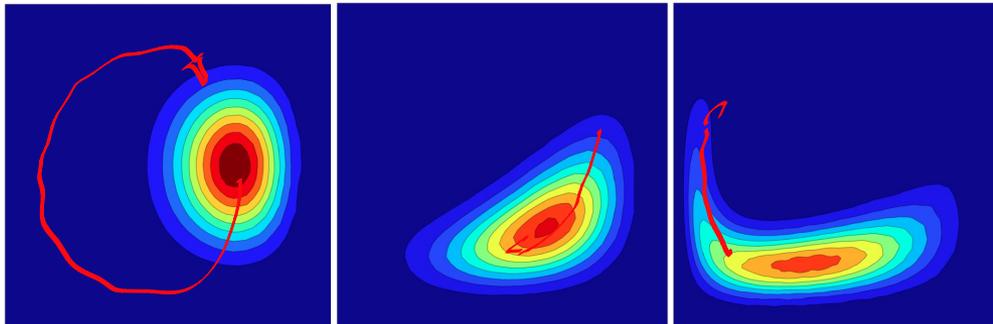
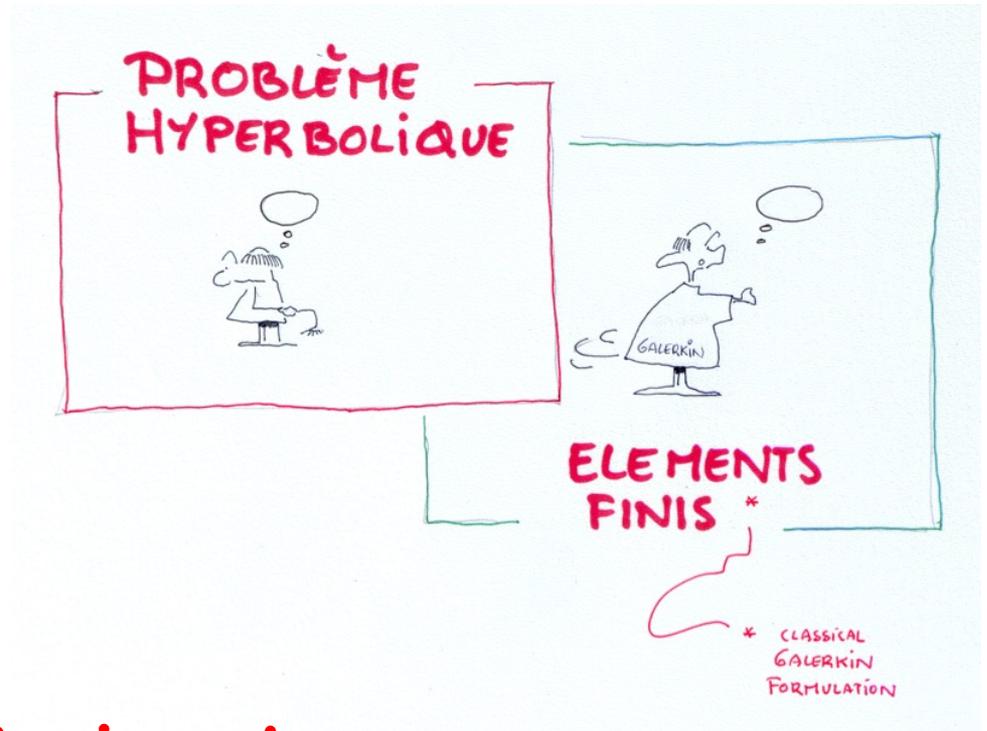
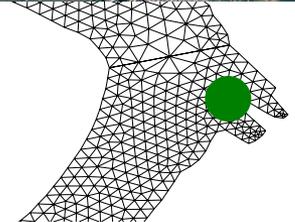
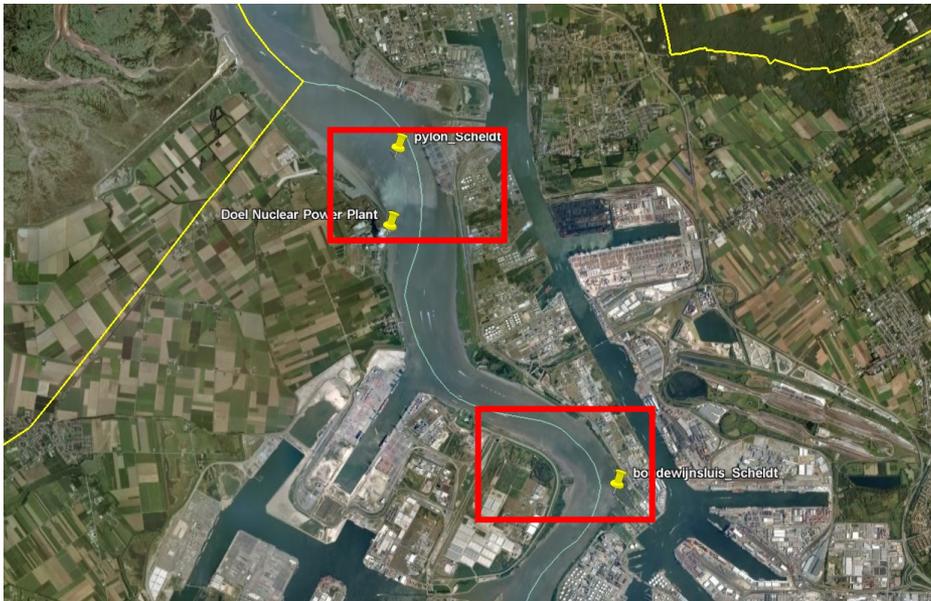
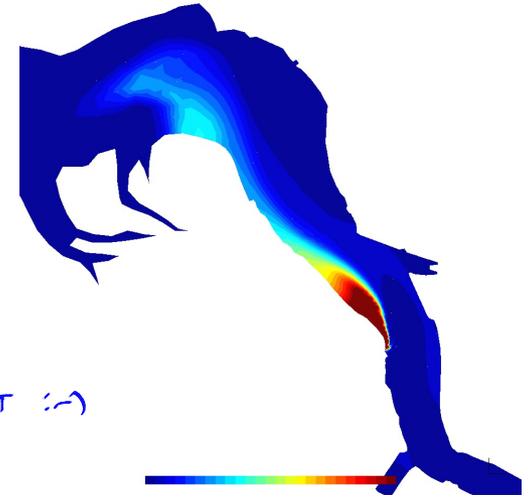
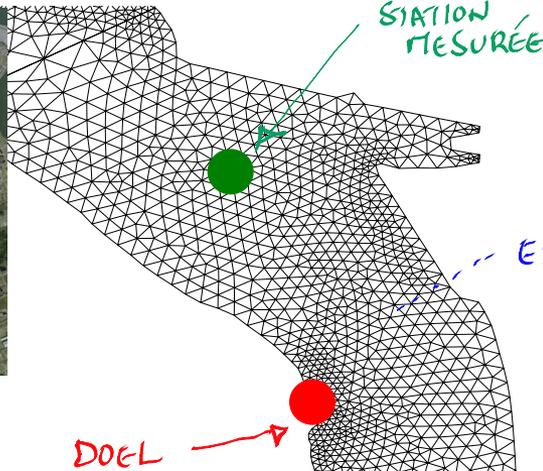


Galerkin, c'était donc optimal pour des équations elliptiques

Mais,  
plus pour des  
équations  
d'advection diffusion !



