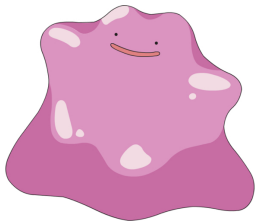
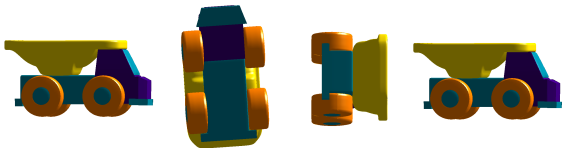


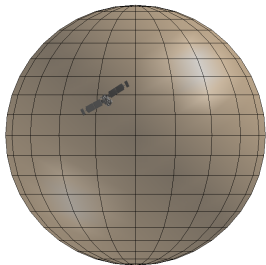
# About interpolation on manifolds...



About interpolation on manifolds...



About interpolation on manifolds...

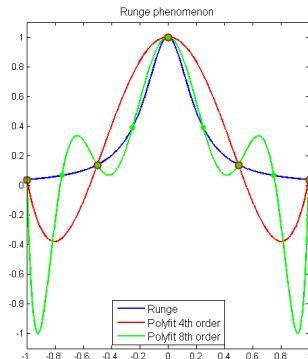
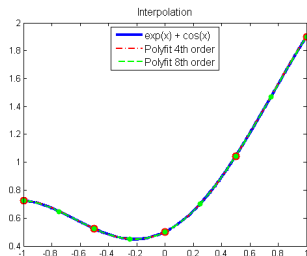


# How to interpolate points on curved spaces ?

Light fast general good looking interpolation

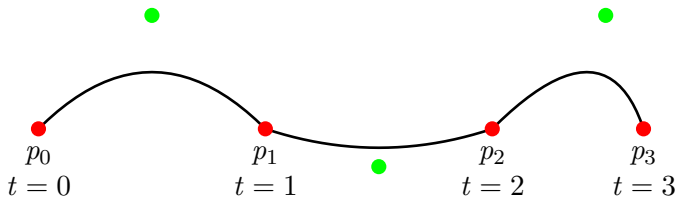
# About interpolation on manifolds...

The Euclidean space is a manifold too but with many solutions for interpolation.



# How to interpolate?

Each segment between two consecutive points is a Bézier function.



**Light**

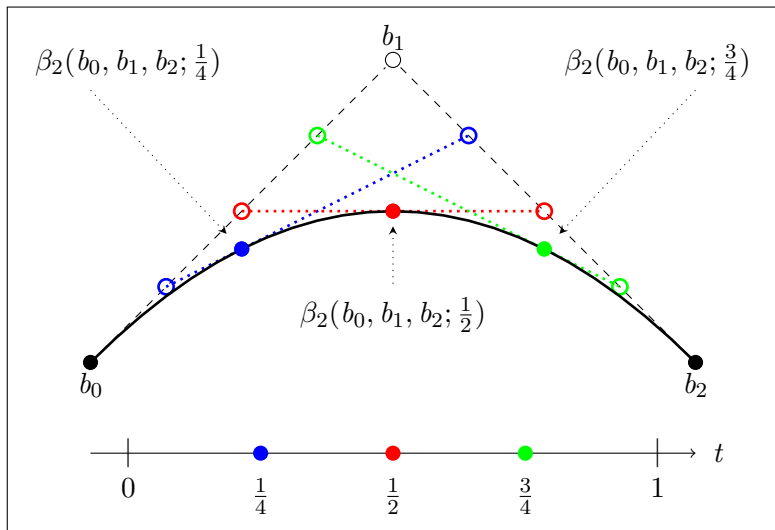
fast

general

good looking

**interpolation**

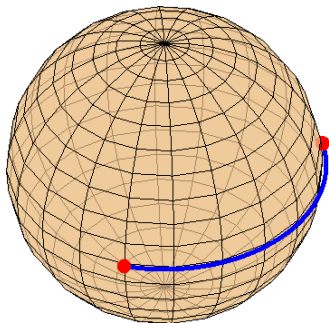
# Reconstruction : the De Casteljau algorithm



