

Strong Controllability of Networked Systems and Minimum Rank of a Graph: what can we compute ?

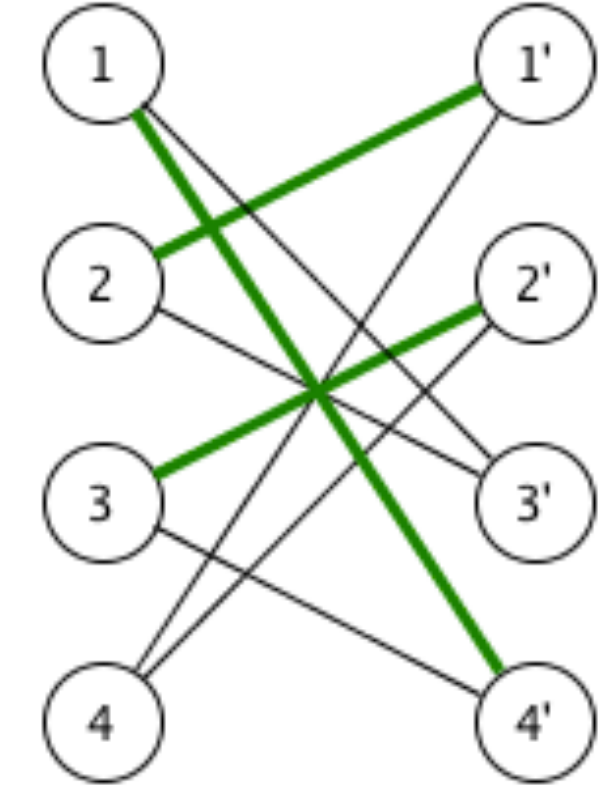
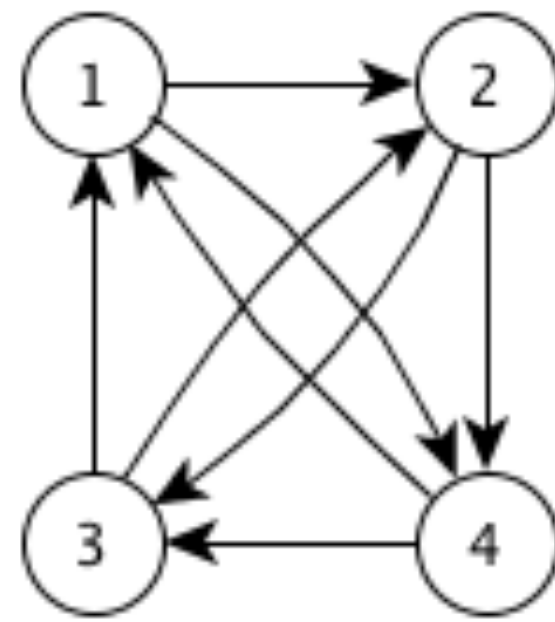
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Some equivalent objects

$$A = \begin{pmatrix} 0 & * & 0 & * \\ 0 & 0 & * & * \\ * & * & 0 & 0 \\ * & 0 & * & 0 \end{pmatrix}$$

$G(A)$:



Strong Structural Controllability

Consider the system described by the equation:

$$\dot{x}(t) = Ax(t) + B(S)u(t)$$

where the matrix $B(S)$ is such that only the nodes of $G(A)$ which are in S are directly controlled by the outside controller.

Goal: Identify a minimum number n of nodes to control in order to have full control over the system.

Definition [1]: The system $(A, B(S))$ is strongly s-controllable if ALL realizations (A, B) are controllable.

Interest: Denote $m := \min\{|S| : (A, B(S)) \text{ is strongly s-controllable}\}$. Then, $n \leq m$.

Question: How to find a set S with minimum size such that $(A, B(S))$ is strongly s-controllable ?

Tool: A maximum constraint matching in a bipartite graph

Notation: A_x is the matrix A with stars along the diagonal.

Theorem [1]: $(A, B(S))$ is strongly s-controllable iff the bipartite graphs associated to $A(S|.)$ and $A_x(S|.)$ have both a constraint matching of size $4-|S|$.

Remark: This theorem holds only if A has a zero diagonal.

Problem: Computing a maximum constraint matching (and even its size) in a bipartite graph is NP-hard.