# Un petit exemple concret



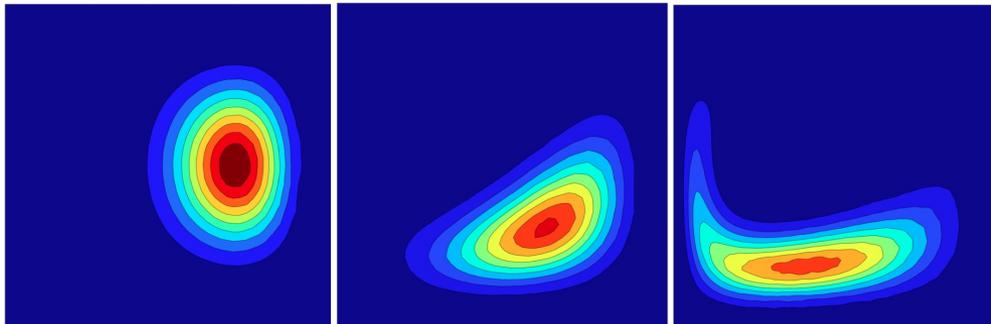
# Diffusion et transport d'un traceur passif

MOYENNE DE LA CONCENTRATION SUR LA PROFONDEUR

COEFFICIENT DE DIFFUSION

$$\frac{\partial c}{\partial t} + \underbrace{\vec{u} \cdot \nabla c}_{\text{TERME DE TRANSPORT}} = \underbrace{\nabla \cdot (D \nabla c)}_{\text{TERME DE DIFFUSION}} + S$$

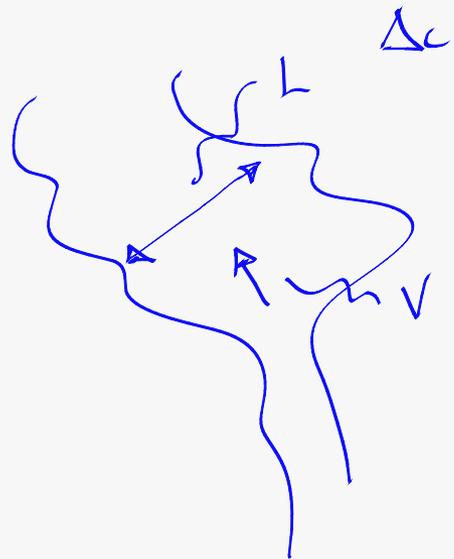
$\vec{u}$  = VITESSE HORIZONTALE



C'est une équation parabolique du second ordre !

Ce n'est pas elliptique !

$$\frac{\partial c}{\partial t} + \underbrace{u \frac{\partial c}{\partial x} + v \frac{\partial c}{\partial y}}_{\partial \left( \frac{V \Delta c}{L} \right)} = \underbrace{k \left[ \frac{\partial^2 c}{\partial x^2} + \frac{\partial^2 c}{\partial y^2} \right]}_{\partial \left( \frac{k \Delta c}{L^2} \right)} + f$$



$$\frac{Pe}{\text{PECLET}} = \frac{\boxed{\text{advection}}}{\boxed{\text{diffusion}}} = \frac{\cancel{V} \Delta c}{\cancel{k} \Delta c} \frac{\cancel{L}^2}{L} = \frac{VL}{k}$$

PECLET

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2}$$

STATIONNAIRE

INSTATIONNAIRE

$$Pe = \frac{VL}{k}$$

$Pe$  PETIT

$$0 = k \frac{\partial^2 c}{\partial x^2} \quad \boxed{\text{ELLIPT}} \quad \boxed{2}$$

$$\frac{\partial c}{\partial t} = k \frac{\partial^2 c}{\partial x^2} \quad \boxed{\text{PARA}} \quad \boxed{2}$$

$$v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2} \quad \boxed{\text{ELLIPT}} \quad \boxed{2}$$

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2} \quad \boxed{\text{PARA}} \quad \boxed{2}$$

$Pe$  GRAND

$$v \frac{\partial c}{\partial x} = 0$$

$\boxed{\text{HYP}}$

$\boxed{1}$

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = 0$$

$\boxed{\text{HYP}}$

$\boxed{1}$

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2}$$

$P_e$  PETIT

STATIONNAIRE

$$0 = k \frac{\partial^2 c}{\partial x^2}$$

ELL  
2

$$v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2}$$

ELL  
2

$P_e$  GRAND

$$v \frac{\partial c}{\partial x} = 0$$

HYP  
1

INSTATIONNAIRE

$$\frac{\partial c}{\partial t} = k \frac{\partial^2 c}{\partial x^2}$$

PARA  
2

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2}$$

PARA  
2

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = 0$$

HYP  
1

Le nombre de Péclet permet d'estimer l'importance du terme de transport par rapport à celui de la diffusion !

