume that the instantaneous utility of the consumer is separable between consumption and effort (but not necessarily time-separable):

$$U(c_t, h_t) = u(c_t, \cdot) - d_t(h_t - h(\cdot))^2$$

in which d_t is an indicator variable being equal to 0 if the agent is unemployed and 1 if he is employed. Taking the first order necessary condition with respect to h_t leads to

$$h_t = h(\cdot)$$

In the standard approach, the disutility of effort and, hence, the effort function depends on the level of wages compared to the level of the alternative wage: $h(w_t^c/\overline{w}_t^c)$. Assuming furthermore that the alternative wage is equal to the wage times the probability of finding a job, i.e. one minus the unemployment rate, $\overline{w}_t^c = (1 - u_t)w_t^c$, the level of effort depends positively on the unemploy-

ment rate. The firm's optimality conditions state that, at equilibrium, the elasticity of effort with respect to wages should be one (this relation is known as the Solow (1979) condition).² In this paper we consider "extended preferences" (Becker 1996) assuming that the disutility of effort also depends on the growth of the wage in the firm compared to the growth of the alternative wage, i.e. the wage paid by other firms of the sector weighted by the probability of finding a job in these firms. This approach follows the same argument as the one invoked to introduce habit formation in consumption (see e.g. Duesenberry (1949) and Ferson and Constantinides (1991)) or time-nonseparable utility of leisure (see e.g. Kydland and Prescott (1982)). Our disutility of effort takes the following specific form:

$$h(\cdot) = \left(\frac{w_t^c - \overline{w}_t^c}{\overline{w}_t^c}\right)^{\nu} \left(1 + \gamma \left(\frac{w_t^c}{w_{t-1}^c} - \frac{\overline{w}_t^c}{\overline{w}_{t-1}^c}\right)\right),\tag{4}$$

in which

$$w_t^c = \frac{w_t}{p_t^c}$$
 and $\overline{w}_t^c = \frac{\overline{w}_t}{p_t^c}$

are respectively the hourly real wage paid by the firm and the average hourly real wage in the rest of the sector and the consumption price index is used as deflator. The parameter $\nu < 1$ measures the extent to which the disutility of effort is sensitive to the difference in percent between the worker's wage and the alternative wage. The parameter γ measures the extent to which the disutility of effort is sensitive to the difference between the growth of the worker's wage and the growth of the alternative wage. The interest of the specific functional form (4) is to directly extend previous work: if $\gamma = 0$, one retrieves a standard formulation of efficiency wage models, see e.g. Summers (1988).

Real profits of the firm are:

$$s_t = y_t - w_t^p l_t - \frac{p_t^i}{p_t} i_t,$$

where i_t is gross investment and p_t^i its price. w_t^p denotes the real wage when the price index of output p_t is used as a deflator:

$$w_t^p = \frac{w_t}{p_t}.$$

The capital stock obeys the standard accumulation rule:

$$k_t = (1 - \delta)k_{t-1} + i_t,$$

Notice that the implications of this relation are not easily in accordance with a high degree of persistence in unemployment. Indeed the optimality condition contains a variable which is not far from being non-stationary so that it has to include other elements in order to become empirically plausible.

where δ is the depreciation rate. At time t, the firm chooses plans for wages, hours input and capital input so as to maximize the expected current real value of future profits given the information Ω_t available at time t:

$$\max_{w_t, l_t, k_t} \mathbf{E} \left[\sum_{i=t}^{\infty} R_t^i s_i | \Omega_t \right].$$

The uncertainty comes from the realization of the future exogenous variables among which technological shocks, prices and alternative wages. R_t^i is the discount factor between time t and time i. Ω_t is the information set at time t including current and past values of the exogenous variables and past values of the endogenous variables. The first order necessary conditions for a maximum are:

$$w_t^p = \frac{\partial f}{\partial \tilde{l}_t} e^{\mu t} h_t \tag{5}$$

$$w_t^p = \frac{\partial f}{\partial \tilde{l}_t} e^{\mu t} h_t \left(\frac{v w_t^c}{w_t^c - \overline{w}_t^c} + \gamma X_t \right) - \mathcal{E}_t \left[R_t^{t+1} \frac{l_{t+1}}{l_t} \frac{\partial f}{\partial \tilde{l}_{t+1}} e^{\mu(t+1)} h_{t+1} \gamma X_{t+1} \right]$$
(6)

$$\frac{p_t^i}{p_t} = \mathbf{E}_t \left[(1 - \delta) R_t^{t+1} \frac{p_{t+1}^i}{p_{t+1}} \right] + \frac{\partial f}{\partial k_t} \tag{7}$$

with

$$\frac{\partial f}{\partial \tilde{l}_t} = \psi(1 - \alpha)e^{a_t} \left(\frac{y_t}{\psi e^{a_t} e^{\mu t} h_t l_t}\right)^{1/\sigma} \tag{8}$$

$$\frac{\partial f}{\partial k_t} = \psi \alpha e^{a_t} \left(\frac{y_t}{\psi e^{a_t} k_t} \right)^{1/\sigma} \tag{9}$$

$$X_{t} = \frac{w_{t}^{c}/w_{t-1}^{c}}{1 + \gamma(w_{t}^{c}/w_{t-1}^{c} - \overline{w}_{t}^{c}/\overline{w}_{t-1}^{c})}$$
(10)

where $E_t\{.\} = E\{. | \Omega_t\}.$

The dynamics of the system results from the dynamics of the technological shock, the effort function and the accumulation of capital. The first equation states that workers are hired up to the point where the marginal productivity of labor in efficiency units is equal to the real wage. The second equation is a modified Solow condition. If $\gamma = 0$ it states that the wages should be set such that the elasticity of effort to wages is equal to one, or stated otherwise, that the wage of the firm is a mark-up over the alternative wage

$$(1-v)w_t^c = \overline{w}_t^c.$$

When $\gamma \neq 0$ this condition has to be modified to take into account the fact that workers are also interested in relative wage growth. The third equation is the standard optimal investment rule.

Equation (6) also gives rise to an interesting interpretation in the framework of a symmetric equilibrium. Indeed, in the majority of efficiency wage models the alternative wage \overline{w}_t is given at the symmetric equilibrium by

$$\overline{w}_t = (1 - u_t)w_t + u_t B_t, \tag{11}$$

where u_t is the unemployment rate, with $1 - u_t$ measuring the probability of finding a job in the rest of the economy. B_t represents the sum of unemployment benefits and the value of home production (or disutility of work). This can be rearranged into

$$\overline{w}_t = (1 - (1 - \beta)u_t)w_t,\tag{12}$$

where β is the ratio B_t/w_t . The parameter β is inversely related to the relative importance of unemployment in determining the worker's outside opportunities. Using (5) to replace $\frac{\partial f}{\partial \tilde{l}_t} e^{\mu t} h_t$ by its value, and using (12), we find:

$$0 = \frac{1}{\gamma} \left(\frac{v}{(1 - \beta)u_t} - 1 \right) + X_t - E_t \left[R_t^{t+1} \frac{w_{t+1}^p l_{t+1}}{w_t^p l_t} X_{t+1} \right]. \tag{13}$$

Notice that, at the symmetric equilibrium, the variable X depends on the growth rates of wages and unemployment. Loosely speaking, the parameter $1/\gamma$ measures the importance of the level of unemployment in the wage formation process. If $1/\gamma$ is very low, the fact that u_t could depart from a value given by $v/(1-\beta)$ will not affect significantly the optimal rule of the firm, and the growth rate of wages depends only on the growth rate of unemployment. If $1/\gamma$ is high, the level of unemployment is important and affects the optimal growth rate of wages. To summarize, if workers attach much weight to wage growth in determining their effort level, the optimal wage set by the firm will not react much to the level of unemployment. In a general equilibrium model, this characteristic may in turn lead to persistence in unemployment (Collard and de la Croix, 1999).