**Light**   **fast**   general   good looking   **interpolation**

# How to generalize Bézier curves to manifolds?

The straight line is a geodesic



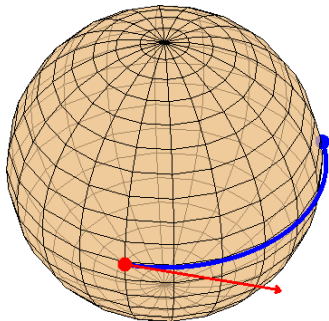




# How to generalize Bézier curves to manifolds?

The exponential map to construct the geodesic

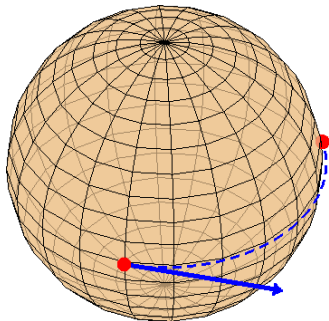
$$\gamma(t) = \text{Exp}_x(t\xi_x)$$



# How to generalize Bézier curves to manifolds?

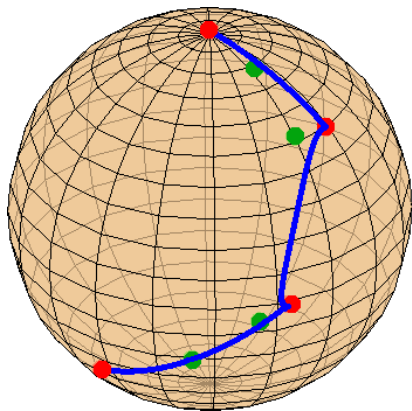
The logarithmic map to determine the starting velocity

$$\text{Log}_x(y) = \xi_x$$





# Piecewise interpolation on the sphere



Light

fast

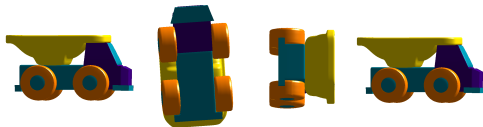
general

good looking

interpolation

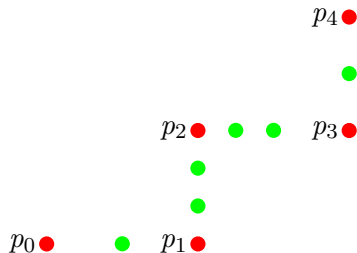
# Interpolation on Riemannian manifolds with a $C^1$ piecewise-Bézier path

Pierre-Yves Gousenbourger



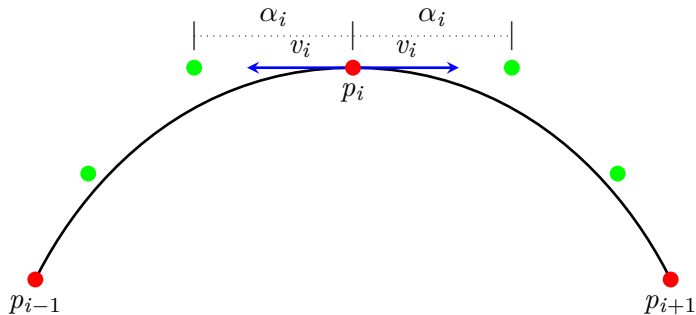
8 october 2014

# Good-looking curve on the Euclidean space



Find the optimal position of control points

# $\mathcal{C}^1$ -piecewise Bézier interpolation



$$b_i^L = \text{Exp}_{p_i}(-\alpha_i v_i)$$

$$b_i^R = \text{Exp}_{p_i}(\alpha_i v_i)$$

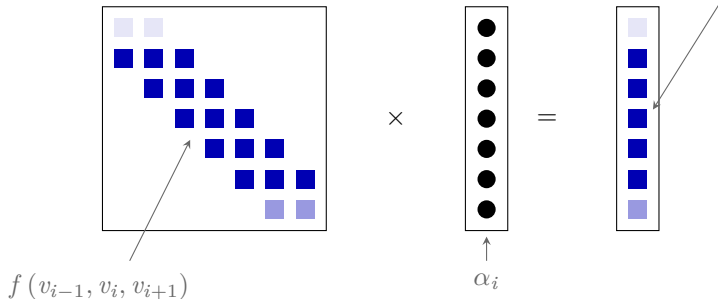


# Optimal $\mathcal{C}^1$ -piecewise Bézier interpolation

Minimization of the mean square acceleration of the path

$$\min_{\alpha_i} \|\ddot{\beta}_2^0(b_j; \mathbf{t})\|^2 + \sum_{i=1}^{n-1} \|\ddot{\beta}_3^i(b_j; \mathbf{t})\|^2 + \|\ddot{\beta}_2^n(b_j; \mathbf{t})\|^2$$