$$P_e = \frac{vL}{k}$$

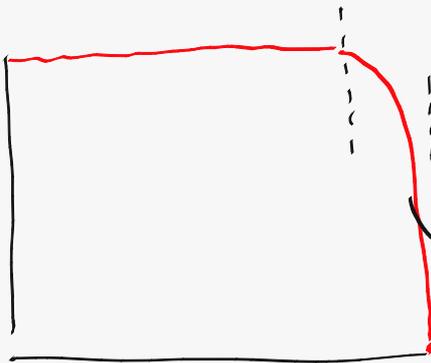
$$\beta \frac{du}{dx} - \epsilon \frac{d^2u}{dx^2} = 0$$

$$u(x) = C \exp\left[\frac{\beta x}{\epsilon}\right]$$

$$\epsilon u'' = \frac{\beta^2}{\epsilon^2} \epsilon \exp[\ ] C$$

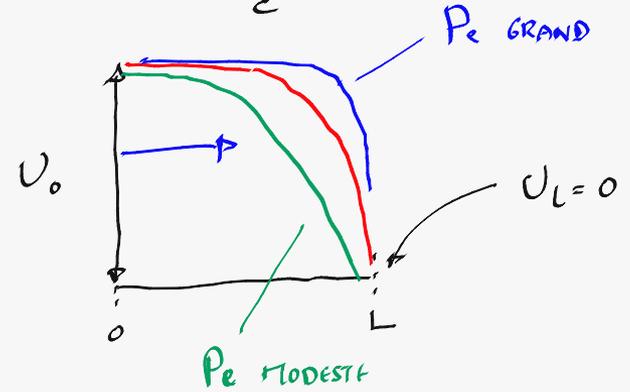
$$\beta u' = \frac{\beta}{\epsilon} \beta \exp[\ ] C$$

$$\frac{u(x) - U_0}{U_L - U_0} = \frac{\exp(\beta x / \epsilon) - 1}{\exp(\beta L / \epsilon) - 1}$$



COUCHE LIMITE  $\mathcal{O}\left(\frac{L}{Pe}\right)$

$$Pe = \frac{\beta L}{\epsilon} \quad \beta > 0$$



$$\epsilon \frac{d^2u}{dx^2} = 0$$

$$\beta \frac{du}{dx} = 0$$

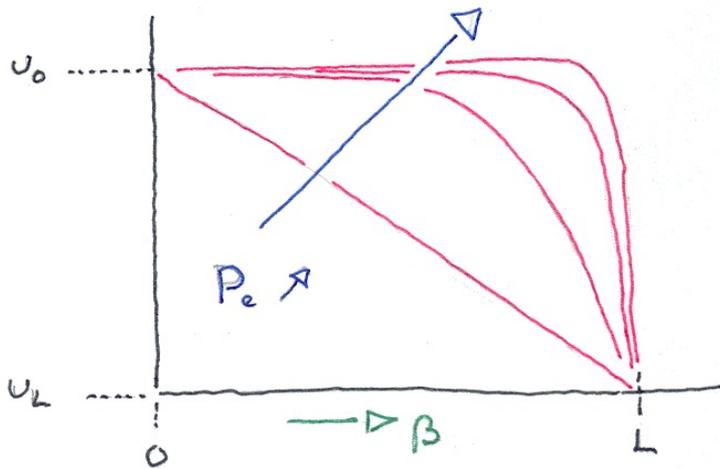


# EQUATION D'ADVECTION - DIFFUSION

$$\beta \frac{du}{dx} - \epsilon \frac{d^2u}{dx^2} = 0$$

$$u(0) = u_0$$

$$u(L) = u_L$$



$$P_e = \frac{\beta L}{\epsilon}$$

$$\frac{u - u_0}{u_L - u_0} = \frac{\exp\left(\frac{\beta x}{\epsilon}\right) - 1}{\exp\left(\frac{\beta L}{\epsilon}\right) - 1}$$

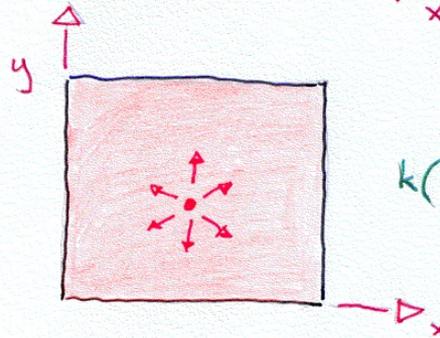
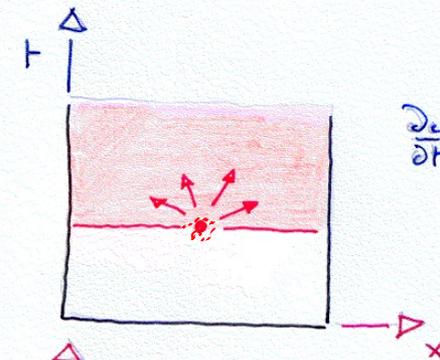
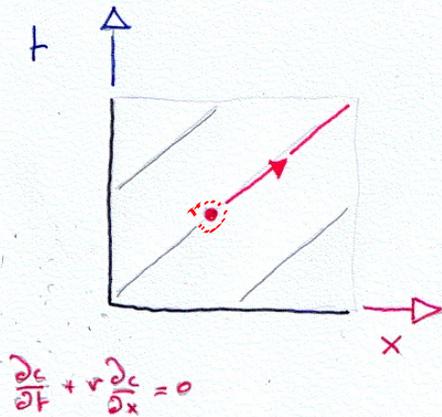
$P_e \times /L$

$P_e$

# PROBLEME BIEN POSE

→ CONDITIONS  
AUX LIMITES

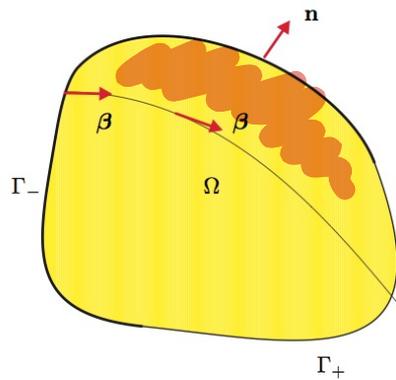
$$\rho c \frac{\partial T}{\partial t} = k \frac{\partial^2 T}{\partial x^2}$$



$$\frac{\partial^2 T}{\partial t^2} + \frac{\partial^2 T}{\partial x^2} = 0$$

$$\frac{\partial^2 T}{\partial t^2} = c^2 \frac{\partial^2 T}{\partial x^2}$$

# Advection pure

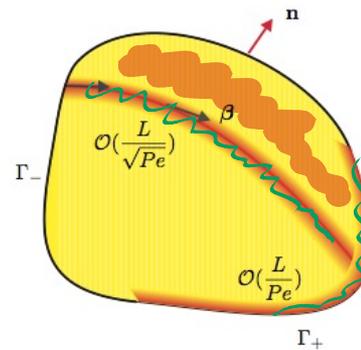


Trouver  $u(\mathbf{x})$  tel que

$$\beta \cdot \nabla u = f, \quad \forall x \in \Omega,$$

$$u = 0, \quad \forall x \in \Gamma_-$$

$$\frac{d\mathbf{x}}{ds}(s) = \beta(\mathbf{x}, s)$$



Trouver  $u(\mathbf{x}) \in \mathcal{U}_s$  tel que

$$\beta \cdot \nabla u - \nabla \cdot (\epsilon \nabla u) = f, \quad \forall \mathbf{x} \in \Omega,$$