Let us briefly consider the implications of these first order conditions for the estimation method. Considering that the growth rate of real wages is stationary and assuming that unemployment is stationary, in which case effort is itself stationary, we may consider two different cases, depending on whether the technical progress is stationary or not. In both cases, a natural way to estimate the Euler equations of the model is to use the Generalized Method of Moments (GMM) proposed by Hansen (1982). When applying GMM we impose the unit roots and/or the cointegration relationships established in the first step of the empirical analysis. By imposing these restrictions, we want to avoid estimating unit roots and satisfy ergodicity and mixing conditions and thereby minimize the risk for GMM estimates and GMM-based tests to have non-standard asymptotic properties. A similar approach is used, a.o., by Ogaki (1992) and de la Croix and Urbain (1998). This two-step approach extends the one proposed by Dolado, Galbraith and Banerjee (1991) to nonlinear Euler equations with I(1) variables. We now investigate in turn the case in which the stochastic technical progress is stationary, i.e. $\phi < 1$, (case A) and the case in which this technical progress has a unit root, i.e. $\phi = 1$ (case B).

Let us assume that the technical progress is stationary ($|\phi| < 1$). In this situation and if the exogenous variables are I(1) processes, the theoretical model implies that real wages w_t^p and productivity y_t/l_t should be cointegrated I(1) processes. Similarly, if prices and wages are I(2), then they should cointegrate to yield an I(1) w_t^p which should then cointegrate with the I(1) y_t/l_t . The model remains valid if all the series are stationary.

Indeed, a cointegration restriction between real wages and average labor productivity is implicit in (5):

$$\sigma \ln[w_t^p] - \ln[(1 - \alpha)^{\sigma} \psi^{\sigma - 1}] - \ln[y_t/l_t] + (1 - \sigma)\mu t = v_t, \tag{14}$$

where we define

$$v_t \stackrel{\text{def}}{=} (\sigma - 1)(a_t + \ln h_t). \tag{15}$$

Since a_t and h_t only contain stationary variables, (14) defines a cointegration restriction. Notice that equation (14) admits several alternative interesting economic interpretations. If for instance labor-saving technical progress also had a stochastic trend a_{lt} , in equation (14), the term μt would have to be replaced by $\mu t + a_{lt}$. The stochastic part a_{lt} could be included in v_t yielding $v_t = (\sigma - 1)(a_{lt} + a_t + \ln h_t)$. Testing for cointegration would then be equivalent to testing whether $a_{lt} + a_t$ is I(0). This would be the case if the components a_{lt} and a_t were I(0) or if they were I(1) and cointegrated. In the model without stochastic total factor productivity which arises as a special case (i.e. $a_t \equiv 0$), cointegration between wages and productivity arises when a_{lt} is I(0).

In order to get reliable estimates of the parameters of this model it is useful to proceed in two steps. In the first step we estimate this cointegration relation by an appropriate method. We obtain super-consistent estimates $\hat{\sigma}$ and $\hat{\mu}$. These point estimates can be used in a second GMM step to get estimates of γ , ϕ and ν . Using (15), the first order conditions (5)–(6) can be written as:

$$\frac{\hat{v}_{t} - \phi \hat{v}_{t-1}}{\hat{\sigma} - 1} - v \ln \left[\frac{w_{t}^{c} - \overline{w}_{t}^{c}}{\overline{w}_{t}^{c}} \right] - \ln \left[1 + \gamma \left(\frac{w_{t}^{c}}{w_{t-1}^{c}} - \frac{\overline{w}_{t}^{c}}{\overline{w}_{t-1}^{c}} \right) \right]
+ \phi v \ln \left[\frac{w_{t-1}^{c} - \overline{w}_{t-1}^{c}}{\overline{w}_{t-1}^{c}} \right] + \phi \ln \left[1 + \gamma \left(\frac{w_{t-1}^{c}}{w_{t-2}^{c}} - \frac{\overline{w}_{t-1}^{c}}{\overline{w}_{t-2}^{c}} \right) \right] = z_{t}$$
(16)

$$\frac{1}{\gamma} \left(\frac{v w_t^c}{w_t^c - \overline{w}_t^c} - 1 \right) + \frac{\frac{w_t^c}{w_{t-1}^c}}{1 + \gamma \left(\frac{w_t^c}{w_{t-1}^c} - \frac{\overline{w}_t^c}{\overline{w}_{t-1}^c} \right)}$$

$$-\frac{w_{t+1}^{p}l_{t+1}}{w_{t}^{p}l_{t}}\frac{R_{t}^{t+1}\frac{w_{t+1}^{c}}{w_{t}^{c}}}{1+\gamma\left(\frac{w_{t+1}^{c}}{w_{t}^{c}}-\frac{\overline{w}_{t+1}^{c}}{\overline{w}_{t}^{c}}\right)}=e_{t+1},$$
(17)

where the error term of (16) is simply the innovation in the productivity shock and the error term of (17) represents forecast errors and is defined as

$$e_{t+1} = \mathbf{E}_{t} \left[\frac{w_{t+1}^{p} l_{t+1}}{w_{t}^{p} l_{t}} \frac{R_{t}^{t+1} \frac{w_{t+1}^{c}}{w_{t}^{c}}}{1 + \gamma \left(\frac{w_{t+1}^{c} - \overline{w}_{t+1}^{c}}{\overline{w}_{t}^{c}} \right)} \right] - \frac{w_{t+1}^{p} l_{t+1}}{w_{t}^{p} l_{t}} \frac{R_{t}^{t+1} \frac{w_{t+1}^{c}}{w_{t}^{c}}}{1 + \gamma \left(\frac{w_{t+1}^{c} - \overline{w}_{t+1}^{c}}{\overline{w}_{t}^{c}} - \overline{w}_{t}^{c}} \right).$$

When estimating the Euler equations (16)–(17), we shall assume that the productivity shock z_t has already occurred and is known to the firm when it takes its decision. The shock is of course an unobservable for the investigator. Therefore, z_t is treated as a disturbance in equation (16).

Let I_t be a subset of Ω_t consisting of observed lagged stationary variables. The moment restrictions used for the GMM estimation of the parameters can be summarized as:

$$E[(z_t e_{t+1})' \otimes I_t] = 0. \tag{18}$$

Finally notice that for reasons of flexibility equation (7) will not be included in the GMM estimation. This will result in a loss of efficiency but not in inconsistency as in the sequel the capital stock will be treated as an endogenous variable for which an instrumental variable is used.