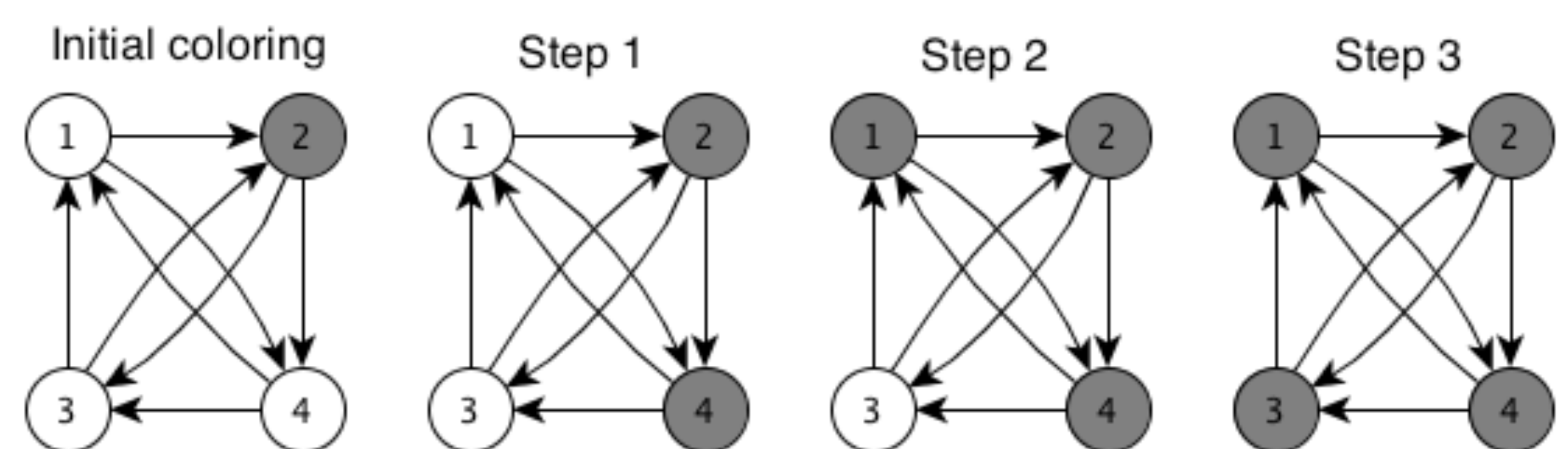
Minimum Rank of a Graph

Definition: The minimum rank of A is the minimum possible rank for a realization of A .

Question: How compute the minimum rank of A ?

Tool: The zero forcing number (ZFN) $Z(G)$ of $G(A)$

A color change rule (CCR):



Definition [2]: The ZFN of a graph is the minimum number of nodes which have to be initially black so that after the CCR the whole graph is black.

Theorem [2]: If G is a loop directed tree, $|G| - Z(G) = mr(G)$

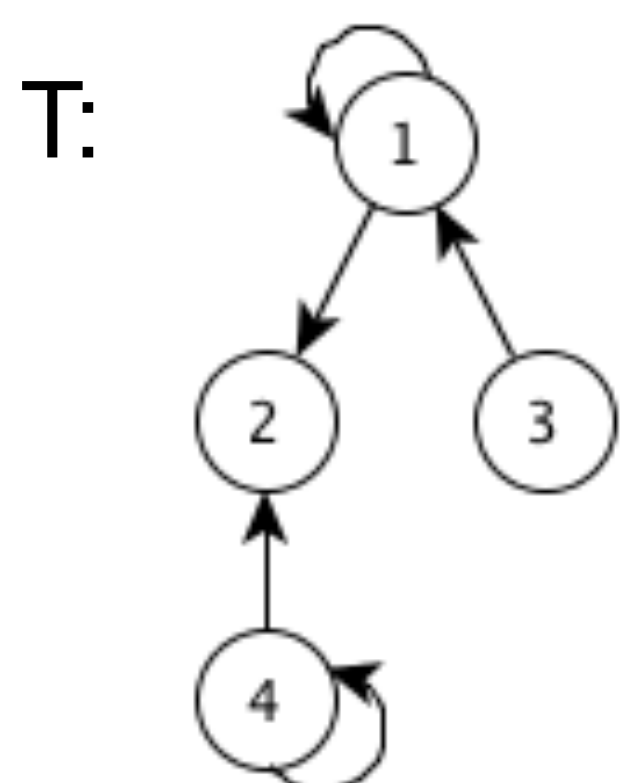
Problem: How compute $Z(G)$?