$$\mathbf{n} \cdot (\epsilon \nabla u) = g, \quad \forall \mathbf{x} \in \Gamma_N,$$

$$u = t, \quad \forall \mathbf{x} \in \Gamma_D,$$

$$\frac{d\mathbf{x}}{ds}(s) = \beta(\mathbf{x}, s)$$

# Advection-diffusion



# EQUATION DE TRANSPORT

$$\frac{du}{dx} = f$$
$$u(0) = u_0$$

$$u \approx u_h = \sum_i U_i \tau_i(x)$$


## GALERKIN

?  $U_i$  TELS QUE

$$\langle \tau_i, \Gamma_h \rangle = 0$$

$$\sum_j \underbrace{\langle \tau_i, \tau_j, x \rangle}_{A_{ij}} U_j = \underbrace{\langle \tau_i, f \rangle}_{B_i}$$

≠  
MATRICE  
DEFINIE  
POSITIVE !

CE PETIT  
 RAPPEL EST  
 DEDIE A BENOIT  
 ET LEA :-)

$$u'' + f = 0$$

$$u(0) = u(1) = 0$$

$$u_h \approx \sum U_i \tau_i$$

$$\underbrace{(u_h)'' + f}_{r_h} \approx 0$$

METHODE  
 GALERKIN!

$$\langle r_h, \tau_i \rangle = 0$$

LES ELEMENTS  
 FINIS  
 SONT UNE  
 METHODE  
 VARIATIONNELLE

$$\langle \sum U_j \tau_{j,xx} \tau_i + f \tau_i \rangle = 0$$

$$\sum U_j \langle \tau_{j,xx} \tau_i \rangle + \langle f \tau_i \rangle = 0$$

$$- \langle \tau_{j,x} \tau_{i,x} \rangle$$

$$\sum U_j \underbrace{\langle \tau_{j,x} \tau_{i,x} \rangle}_{A_{ij}} = \underbrace{\langle f \tau_i \rangle}_{B_i}$$

LES  
 ELEMENTS  
 FINIS SONT  
 UNE METHODE  
 DE RESIDUS  
 PONDRES

TRANSPORT  
FOR :-)

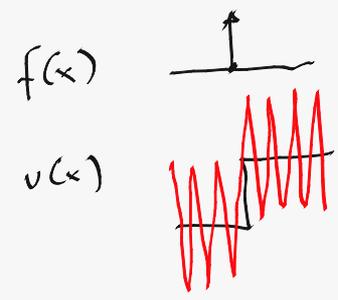
$$\boxed{\frac{dv}{dx} \approx f}$$

$$v^h = \sum U_i \tau_i$$

$$\langle \overbrace{[(v^h)'] - f}^{r^h} \tau_i \rangle = 0 \quad \forall i$$

$$\sum U_j \underbrace{\langle \tau_{j,x} \tau_i \rangle}_{A_{ij}} = \underbrace{\langle f \tau_i \rangle}_{B_i}$$

$f(x) = \sin(x)$   
OK :-)



$$\frac{U_{j+1} - U_{j-1}}{2h} = F_j$$

CE N'EST  
PLUS UNE  
MATRICE  
SYM DEFINIE  
POSITIVE

$$\langle \overbrace{[(\phi^h)'] - f}^{rh} \tau_{i,x} \rangle = 0 \quad f_i$$

$$\sum U_j \langle \underbrace{\tau_{j,x}}_{A_{ij}} \underbrace{\tau_{i,x}}_{B_i} \rangle = \langle \underbrace{f}_{B_i} \tau_{i,x} \rangle$$



$$\frac{d^2 u}{dx^2} = \frac{df}{dx}$$

$$U_{j+1} - \frac{2U_j - U_{j-1}}{h^2} = \frac{F_j - F_{j-1}}{h}$$

LA BONNE  
SOLUTION :-)

$$U_j - \frac{U_{j-1}}{h} = F_{j-1}$$

$$\frac{du}{dx} = f$$

GALERKIN

$$\sum_j A_{ij} U_j = B_i$$

BUBNOV - GALERKIN

DIFFERENCES FINIES CENTREES

$$U_{j+1} - U_{j-1} = B_j \cdot 2\Delta x$$



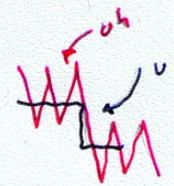
PROBLEME DE MINIMISATION

$$f(x) = \sin(x)$$

$$f(x) = \uparrow$$

OK

"Bout"



# PETROV-GALERKIN

?  $U_j$  TELS QUE

$$\langle \tau_{j,x} | r^h \rangle = 0$$

0 →  $\Delta$   
 INTEGRATION  
 LE LONG DES  
 CARACTERISTIQUES

$\Delta$

DIFFERENCES  
 FINIES  
 AMONT

$$U_{j+1} - U_j = B_j \Delta x$$

$$\sum_j \underbrace{\langle \tau_{i,x} | \tau_{j,x} \rangle}_{A_{ij}} U_j = \underbrace{\langle \tau_{i,x} | f \rangle}_{B_i}$$

MATRICE  
 DEFINIE  
 POSITIVE

1 CONDITION  
 AUX LIMITES !

$\frac{du}{dx} = f$

A ÉTÉ  
 REMPLACÉ PAR

2 CONDITIONS  
 AUX LIMITES !

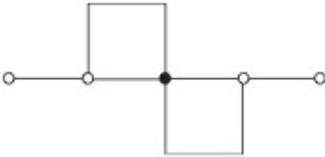
HIC

$\frac{d^2 u}{dx^2} = \frac{df}{dx}$

# En bref :-)

$$\frac{du}{dx} = f,$$

$$u(0) = 0,$$

<p>Galerkin <math>w_i = \tau_i</math></p> 	<p><i>Différences finies centrées</i></p> <p>Simple et donc tentant... Oscillations numériques si <math>f</math> n'est pas lisse !</p> $\frac{U_{i+1} - U_{i-1}}{2h} = \frac{F_{i+1} + 4F_i + F_{i-1}}{6},$
<p>Petrov-Galerkin <math>w_i = \tau_{i,x}</math></p> 	<p><i>Différences finies centrées d'ordre deux</i></p> <p>Mathématiquement, tentant Condition frontière parasite !</p> $\frac{U_{i+1} - 2U_i + U_{i-1}}{h^2} = \frac{F_{i+1} - F_{i-1}}{2h},$
<p>Petrov-Galerkin <math>w_i = \tau_{i-1}^{cst}</math></p> 	<p><i>Différences finies amont</i></p> <p>Quasiment optimal... Correspond à une intégration le long de la caractéristique, Pas d'oscillation numérique</p> $\frac{U_i - U_{i-1}}{h} = \frac{F_{i+1} + F_{i-1}}{2},$