If the technical progress is integrated of order one, in order to impose this unit root it is necessary to take equation (5) in first differences:

$$\frac{\sigma \Delta \ln[w_t^p] - \Delta \ln[y_t/l_t] + (1 - \sigma)\mu}{\sigma - 1} - v \Delta \ln\left[\frac{w_t^c - \overline{w}_t^c}{\overline{w}_t^c}\right]
- \Delta \ln\left[1 + \gamma \left(\frac{w_t^c}{w_{t-1}^c} - \frac{\overline{w}_t^c}{\overline{w}_{t-1}^c}\right)\right] = z_t,$$
(19)

where the error term of (19) is simply the innovation in the random walk a_t . The parameters σ , μ , and γ should be estimated using (17) in which the error term has the same interpretation as before. The restrictions used in GMM are the same as in (18).

3. The data

We use quarterly seasonally adjusted data on manufacturing sectors in the United-States, Germany, Great-Britain and France (industrial production, hours of work, hourly compensation, aggregate unemployment rate, price index). A detailed description and the source of these data are provided in Appendix A. The sample is the same for all countries and covers the period 1963:3–1994:4.

In the case where the stochastic process representing the technological progress is assumed to be a stationary AR(1) process (Case A), our empirical analysis will consist of different steps. For each country, we proceed as follows: (i) determination of the order of integration of the individual series, (ii)

³ The assumption implies that the expectation error and the shock z_t are un-correlated. This condition is not explicitly used in the estimation.

investigation of the presence of cointegration between w_t^p and y_t/l_t in order to obtain point estimates of σ and μ , (iii) given that these are super-consistently estimated in the case of cointegration, we may then fix these parameters at their point estimates $\hat{\sigma}$ and $\hat{\mu}$ and estimate the remaining parameters of (16) and (17), i.e. ϕ , γ and ν , in a second step by Generalized Methods of Moments. The last step of the empirical analysis is then the investigation of the potential parameter (non)-constancy of our retained specification and estimation results.

Accordingly we first compute⁴ some standard univariate unit root tests in order to obtain empirical evidence in favor or against the assumption of stochastic trends in our data. Notice that under the assumption of a stationary technical progress, and the assumption of I(2) nominal wages and prices, one of the implication of our theoretical model is that both real wages and productivity should be co-integrated I(1) processes. The Appendix B presents the outcome of standard Dickey-Fuller (1979, 1981) tests denoted by $DF_{(.)}$, and Phillips and Perron (1988) tests $Z_{(.)}$. Since nominal variables are possibly represented by I(2) processes, the test statistics are computed for the second differences, the first differences as well as for the level of the series. From appendix B, it appears that if we base the analysis on the Z tests, for almost all series and all countries, we may not reject the hypothesis of a single unit root in our series. If the results are based on DF type of statistics, there is some evidence in favor of I(2) prices and wages, but again the outcomes favor the I(1) nature of real wages. Note that in accordance with many empirical studies⁵, unemployment rates again are found to be I(1) processes over the sample period.⁶ Employment on the other hand is possibly trend stationary for the US (with a negative trend) while the outcomes for the other countries again favor the I(1) assumption. Real wages and labor productivity are always best described by I(1) processes. Note finally that Phillips-Perron's tests reject the unit root hypothesis for all the interest rates series.

4. Estimation results

4.1. Cointegration Analysis

There exists a wide range of approaches to cointegration testing and estimation in the literature, ranging from simple Engle and Granger (1987) static regressions to multivariate analyses. While the latter methods—like the popular Johansen (1991) maximum likelihood framework—have a number of clear statistical advantages in terms of their efficient use of the sample information and the underlying optimal inference that can be conducted, they are usually characterized by some particular maintained assumptions which we cannot retain for our analysis. The assumption of a linear finite order Gaussian VAR model which underlies for example Johansen's framework can be hardly maintained given our theoretical set-up. A possible alternative is therefore to

⁴ All the empirical calculations have been performed with Gauss 3.2.0 & TSP 4.3.

⁵ See e.g. Hall (1986), Jaeger and Parkinson (1994) and de la Croix and Lubrano (1996).

⁶ This again raises the issue of the usefulness of standard univariate unit root test for time series like unemployment rate. Whether one should follow a more general approach to the persistency in unemployment, allowing for stationary long memory processes, i.e. fractional processes, or for some form of non-linearity in the dynamics is however outside the scope of this study.

	Cnst	$(1-\sigma)\mu$	σ	Lc	MeanF	SupF
US	-0.2165	0.0083	0.2865	0.3444	2.9204	5.6111
UK	(0.0105) -0.1097	(0.0002) 0.0049	(0.0929) 0.8476	0.5917	4.4923	8.2295
ED	(0.0337)	(0.0008)	(0.1414)	0.2522	2.0542	6 6024
FR	-0.1568 (0.0263)	0.0047 (0.0008)	0.6264 (0.0933)	0.2522	2.9542	6.6024
GY	-0.0893	0.0050	0.4275	0.3954	4.1440	7.0142
	(0.0290)	(0.0008)	(0.0727)			

Table 1. Cointegration results (FMLS)

use asymptotically median-unbiased estimators that do not require a specific parametric representation of the short run dynamic and that nevertheless lead to optimal inference (in the sense of Phillips (1991)). The latter can for example be achieved by means of semi-parametric corrections for endogeneity and serial correlation which in our case would stem from the presence of $\ln h_t$ in v_t , see (14). In this paper, we choose to use the Fully Modified Least Squares (FMLS) estimators proposed by Phillips and Hansen (1990) and Hansen (1992b) as well as Park (1992) Canonical Cointegration Regressions (CCR) which yield asymptotically optimal estimates of the non-stationary components and are asymptotically equivalent to FIML parametric estimators but without requiring an explicit parametrization of the short run dynamics. Given the first order condition, we choose productivity as the regressand and real wages as the regressor. From (14) we see that we should also allow for the possibility of a linear trend in the cointegration regression. The resulting parameters, whose significance can be tested using fully modified t-statistics, are then simply σ for the real wages and $(1-\sigma)\mu$ for the linear trend.

Table 1 reports the cointegration results obtained from the use of the FMLS estimator computed with a Quadratic Spectral kernel function and an automatic plug-in bandwidth parameter. The Appendix C reports some comparable results obtained by using different estimation techniques such as CCR, straightforward OLS as well as FMLS both with and without VAR(1) pre-whitening. As pointed out for example by Haug (1996) and Cappucio and Lubian (1994), the way by which we estimate the long run covariance matrix used to correct the estimates can play an important role, especially in finite samples. Following the existing Monte Carlo evidence reported in Andrews and Monahan (1992), Cappucio and Lubian (1994), our FMLS estimates are computed using a quadratic spectral estimator with the automatic plug-in bandwidth parameter.⁷

The last columns of Table 1 report several statistics. L_c is Hansen (1992a) LM test for the null of cointegration against the alternative of no-cointegration based on the constancy of the intercept of the cointegration regression.