$$g(p_{i-1} - p_i, p_{i+1} - p_i, v_i)$$

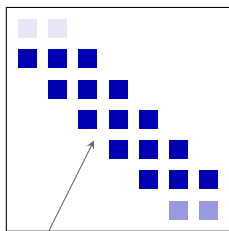


# Optimal $\mathcal{C}^1$ -piecewise Bézier interpolation

Minimization of the mean square acceleration of the path

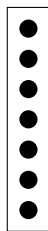
$$\min_{\alpha_i} \|\ddot{\beta}_2^0(b_j; \mathbf{t})\|^2 + \sum_{i=1}^{n-1} \|\ddot{\beta}_3^i(b_j; \mathbf{t})\|^2 + \|\ddot{\beta}_2^n(b_j; \mathbf{t})\|^2$$

$$g(\text{Log}_{p_i}(p_{i-1}), \text{Log}_{p_i}(p_{i+1}), v_i)$$



$$f(\langle v_{i-1}, v_i \rangle \cdots \langle v_{i+1}, v_i \rangle)$$

×

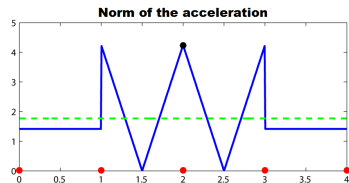
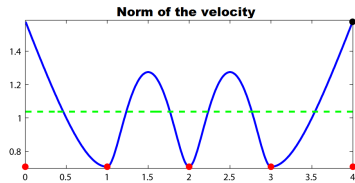
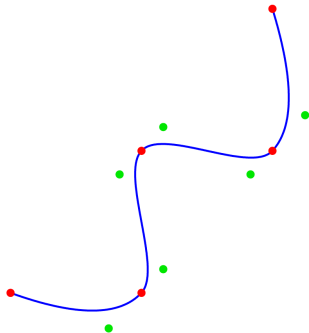


$$\alpha_i$$

=

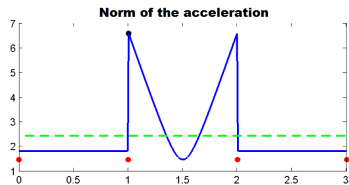
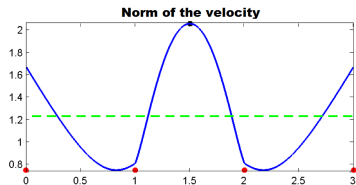
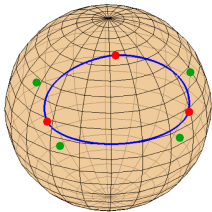


# A result on $\mathbb{R}^2$

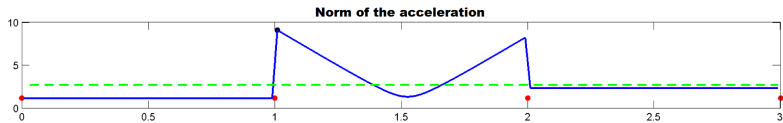
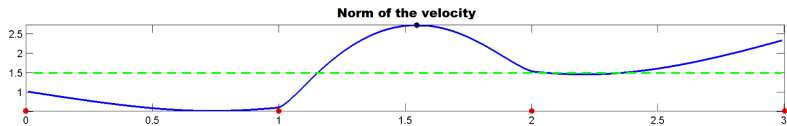


Light fast general good looking interpolation

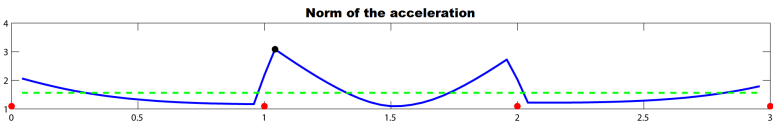
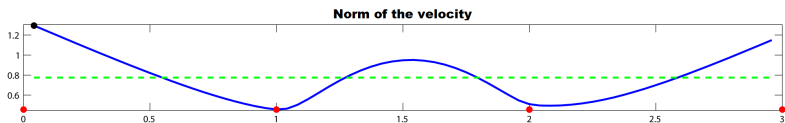
# Generalization to manifolds : the sphere $\mathbb{S}^2$



# Generalization to manifolds : the special orthogonal group $SO(3)$



# Generalization to manifolds : morphing of shapes



# Conclusions

**Light fast general good looking interpolation**

Choice of the velocities  $v_i$  ?

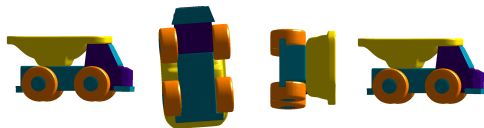
Application to manifolds of high dimension ?

Other methods, different from Bézier ?

Any questions ?

# Interpolation on Riemannian manifolds with a $C^1$ piecewise-Bézier path

Pierre-Yves Gousenbourger



8 october 2014