# PETROV GALERKIN $\hat{u}_i$

$$u^h = \sum U_j \tau_j$$

$$\langle (\tau_i + \zeta \tau_{i,x}) (u_{,x}^h - \varepsilon u_{,xx}^h - f) \rangle = 0$$

$$\sum_j U_j \left[ \begin{array}{l} + \zeta \langle \tau_{i,x} \tau_{j,x} \rangle - \varepsilon \zeta \langle \tau_{i,x} \tau_{j,xx} \rangle \\ + \varepsilon \langle \tau_{i,x} \tau_{j,x} \rangle + \langle \tau_i \tau_{j,x} \rangle \end{array} \right] = \dots$$

DEFINI  
POSITIF



PAS DEFINI  
POSITIF :-)



$\zeta \rightarrow$  COTE POSITIF  $\nearrow$   
 COTE NEGATIF  $\nearrow$   
 Si  $u^h$  LINEAIRE PAR MORCEAUX!  
 $\tau_{j,xx} = 0$

# PETROV-GALERKIN

$$\langle (\tau_c + \zeta \tau_{c,x}) (u_{,x}^h - \epsilon u_{,xx}^h - f) \rangle = 0$$

$\Gamma^h$

$\hat{\tau}_c$

How TO SELECT  $\zeta$  ?

2D

$$\hat{\tau}_c = \tau_c + \zeta \beta \cdot \nabla \tau_c$$

STREAMLINE UPWINDING

$$\sum_j ( \zeta \langle \tau_{c,x} \tau_{j,x} \rangle - \epsilon \zeta \langle \tau_{c,x} \tau_{j,xx} \rangle + \epsilon \langle \tau_{c,x} \tau_{j,x} \rangle + \langle \tau_c \tau_{j,x} \rangle ) U_j = \dots$$



# DIFF. CENTRÉES

$$\beta u' = \varepsilon u''$$

$$\beta \frac{U_{i+1} - U_{i-1}}{2h} = \varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$$U_i = A r^i + B$$

$$\cancel{A} r^{i-1} \underbrace{\frac{\beta h}{2\varepsilon}}_{\alpha} (r^2 - 1) = \cancel{A} r^{i-1} (r^2 - 2r + 1)$$

$$0 = \underbrace{(1 - \varepsilon)}_{\alpha} r^2 - 2r + \underbrace{(1 + \varepsilon)}_c$$

$$\begin{aligned} r &= \frac{1 \pm \sqrt{1 - \alpha c}}{\alpha} \\ &= \frac{1 \pm \sqrt{1 - 1 + (\varepsilon)^2}}{1 - \varepsilon} \\ &= \frac{1 \pm \varepsilon}{1 - \varepsilon} \end{aligned} \quad \left. \varepsilon \right\}$$

$$\varepsilon > 0$$

$$\frac{Pe^h}{2} < 1$$

C'EST OK SI

Pe<sup>h</sup> PETIT!

$$\boxed{\frac{1}{2} \frac{\beta h}{\varepsilon}} \quad | \quad (\varepsilon)$$

Pe<sup>h</sup>

Petit de taille

# DIFF DECENTRÉES

$$\beta \frac{U_i - U_{i-1}}{h} = \varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$$U_i = A r^i + B$$

$$\cancel{A} r^{i-1} \frac{\beta h}{2\varepsilon} (r^2 - 1) = \cancel{A} r^{i-1} (r^2 - 2r + 1)$$

$$0 = \underbrace{(1 - \varepsilon)}_a r^2 - 2r + \underbrace{(1 + \varepsilon)}_c$$

$$\begin{aligned} r &= \frac{1 \pm \sqrt{1 - ac}}{a} \\ &= \frac{1 \pm \sqrt{1 - 1 + (\varepsilon)^2}}{1 - \varepsilon} \\ &= \frac{1 + \varepsilon}{1 - \varepsilon} \end{aligned}$$

$$\varepsilon > 0$$

$$\frac{Pe^h}{2} < 1$$

C'EST  
OK SI

$Pe^h$  PETIT!

$$\boxed{\frac{1}{2} \frac{\beta h}{\varepsilon}} \quad | \quad (\varepsilon)$$

$Pe^h$   
PETIT  
DE HAUTE

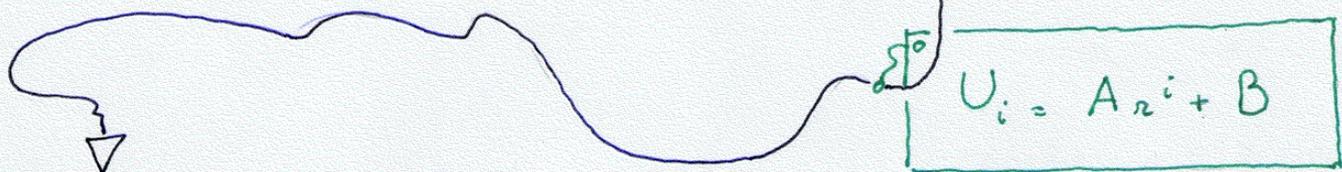
$$\frac{\beta h}{\varepsilon} (r-1)$$

# DIFF. CENTRÉES

$$\beta \frac{U_{i+1} - U_{i-1}}{2h} = \varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$U_0 = u_0$   
 $U_N = u_L$

EQUATION AUX RECURRENCES !



$$\cancel{A} r^{i-1} \underbrace{\frac{\beta h}{2\varepsilon}}_{\text{PECLET DE MAILLE}} (r^2 - 1) = \cancel{A} r^{i-1} (r^2 - 2r + 1)$$

$$\Delta \frac{P_e h}{2}$$

PECLET DE MAILLE

$$0 = \left( \frac{1 - P_e h/2}{2} \right) r^2 - r + \left( \frac{1 + P_e h/2}{2} \right)$$

$$r = \frac{1 \pm \sqrt{1 - (1 + P_e h/2)(1 - P_e h/2)}}{(1 - P_e h/2)}$$

$$r = \frac{1 + P_e h/2}{1 - P_e h/2}$$

REJECT  $r=1$  OF COURSE !