⁷ The advantage of using the plug-in bandwidth parameter is that it avoids the arbitrariness of choosing a priori the order of truncation. Although much of the motivation for using pre-whitening is the practical attractiveness of the approach, as it enables one to estimate more easily the long run covariance matrix, it should be noted that in our case the pre-whitening only seems to affect the results for the UK.

Asymptotic critical values are reported in Hansen (1992a). The 5% critical value is approximately equal to 0.575 in our case. The columns *SupF* and *MeanF* are parameter constancy statistics derived by Hansen (1992a). These statistics are in the spirit of sequences of standard Chow tests for parameter constancy. We compute a standard Chow test for a fixed break date and then consider the sequence of test statistics by varying the location of the break. The final *SupF* test is then the supremum of the sequence. Under the null of parameter constancy of the cointegration regression, the asymptotic distribution of *SupF* depends on the number of regressors in the cointegration regression and on the specification of the deterministic components. *MeanF* is computed from the same sequence, shares the same null hypothesis but is likely to be more powerful against gradual changes in the parameters. The respective 5% critical values are approximately given by 15.2 and 6.2 respectively.

From this Table we see that the null of cointegration, as tested by means of L_c , cannot be rejected for the US, France and Germany while the results for the UK are much more on the borderline which might indicate, for the UK at least, a possible violation of the assumption made in Case A. This could be an indication of the inappropriateness of the assumption of a stationary AR(1) technological progress which could contain a unit root and hence imply a lack of cointegration – see (14). Case B will therefore be of interest, at least for the UK. This is partly confirmed by the results reported in Appendix C. Notice also that for all countries, Table 1 shows that the assumption of parameter constancy cannot be rejected using Hansen (1992a)'s SupF and MeanF statistics.

4.2. GMM analysis – case A

Given the non-linear dynamic rational expectations formulation of the theoretical model, the non-linear IV version of GMM seems a natural method for estimating the remaining parameters of the Euler equations. In analogy to Engle and Granger's (1987) two-step method, we presume that the asymptotic properties of the second step GMM procedure are not affected by the first step estimation since the estimators for σ and μ from cointegrating regressions converge faster than the GMM estimators. For each country, the two equations (16)–(17) are thus estimated jointly imposing the adequate cross restrictions.

The value of β in a fully worked out model would depend positively on the utility of leisure, the value of unemployment benefits and negatively on the duration of unemployment. Such a richer specification is difficult to implement here due to a lack of appropriate quarterly data concerning these variables for manufacturing. Indeed, even if one were to use the existing annual data on the replacement ratio one should have first to correct them to account for the (unobserved) disutility of work and second to interpolate the resulting series to obtain quarterly data. These interpolated data would then at best be rough proxies for beta and therefore be of little use to understand the dynamics of wages. We shall consider here beta as a constant that we a priori set to 0.9. This value can be seen as the replacement ratio including the disutility of work. We have carried out a sensitivity analysis of the results to the chosen values of β . For values of β between .6 and .9, the point estimates are

only marginally affected except for the parameter v (see equation (13)). ⁸ However the outcome of the parameter constancy statistics becomes in some cases significant. The finding that high values (0.9) of beta give better results for the four countries is an indication that beta measures both replacement income and the disutility of work. The results of the sensitivity analysis with respect to β therefore indicate that it is probably not appropriate to include observations on replacement income only to resolve the problem. Instead, one would have to expand the model by including a specification which treats β as an observable variable with the disutility of work being unobserved. Resolving this issue would however go beyond the purpose of this paper.

Concerning the discount factor, we use a varying discount factor of the form:

$$\begin{cases}
R_t^t = 1 \\
R_t^i = \prod_{j=t}^i \left(\frac{1}{1+r_j}\right), \quad i > t
\end{cases}$$
(20)

where r_j is the real interest rate. The model has also been estimated using a constant (imposed) discount factor of 0.99. This leads to the same conclusions as the analysis of the main text, and the corresponding results are presented in appendix D.

As discussed in Hall (1993) and Ogaki (1993a), the GMM often appears to be sensitive to the chosen instrument set. In particular, for a fixed sample size, increasing the number of instruments increases the number of over-identifying restrictions but, at the same time, may introduce substantial bias in the estimates of the coefficients. For case A, the retained instrument set includes all stationary pre-determined variables in equations (16)–(17) for which data are available,

$$I_t = \{\text{cst}, \text{trend}, \text{trend}^2, \hat{v}_{t-1}, \Delta u_{t-1}, \Delta \ln w_{t-1}^c, \Delta \ln l_{t-1}, \hat{v}_{t-2}, \Delta \ln w_{t-2}^c\},\$$

where \hat{v}_t is the residual of the cointegration regression as defined in (14) and hence includes w_t^p and y_t/l_t . The presence of trend² stems from the non-linear structure of the Euler equations. With this instrument set, the number of over-identifying restrictions is equal to 15. As suggested by Kocherlakota (1990) and Nelson and Startz (1990), we iterate on the optimal weighting matrix (i.e. the inverse of the covariance matrix of the orthogonality conditions) in order to improve the properties of the estimators.

The results of the GMM estimation of (16)–(17) are presented in Table 2. Robust standard errors are reported in parentheses. These are obtained on the basis of the heteroscedasticity and autocorrelation consistent covariance matrix of Newey and West (1987). J is Hansen (1982)'s test for over-identifying restrictions, asymptotically χ^2 distributed with q degrees of freedom, where q is the number of over-identifying restrictions. Corresponding p-values are reported between square brackets.

⁸ Moreover, the J_{test} is not much affected by the choice of β and the over-identifying restrictions are never rejected at 5% for these different values of β .

	φ	ν	1/γ	J_{test}	$t_{\phi=1}$	SupLR
US	0.8733 (0.0324)	0.0048 (0.0003)	0.0396 (0.0079)	17.1647 [0.3091]	-3.9090 [0.0031]	5.1904
UK	0.8678	0.0027	0.0156	15.0098	-3.6061	10.2658
FR	(0.0366) 0.7361	(0.0006) 0.0016	(0.0057) 0.0114	[0.4507] 15.0771	[0.0072] -4.0601	16.3890
GY	(0.0650) 0.8674	(0.0004) 0.0015	(0.0021) 0.0162	[0.4459] 20.3443	[0.0021] -3.7344	10.7749
	(0.0355)	(0.0003)	(0.0043)	[0.1591]	[0.0051]	10.7719

Table 2. GMM estimates (case A)

Given that, following the cointegration analysis, we do not reject the constancy of the long-run parameters, we analyze the constancy of the short-run parameters conditionally on the estimates of the long-run parameters. The analysis considers a sequence of *LR* type tests, see Andrews (1993), computed as the difference between the partial sample-GMM objective function evaluated at the full sample GMM and at the partial sample-GMM estimators.⁹

The structural break is allowed to occur in the interval of time [0.15, 0.85]. SupLR is thus the supremum of the sequence of the quasi likelihood ratio type tests for parameter constancy. The critical values are 14.15 at 5% and 17.68 at 1% for a model with three parameters.