Theorem [3]: Computing $Z(G)$ is equivalent to compute the size of a maximum constraint matching in the bipartite graph associated with G .

Question: Is it easy for trees ?

Minimum Rank of a Loop Oriented Tree

Example



$$A(T) = \begin{pmatrix} * & * & 0 & 0 \\ 0 & 0 & 0 & 0 \\ * & 0 & 0 & 0 \\ 0 & * & 0 & * \end{pmatrix}$$

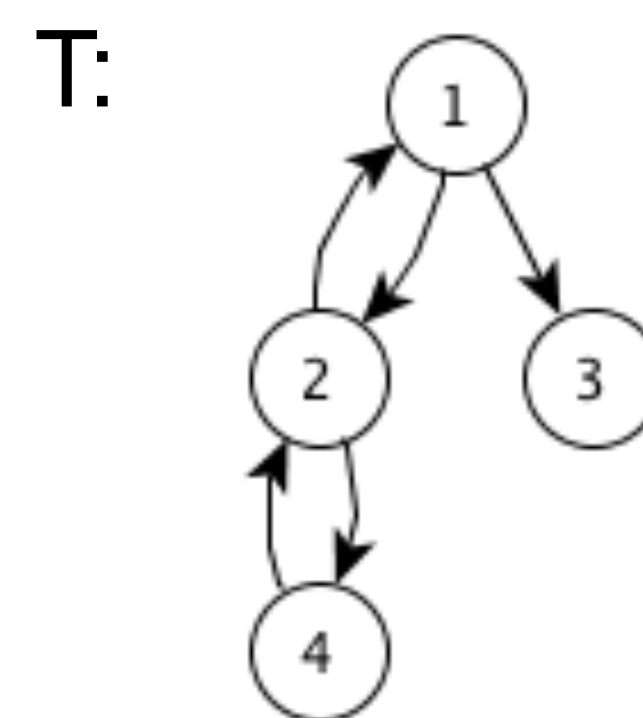
An elimination process:

$$mr(T) = mr \begin{pmatrix} * & * & 0 & 0 \\ * & 0 & 0 & 0 \\ * & 0 & 0 & 0 \\ 0 & * & 0 & * \end{pmatrix} = 1 + mr \begin{pmatrix} * & 0 & 0 \\ 0 & 0 & 0 \\ * & 0 & * \end{pmatrix} = 2 + mr \begin{pmatrix} * & 0 \\ 0 & 0 \end{pmatrix} = 3 + mr(0) = 3$$

Theorem [3]: The minimum rank of any loop oriented tree can be computed in linear time thanks to the elimination process.

Minimum Rank of an Undamped Loop Directed Tree

Example



$$A(T) = \begin{pmatrix} 0 & * & * & 0 \\ * & 0 & 0 & * \\ 0 & 0 & 0 & 0 \\ 0 & * & 0 & 0 \end{pmatrix}$$

An elimination process:

$$mr(T) = mr \begin{pmatrix} 0 & * & * & 0 \\ * & 0 & 0 & * \\ 0 & 0 & 0 & 0 \\ 0 & * & 0 & 0 \end{pmatrix} = 1 + mr \begin{pmatrix} 0 & * & * \\ 0 & 0 & 0 \\ 0 & * & 0 \end{pmatrix} = 2 + mr \begin{pmatrix} 0 & * \\ 0 & 0 \end{pmatrix} = 3 + mr(0) = 3$$

Theorem: The minimum rank of any undamped loop directed tree can be computed in linear time thanks to the elimination process.

Conclusion

If $A(S|.)$ and $A_x(S|.)$ are (a disjoint union of) loop oriented trees, then the strong s-controllability of the system $(A, B(S))$ can be studied in linear time.

References

- [1] A. Chapman, M. Mesbahi, Strong structural controllability of networked dynamics, in American Control Conference, 2013.
- [2] L. Hogben, Minimum rank problems, Linear Algebra Appl., 432(8) (2010), pp. 1961-1974.
- [3] M. Trefois, J.-C. Delvenne, Zero forcing sets, constraint matchings and minimum rank, submitted, 2013.