$$\frac{U_i - v_0}{v_h - v_0} = \frac{\left( \frac{1 + P_e h/2}{1 - P_e h/2} \right)^i - 1}{\left( \frac{1 + P_e h/2}{1 - P_e h/2} \right)^N - 1}$$

$$\approx \exp(P_e h) \cdot N$$

$$\approx \exp\left(\frac{\beta h N}{\epsilon}\right)$$

$P_e$

[SCHAUM p 551]

$$\frac{x}{e^x - 1} \approx 1 - \frac{x}{2}$$

$$\left(1 + \frac{x}{2}\right) = e^x \left(1 - \frac{x}{2}\right)$$

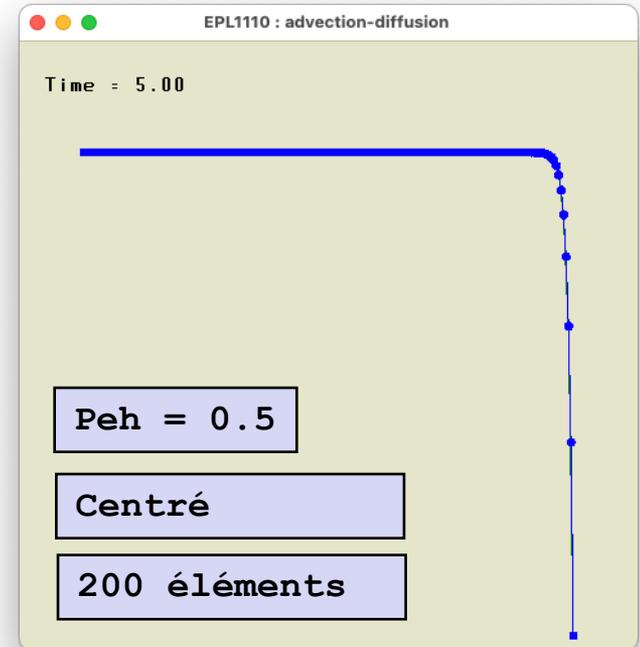
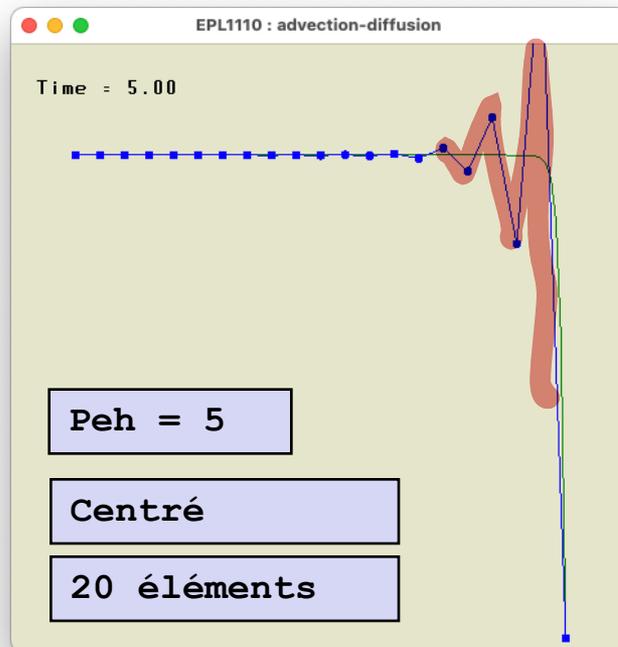
$\frac{P_e h}{2} < 1$

TO AVOID  
OSCILLATORY  
BEHAVIOUR

# Galerkin converge si on raffine le maillage suffisamment !

`epsilon = 0.01;`  
`beta = 1.0;`

L'équation d'advection-diffusion est formellement une équation elliptique et donc c'était prévisible par la théorie !



# UPWIND DIFF.

$$\beta \frac{U_i - U_{i-1}}{h} = \varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$$U_0 = u_0$$

$$U_N = u_L$$

$\cancel{A} r^{i-1} \underbrace{\frac{\beta h}{\varepsilon}}_{\triangleq Pe^h} (\pi - 1) = \cancel{A} r^{i-1} (\pi^2 - 2\pi + 1)$

$$0 = \frac{\pi^2}{2} - (1 + Pe^h/2)\pi + \frac{(1 + Pe^h)}{2}$$

$$\pi = \frac{(1 + Pe^h/2) \pm \sqrt{(1 + Pe^h/2)^2 - (1 + Pe^h)}}{Pe^h/2}$$

$$= 1 + Pe^h$$

$$\frac{U_i - u_0}{u_L - u_0} = \frac{(1 + Pe^h)^i - 1}{(1 + Pe^h)^N - 1}$$

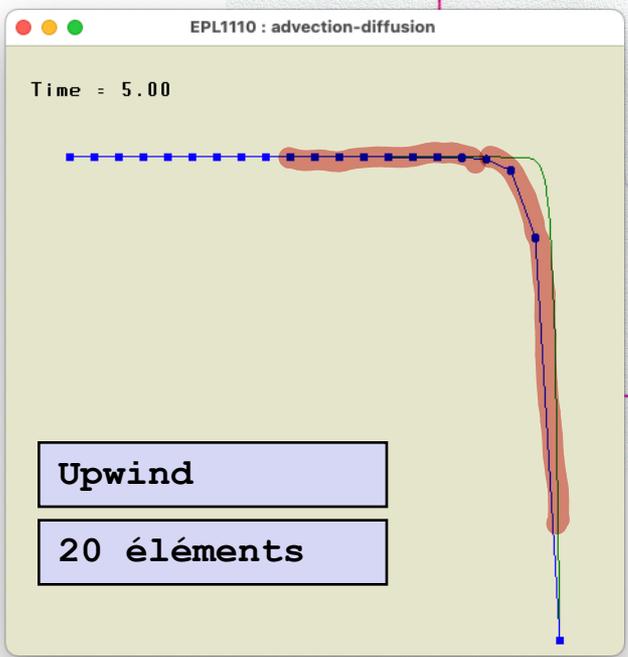
$(1 + Pe^h) > 0$   
 $\forall h$   
 NO OSCILLATIONS

**BUT...**

NUMERICAL  
DIFFUSION

$$\beta \frac{U_i - U_{i-1}}{h} = \epsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$$\beta \frac{U_{i+1} - U_{i-1}}{2h} - \underbrace{\frac{\beta h}{2}}_{\text{NUMERICAL DIFFUSIVITY}} \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$