From Table 2, we may draw the following conclusions. First, all coefficients have the expected sign and are significantly different from zero (except ν for the UK). Second, according to the J_{test} , the over-identifying restrictions arising from the model are never rejected at 5%. Third, the parameter ϕ is always significantly lower than 1, even if we use a Dickey-Fuller distribution instead of a student distribution for $t_{\phi=1}$. This is consistent with the cointegration analysis for three countries out of four. For the UK, the parameter ϕ of the AR(1) process of technological shocks is also significantly lower than one, although the evidence in favor of cointegration is less clearcut. Fourth, parameter constancy is moderately rejected for France (at 5% but not at 1%). It is not rejected in the three remaining countries. Fifth, $1/\gamma$ is significantly larger for the US than for the three European countries. The interpretation of this is discussed later in the text.

4.3. GMM analysis – case B

We now present the estimation results of the model under the assumption that the productivity shock contains a unit root. We have seen that this assumption seems realistic for the UK. To facilitate cross-country comparisons, the estimation under case B has been carried out for each of the four

⁹ As suggested by Gallant (1987), *LR* is computed as the normalized difference between the constrained objective function and the unconstrained one. The constrained estimation is computed with the weighting matrix provided by the unconstrained estimation.

	σ	$(1-\sigma)\mu$	ν	$1/\gamma$	J_{test}	SupLR
US	0.9092	0.0061	0.0054	0.0338	22.1043	23.2113
UK	(0.0994) 1.0546	(0.0009) 0.0025	(0.0004) 0.0024	(0.0095) 0.0140	[0.2274] 17.5961	30.7501
FR	(0.1080) 0.7099	(0.0014) 0.0042	$(0.0007) \\ 0.0011$	(0.0064) 0.0123	[0.4825] 17.6005	28.8220
GY	(0.0982) 0.2046	(0.0016) 0.0071	(0.0004) 0.0012	(0.0022) 0.0247	[0.4822] 27.7115	59.1336
	(0.0619)	(0.0014)	(0.0002)	(0.0054)	[0.0666]	

Table 3. GMM estimates (case B)

countries. The instrument set differs slightly from case A, since we have no cointegration residuals to include in the instrument set:

$$I_{t} = \left\{ \text{cst, trend, trend}^{2}, \Delta u_{t-1}, \Delta \ln w_{t-1}^{c}, \Delta \ln l_{t-1}, \Delta \ln \frac{y_{t-1}}{l_{t-1}}, \Delta \ln \frac{y_{t-1}}{l_{t-2}}, \Delta \ln w_{t-2}^{c}, \Delta \ln w_{t-1}^{p}, \Delta \ln w_{t-2}^{p} \right\}.$$

This leads to 15 over-identifying restrictions. The results are presented in Table 3. As before, all coefficients have the expected sign and are significantly different from zero. The point estimates are not very different from the analysis under $\phi < 1$ except those of σ . According to the J_{test} , the over-identifying restrictions arising from the model are not rejected for the first three countries and at the margin for Germany.

The parameter constancy hypothesis is rejected for all countries (the critical value for a model with four parameters is 16.45 at 5% and 20.71 at 1%).

The cointegration tests presented earlier together with the parameter constancy results favor the idea that for three countries (US, FR and GY) the model with a stationary productivity shock and an estimation method in two step gives better results. For the UK, there is no evidence in favor of cointegration, and the estimation in one step by GMM gives acceptable results although parameter constancy is rejected. We thus retain the assumption that $\phi = 1$ for the UK although the alternative can also be supported on the basis of different arguments. Note that the estimates for γ and ν do not differ substantially between the two alternatives.

An analysis of the residual correlations of the models in cases A and B indicates that there is some serial correlation and cross-correlation present in the disturbances. For France and for the US, the residual first order correlation is of importance and leads to significant values for the Ljung-Box test. For the UK and Germany, residual correlations at lags three and/or four are significant in some instances as well. This could result from seasonality still present in the seasonally adjusted series. Of course, in order to deal with the residual serial correlation, one could further refine the dynamics of the model. For instance, effort could be assumed to depend on a comparison between lagged annual growth rates of wages instead of the lagged quarterly rates.

	$(1-\sigma)\mu$	σ	ϕ	ν	$1/\gamma$
US	0.0083	0.2865	0.9529 (0.0151)	0.0063 (0.0001)	0.1046 (0.0103)
UK	0.0014 (0.0008)	1.1344 (0.0630)	1.0000	0.0020 (0.0003)	0.0153 (0.0041)
FR	0.0047	0.6264	0.6633 (0.0342)	0.0025 (0.0002)	0.0173 (0.0017)
GY	0.0050	0.4275	0.8544 (0.0216)	0.0011 (0.0002)	0.0153 (0.0028)

Table 4. GMM estimates: pooled countries

Such a specification would rely on the assumption that workers compare the evolution of wages over a longer period of time. Alternatively, a more general specification for the process of the technology shocks would account for serial correlation in \hat{z}_t . These extensions are left for future research. However, in view of the moderate size of the residual serial correlations, we do not expect any substantial inconsistency to arise in GMM estimation.

4.4. Cross-country comparison

Considering the results of Table 2 and 3, it may be important to proceed to a cross-country comparisons of the parameters estimates which display some similarities and one interesting difference. The parameter γ which measures the sensitivity of effort to wage growth comparisons is significantly lower in the US. On the other hand, the parameter ν is significantly larger in the US, reflecting that efforts depends more on the comparison between the levels of wages. The question that naturally arises is to know if we can impose the parameters ν and γ to be the same for all three European countries. Exploiting the fact that the sample period is the same for the four countries, this issue can be addressed by estimating an eight equations model using a seemingly unrelated GMM procedure. In that case, the country specific over-identifying restrictions are based on the orthogonality between the residuals and the country specific instruments, so that the instruments related to the three other countries are excluded.

The estimation results are presented in Table 4 in which ϕ has been set to 1 for the UK (case B) and σ and μ are set to the values obtained with FMLS for the three other countries (Table 1). We thus estimate equations (16) and (17) for the US, FR and GY together with equations (19) and (17) for the UK. The number of over-identifying restrictions is 63. The J-test gives a value of 50.5089 which allows us to not reject the over-identifying restrictions (p-value = 0.8720). Using standard Wald-type tests, we cannot reject the hypothesis that $1/\gamma^{UK} = 1/\gamma^{FR} = 1/\gamma^{GY}$ (p-value = 0.7649). On the other hand, the restrictions that $\nu^{UK} = \nu^{FR} = \nu^{GY}$ are rejected (p-value = 0.0000), while the less restrictive assumption that $\nu^{UK} = \nu^{FR}$ is much more close to the borderline case (p-value = 0.1144). These tests imply that, with respect to the parameter γ , the countries can be classified in two blocks, the US on the one side with a relatively low effect of wage growth on effort, and the three Euro-

pean countries on the other side with a relatively high effect of wage growth on effort.

One can be worried by the huge change in the point estimates of the parameters for the US compared to those presented in Table 2. To investigate whether this is due to the instruments choice, we have re-estimated our eight equation system with restrictions based on the orthogonality between the residuals and the whole set of instruments. This leads to point estimates that are very comparable to those presented in Tables 2 and 3. Although the 219 restrictions are surprisingly not rejected in this case, this suggests that the discrepancy between Table 2 and 4 should be related to the choice of the instrument set in the pooled estimation. Addressing this issue in detail would probably require a different set-up (dynamic panel) and is left for future research.

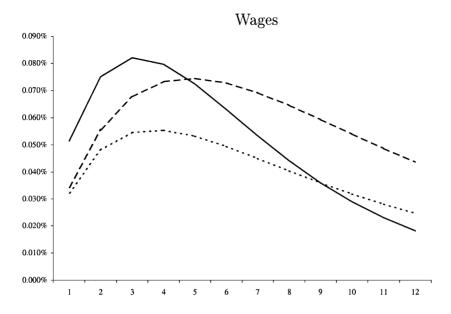
4.5. Impulse responses

To further analyze the cross-country differences in the dynamics of wages and employment, we compute the optimal policy of the firm following a productivity shock and given all other variables (unemployment rate, unemployment benefits and prices). To perform these computations we had to make a series a assumptions. First, we simulate the deterministic version of the model using the method proposed by Boucekkine and Le Van (1996) to solve non-linear models with perfect foresight. Second, as we have assumed constant return to scale, the level of production of the firm is undetermined; in the simulations we keep the ratio v_t/e^{a_t} constant which allows us to interpret our shock as a shift affecting the marginal productivity of labor (using equation (8)). Third, we take the country specific estimates of the persistence parameters (ϕ) and we use the estimated standard errors of the residual of equation (16) as the standard error of the productivity shock. This gives $\sigma_{us}^z = \hat{0}.0129$, $\hat{\sigma}_{fr}^z = 0.0307$ and $\sigma_{\rm gy}^z = 0.0219$. Fourth, we perform the simulations for the countries for which the productivity shock has been found to be stationary (US, FR, GY). The shock is thus transitory.

The aim of the exercise is to illustrate what our theory has to say quantitatively on the adjustment process of wages and employment. Figure 1 displays accumulated response functions for a one standard deviation increase in productivity z_t . We first conclude that, given the scale of the first chart, wages are almost completely rigid. Second, the short-run response of employment is much higher in France than in the US. This is partly due to the difference in the variance of the shock but not entirely. Notice that the volatility of wages, although very low, is of the same order of magnitude in the different countries but the volatility of employment is not. The persistence in the employment series is essentially the same as that of the shock. From this exercise we thus retain that our model can account for a low variability of wages and a high variability of employment.

5. Conclusion

We proposed a dynamic model in which a representative firm chooses employment and a wage level designed to motivate its employees. The effort



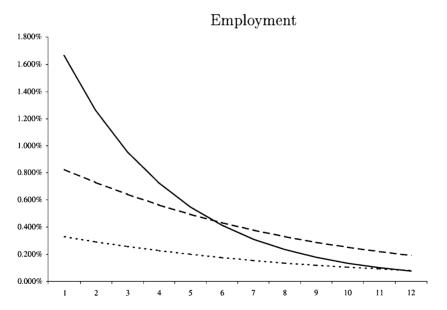


Fig. 1. Accumulated responses to a productivity shock. US: dotted line, FR: solid line, GY: dashed line.

of these employees depends, first, on a comparison between the level of their wage and the level of the alternative wage and, second, on a comparison between the respective growth rates. The restrictions arising from this model have been confronted with data for manufacturing sectors in US, Germany,

Great-Britain and France. From the theoretical model we derive a cointegration restriction between real wages and labor productivity, which is in agreement with the nonstationarities found in the data. Empirical evidence in favor of cointegration is found for the US, France and Germany, indicating that technical progress has been (trend) stationary in these countries. For these three countries, a first set of parameters is estimated by Fully-Modified Least Squares and the remaining parameters are obtained from the estimation of the Euler equations by GMM, given super-consistent estimates of the first set of parameters. For the United-Kingdom, the evidence from the cointegration analysis is less clear-cut. There is evidence in the data in favor of a unit root in the technological shock. We then estimate the full set of parameters in one step by GMM, although the alternative is also defendable.

The conclusion is twofold. First, the implications of the model seem in accordance with the non-stationarity present in the data and the restrictions imposed on the dynamics are not rejected. Parameter constancy is not rejected in three countries among four. Second, the parameters of the US effort function are significantly different from those for European countries. Effort is less sensitive to wage growth comparisons in the US than in the three European countries. In these three countries, we may restrict the sensitivity parameter γ to be the same. In the US, effort is more sensitive to the relative wage than in Europe. European workers seem more attached to previous wage conditions and put more weight on wage increases. According to our results, the optimal wage growth set by the firm is more sensitive to the level of unemployment in the US than in Europe.

Two limitations of the model are worth noting. First, in order to keep the number of parameters of the empirical model low, the specification of the alternative wages is the simplest possible. They only depend on wages in the manufacturing sector and on the level of unemployment. A more general formulation should include wages outside the manufacturing sectors and some variables related to unemployment (benefits, duration etc...). The inclusion of additional countries would be useful to further enrich the analysis. Second, as it has been discussed earlier in the text, because the technological shock has a very simple formulation and because the memory of workers is limited to one period, the dynamics of the model is very simple. As already indicated, further refining the dynamics of the effort function would also be interesting.

Appendix A: data sources

Table 5.

US		
y_t	Output of manufacturing industries	Federal reserve bulletin
l_t	Worked hours in manufacturing industries	Bulletin des statistiques du travail
w_t	Hourly gains in manufacturing industries	Employment and earnings
p_t	Producer price index, finished goods	Business cycles indicators
p_t^c	Consumption price index	Federal reserve bulletin
u_t	Civilian unemployment rate	Federal reserve bulletin

¹⁰ From a practical point of view, parameter constancy appears as a necessary but not sufficient condition for robustness to the Lucas critique.

Table 5. Continued

UK		
y_t	Output of manufacturing industries	Monthly digest
l_t	Worked hours in manufacturing industries	Employment gazette
w_t	Weekly gains in manufacturing industries	Employment gazette
p_t	Wholesale price of finished goods	Trade and industry
p_t^c	Consumption price index	Monthly digest
u_t	Unemployed as a percentage of active population	Trade and industry
FR		
y_t	Output of manufacturing industries	OECD industrial production
l_t	Worked hours in manufacturing industries	Bulletin des statistiques du travail
w_t	Hourly wage in transformation industries (bef. 1973: all industries)	Bulletin mensuel de statistiques
p_t	Consumption price index of manufactured goods	Bulletin mensuel de statistiques
p_t^c	Consumption price index	Bulletin mensuel de statistiques
u_t	Unsatisfied employment demand	Bulletin mensuel de statistiques
	Active population	OCDE stat. de la population active
GY		
y_t	Output of manufacturing industries	Wirtschaft und Statistik
l_t	Hourly productivity in manufacturing industries	Wirtschaft und Statistik
	Output of manufacturing industries	Wirtschaft und Statistik
w_t	Hourly wages in manufacturing industries	Indikatoren zur Wirtschaftsenwicklung
p_t	Wholesale price of industrial products	Wirtschaft und Statistik
p_t^c	Consumption price index	Wirtschaft und Statistik
u_t	Unemployed persons	Wirtschaft und Statistik
	Active population	OCDE stat. de la population active

Appendix B: Unit Roots Tests

Two versions of the statistics are considered: with both a constant and a linear time trend in the underlying regression model, denoted by a subscript tr, and with a constant term alone, denoted by the subscript cst. For the level (i.e. I(1) versus I(0)), we compute the statistics for the null of a random walk with drift against the alternative of a trend stationary process. For the first difference we consider both the case with and without trend while for the second difference we only retain the case with a constant as it seems unlikely to have I(2) series with drift.