# HYBRID SCHEME

$$(1-\zeta)\beta \frac{U_{i+1}-U_{i-1}}{2h} + \zeta\beta \frac{U_i-U_{i-1}}{2h} = \varepsilon \frac{U_{i+1}-2U_i+U_{i-1}}{h^2}$$

$$0 = \left(1 - \frac{(1-\zeta)P_e h/2}{2}\right) \pi^2 - \left(1 + \zeta P_e h/2\right) \pi + \left(1 + \frac{(1-\zeta)P_e h/2}{2} + \zeta P_e h/2\right)$$

$$\pi = \frac{(1 + \zeta P_e h/2) \pm \sqrt{\begin{matrix} (1 + \zeta P_e h/2)^2 \\ - (1 - (1-\zeta)P_e h/2) \cdot \\ (1 + (1+\zeta)P_e h/2) \end{matrix}}}{(1 - (1-\zeta)P_e h/2)}$$

} =  $P_e h/2$

$$\pi = \frac{1 + (1 + \zeta) P_e h/2}{1 - (1 - \zeta) P_e h/2}$$

HOW TO  
SELECT  $\zeta$ ?

$$U_i = u(ih)$$

$$\left( \frac{1 + (1 + \zeta) P_e h/2}{1 - (1 - \zeta) P_e h/2} \right)^i = \pi^i$$

$$= \underbrace{\exp\left(\frac{\beta h}{\varepsilon} i\right)}_{\left(\exp(P_e h)\right)^i}$$

$$(1 + P_e h/2) - \zeta P_e h/2 = \exp(P_e) \left( (1 - P_e h/2) + \zeta P_e h/2 \right)$$

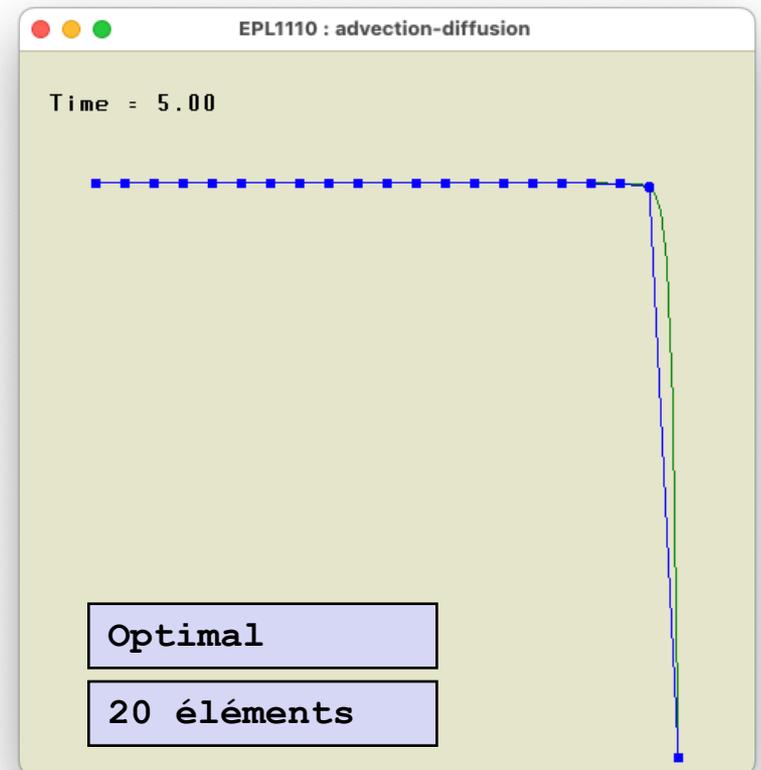
$$\begin{aligned}
 \zeta \frac{P_e h}{2} (1 - \exp(-P_e)) &= \exp(P_e^h) \left(1 - \frac{P_e^h}{2}\right) - \left(1 + \frac{P_e^h}{2}\right) \\
 &\downarrow \\
 \zeta &= \frac{\exp(P_e^h) \left(\frac{2}{P_e^h} - 1\right) - \left(\frac{2}{P_e^h} + 1\right)}{(1 - \exp(P_e^h))} \\
 &\downarrow \\
 &= \underbrace{-\frac{(1 + \exp(P_e^h))}{(1 - \exp(P_e^h))}}_{\coth(P_e^h/2)} - \frac{2}{P_e^h}
 \end{aligned}$$

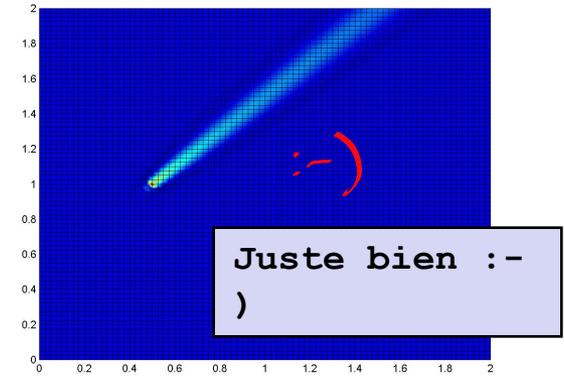
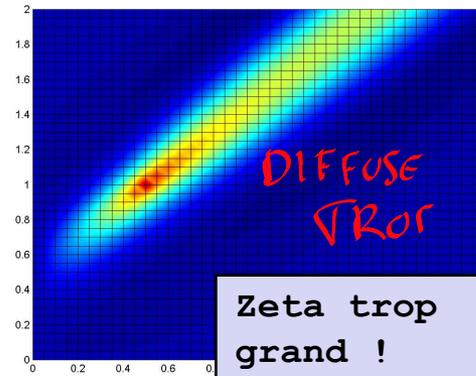
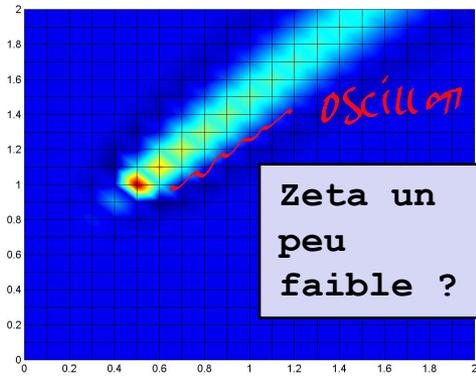
$$\boxed{\zeta = \coth\left(\frac{P_e^h}{2}\right) - \frac{2}{P_e^h}} \quad \square$$

On a trouvé  
la méthode parfaite  
pour des équations  
unidimensionnelles !

$$\zeta = \coth\left(\frac{Pe^h}{2}\right) - \frac{2}{Pe^h}$$

$$\begin{aligned}\beta \frac{du}{dx} - \epsilon \frac{d^2u}{dx^2} &= 0, \\ u(0) &= u_0, \\ u(L) &= u_L,\end{aligned}$$





En extrapolant  
aux dimensions  
supérieures...