Note to Table:

- For Phillips-Perron non-parametric corrections, the long run variances are estimated using a Quadratic Spectral kernel function and an automatically plug-in bandwidth parameter. For the ADF tests, the augmentation lag length was chosen by minimising Akaike's AIC criteria.
- Two versions of the statistics are considered: with both a constant and a linear time trend in the underlying regression model, denoted by a subscript *tr*, and with a constant term alone, denoted by the subscript *cst*.
- Critical values for DF and Z tests are, for T = 100, as follows: for DF_{cst} and Z_{cst} : -2.89 and -2.58 at a 5% and 10% level respectively, For DF_{tr} and Z_{tr} : -3.45 and -3.15 at a 5% and 10% level respectively.

Table 6. Unit Roots Tests

		Level		1st difference	ce			2nd difference	nce
		DF_{tr}	Z_{tr}	DF_{cst}	DF_{tr}	Z_{cst}	Z_{tr}	DF_{cst}	Z_{cst}
Ω S	W_{ℓ}	-1.1849	1.3966	-1.1342	-2.0773	-4.0610	-4.7602	-7.2155	-2.5493
	p_t	-1.4881	-0.0171	-2.4010	-2.5713	-6.4258	-6.5821	-7.5142	-3.3493
	pc_t	-1.1670	-0.8691	-2.5696	-2.6794	-4.4445	-4.4833	-5.0293	-3.4161
	wp_t	-3.0740	-2.2464	-3.7289	-3.8152	-10.8512	-10.9112	-4.4525	-5.4035
	wpc_t	-1.7347	-1.8891	-3.6617	-4.8677	-9.2254	-9.9431	-6.5120	-6.0646
	n_t	-2.3166	-2.2643	-3.5900	-3.6434	-6.3173	-6.3351	-4.5800	-5.2302
	l_i	-4.0170	-4.0219	-4.4680	-4.4682	-6.7856	-6.8521	-5.6772	-5.6966
	y_t/l_t	-2.4840	-2.9362	-7.3717	-7.3377	-12.5887	-12.5820	-5.8398	-8.1838
	R_t^{t+1}	-2.4626	-7.6090	-7.8826	-7.8794	-26.1260	-26.1251	-5.9469	-12.2255
UK	W_{ℓ}	-1.3570	-0.4601	-2.4134	-2.6079	-10.2675	-10.3900	-4.4260	-5.3070
	p_t	-1.9831	-0.9885	-1.5924	-1.7693	-3.7167	-3.8055	-4.8564	-3.0995
	pc_t	-1.5058	-0.1769	-1.9694	-2.1077	-5.7318	-5.8628	-3.9362	-3.7109
	wp_t	-2.0609	-1.9277	-2.4738	-2.4606	-13.1659	-13.1644	-6.2746	-7.9354
	wpc_t	-2.3545	-3.1686	-5.0436	-5.0210	-15.0911	-15.0919	-5.8656	-8.9315
	u_t	-2.4074	-2.2669	-3.8951	-3.9019	-4.5466	-4.5663	-6.8523	-4.2221
	l_t	-2.5997	-2.5479	-4.6496	-4.7059	-7.5222	-7.5599	-3.9334	-5.1269
	y_t/l_t	-0.9840	9898.0—	-3.0787	-3.2173	-12.1875	-12.2447	-5.2667	-7.0728
	R_t^{t+1}	-1.6415	-4.5955	-4.8566	-4.8692	-14.7206	-14.7188	-6.6371	-9.8317
FR	W_t	-1.2084	-1.7584	-2.0953	-1.8559	-4.8009	-5.5982	-6.7899	-3.0826
	p_t	-1.4268	-0.4494	-2.4584	-2.5614	-3.5292	-3.6284	-5.4159	-2.7073
	pc_t	-1.3759	-0.2043	-1.4499	-1.7545	-3.4128	-3.6455	-7.4692	-2.4470
	wp_t	-1.0950	-1.1186	-4.9178	-5.9839	-10.0701	-11.3330	-5.7372	-6.2882
	wpc_t	-0.0654	-0.5968	-0.9790	-6.4609	-11.1015	-12.7390	-5.7901	-6.9880
	u_t	-2.5157	-2.1399	-2.3885	-2.3804	-9.2488	-9.3036	-5.1267	-6.4811
	I_t	-2.2237	-1.6589	-2.4855	-2.6285	-7.8215	-8.0620	-5.9762	-5.3654
	y_t/l_t	-1.8362	-2.3646	-6.11116	-6.3673	-14.8394	-14.9942	-5.3932	-9.2897
	R_t^{t+1}	-2.8153	-6.0777	-7.3726	-7.3692	-20.7181	-20.7155	-6.2498	-10.4124

Table 6. Continued

		$\mathop{\mathrm{Level}}_{DF_{tr}}$	Z_{tr}	1st differer DF_{cst}	DE_{tr}	Z_{cst}	Z_{tr}	$rac{2}{D} F_{cst}$ difference	Z_{cst}
3		0 1 400	0000	3003 0	()(()	3011.01	20 7173	2012	03000
z 5	V,	-0.1499	-0.2089	C00C.8-	-5.2205	-19.1125	-20.01/3	-2.01/0	-8.2838
þ	٦,	-1.2499	-0.9359	-3.5472	-3.5745	-6.0524	-6.0971	-5.1118	-4.5385
<i>A</i>	c_t	-1.4118	-0.6181	-2.4384	-2.5397	-8.4869	-8.5737	-3.3256	-6.2894
. =	v p,	-2.5072	-2.0028	-7.9615	-8.6779	-18.7870	-19.6340	-6.4307	-8.6394
z	wpc_t	-1.2884	-1.1355	-8.1404	-5.4314	-20.2178	-21.4309	-5.9192	-8.9585
n	ىي ا	-2.3198	-1.8500	-3.6825	-3.6690	-7.2390	-7.2384	-5.0055	-5.1489
l,		-2.5853	-1.7999	-4.4155	-4.4055	-13.0630	-13.1264	-6.4517	-6.0712
7	ν_t/l_t	-1.5402	-1.7753	-7.0574	-7.4031	-13.9536	-14.3555	-5.1193	-7.7085
4	Q_t^{t+1}	-3.1377	-8.1322	-4.8117	-4.8279	-16.3410	-16.3410	-5.8247	-10.0554

Appendix C: Cointegration analysis

All the results are obtained using the full sample for each country. For each case, we consider the estimation of the cointegrating vectors by means of the following estimation methods:

- 1. OLS: CRDW is the cointegration Durbin Watson statistic and Z is Phillips-Oulliaris test for the null of no-cointegration based on the OLS estimation of the cointegration regression. The 5% critical value is approximately equal to -3.64.
- 2. Fully Modified LS (Phillips and Hansen (1990)) where the long run variance/covariance matrix used to perform the non-parametric correction is estimated using a Quadratic Spectral kernel function and the bandwidth parameter is automatically selected following Andrews and Monahan (1992). We consider both the case with and without pre-whitening by means of a AR(1) filter.
- 3. CCR: the same applies than for FMLS

For the test statistics we report:

- 1. Phillips-Ouliaris Z tests computed with a quadratic spectral kernel and where the bandwidth parameter is again automatically selected both with or without pre-whitening,
- 2. Park (1990)'s H (p, q) test which test the null hypothesis that the cointegration residuals are well characterized by a *pth* order trend stationary process against an alternative of *qth* order trend polynomial. We computed both the statistics using the CCR and the FMLS residuals. These test statistics are asymptotically $\chi^2(p-q)$ distributed under the null. H(0,1) is a test of the null hypothesis of deterministic cointegration since the restrictions tested implies that the cointegrating vector eliminates both the stochastic and the deterministic trends.
- 3. Hansen (1992a) test for parameter constancy among which the Lc tests which test the null of a unique cointegrating vector with constant parameters.

Ta	hl	e '	7.	O	LS

	Cnst	$(1-\sigma)\mu$	σ	CRDW	Z-prew	Z-noprew
US	-0.2147 (0.0038)	0.0082 (0.0001)	0.2916 (0.0332)	0.4154	-3.5791	-3.6929
UK	-0.1367 (0.0123)	0.0056 (0.0003)	0.7273 (0.0514)	0.2943	-2.7997	-2.8731
FR	-0.1546 (0.0109)	0.0047 (0.0003)	0.6190 (0.0381)	0.6291	-4.5818	-4.6995
GY	-0.1162 (0.0110)	0.0055 (0.0003)	0.4036 (0.0272)	0.3991	-3.0743	-3.2584

Table 7. Continued

FMLS	- Prewhitening							
	Cnst	$(1-\sigma)\mu$	σ	Lc	MeanF	SupF		
US	-0.2148	0.0082	0.3203	0.3915	3.5810	6.4833		
	(0.0104)	(0.0002)	(0.0917)					
UK	-0.0796	0.0042	0.9752	0.3940	4.2062	9.9182		
	(0.0436)	(0.0011)	(0.1830)					
FR	-0.1488	0.0047	0.6009	0.4314	8.4793	12.7324		
	(0.0233)	(0.0007)	(0.0829)					
GY	-0.0847	0.0049	0.4259	0.2242	2.5970	5.1924		
	(0.0367)	(0.0010)	(0.0921)					
FMLS	- No Prewhiter							
	Cnst	$(1-\sigma)\mu$	σ	Lc	MeanF	SupF		
US	-0.2165	0.0083	0.2865	0.3444	2.9204	5.6111		
	(0.0105)	(0.0002)	(0.0929)					
UK	-0.1097	0.0049	0.8476	0.5917	4.4923	8.2295		
	(0.0337)	(0.0008)	(0.1414)					
FR	-0.1568	0.0047	0.6264	0.2522	2.9542	6.6024		
CM	(0.0263)	(0.0008)	(0.0933)	0.2054	4.1.440	7.01.42		
GY	-0.0893	0.0050	0.4275	0.3954	4.1440	7.0142		
	(0.0290)	(0.0008)	(0.0727)					
CCR -	Prewhitening							
	Cnst	$(1-\sigma)\mu$	σ	H(0,1)	H(0, 2)	H(1,2)		
US	-0.2150	0.0082	0.3178	2483.9183	2515.3571	0.2192		
	(0.0104)	(0.0002)	(0.0894)					
UK	-0.0962	0.0046	0.8973	26.2352	65.5756	5.6935		
	(0.0377)	(0.0009)	(0.1514)					
FR	-0.1481	0.0047	0.6043	44.4013	76.0244	7.0169		
	(0.0238)	(0.0007)	(0.0824)					
GY	-0.0850	0.0049	0.4248	28.2294	102.7034	13.1393		
	(0.0353)	(0.0009)	(0.0867)					
CCR – No prewhitening								
	Cnst	$(1-\sigma)\mu$	σ	H(0, 1)	H(0, 2)	H(1, 2)		
US	-0.2165	0.0083	0.2864	2512.8058	2637.2042	0.4190		
	(0.0104)	(0.0002)	(0.0882)					
UK	-0.1121	0.0050	0.8359	39.7712	99.5992	8.3497		
	(0.0324)	(0.0008)	(0.1342)					
FR	-0.1572	0.0047	0.6243	35.8554	63.6070	6.6481		
	(0.0269)	(0.0008)	(0.0918)					
GY	-0.0900	0.0050	0.4254	48.2654	232.2891	27.5639		
	(0.0275)	(0.0007)	(0.0670)					

Appendix D: GMM estimates assuming a constant discount factor

Table 8. GMM estimates (case A)

	ϕ	ν	$1/\gamma$	J_{test}	$t_{\phi=1}$	SupLR
US	0.8656	0.0043	0.0340	17.2899	-3.9946	8.2732
UK	(0.0336) 0.8619	$(0.0004) \\ 0.0010$	(0.0068) 0.0155	[0.3018] 11.2143	[0.0025] -3.6652	6.6536
FR	(0.0377) 0.7542	$(0.0008) \\ 0.0011$	(0.0056) 0.0096	[0.7373] 10.9277	[0.0061] -3.7991	14.5281
CV	(0.0647)	(0.0004)	(0.0017)	[0.7577]	[0.0042]	
GY	0.8779 (0.0360)	0.0013 (0.0003)	0.0157 (0.0043)	20.9957 [0.1370]	-3.3893 [0.0130]	11.7453

Table 9. GMM estimates (case B)

	σ	$(1-\sigma)\mu$	ν	$1/\gamma$	J_{test}	SupLR
US	0.9013 (0.0980)	0.0057 (0.0009)	0.0048 (0.0003)	0.0327 (0.0087)	21.7664 [0.2425]	34.4595
UK	0.9961 (0.1074)	0.0031 (0.0014)	0.0010 (0.0008)	0.0150 (0.0060)	14.4002 [0.7027]	22.2567
FR	0.6932 (0.0929)	0.0040 (0.0016)	0.0007 (0.0005)	0.0109 (0.0021)	15.0011 [0.6619]	24.1962
GY	0.1982 (0.0630)	0.0073 (0.0014)	0.0011 (0.0002)	0.02449 (0.0053)	27.9434 [0.0629]	66.1297

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