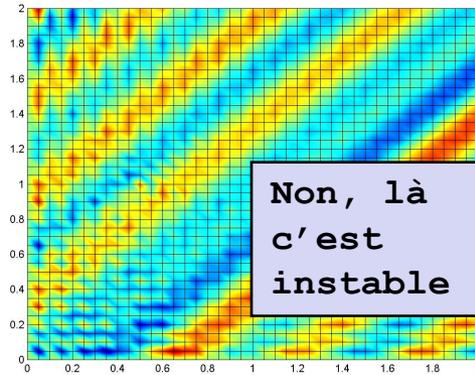
$$w_i = \tau_i + \zeta \beta \cdot \nabla \tau_i$$



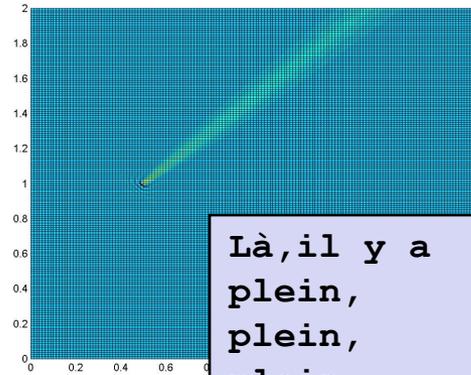
*Facteur de stabilisation*  
*Trop grand : diffusion numérique !*  
*Trop petit : instable !*

Trouver  $U_j \in \mathbb{R}^n$  tel que

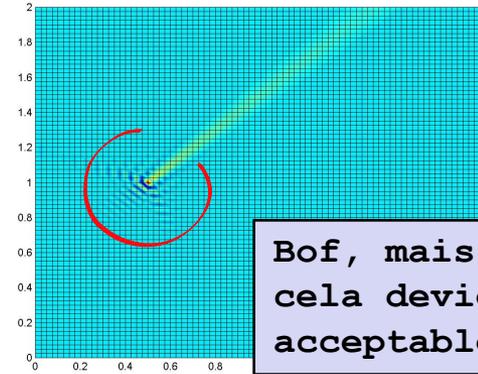
$$\sum_{j=1}^n \underbrace{\langle w_i \beta \cdot \nabla \tau_j + \epsilon \nabla w_i \cdot \nabla \tau_j \rangle}_{A_{ij}} U_j = \underbrace{\langle w_i f \rangle + \ll w_i g \gg_N}_{B_i}, \quad i = 1, \dots, n,$$



Non, là  
c'est  
instable



Là, il y a  
plein,  
plein,  
plein  
d'éléments



Bof, mais  
cela devient  
acceptable !

Et en payant le prix,  
Galerkin fonctionne !

$$w_i = \tau_i + \zeta \beta \cdot \nabla \tau_i$$



*Pas de stabilisation !  
Zeta = 0 !*

Trouver  $U_j \in \mathbb{R}^n$  tel que

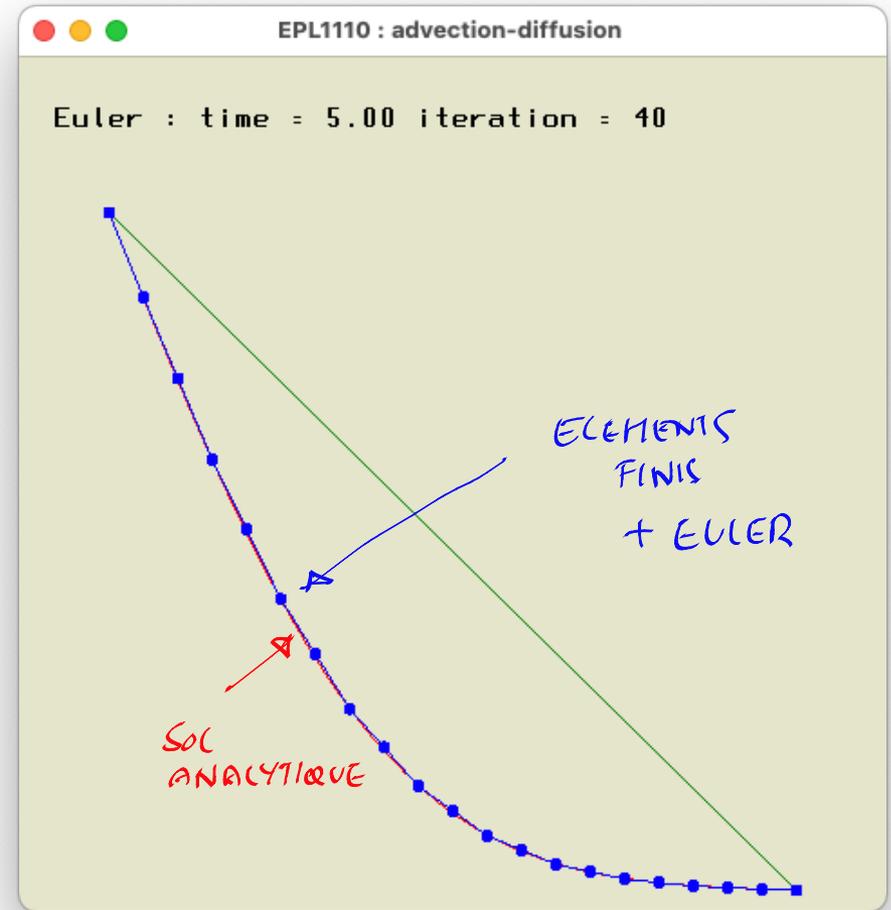
$$\sum_{j=1}^n \underbrace{\langle w_i \beta \cdot \nabla \tau_j + \epsilon \nabla w_i \cdot \nabla \tau_j \rangle}_{A_{ij}} U_j = \underbrace{\langle w_i f \rangle + \ll w_i g \gg_N}_{B_i}, \quad i = 1, \dots, n,$$

Et maintenant  
introduisons  
le temps...

$$\frac{\partial u}{\partial t} = \epsilon \frac{\partial^2 u}{\partial x^2}$$

$$u(0) = 1$$

$$u(1) = 0$$



```
epsilon = 0.01;  
L = 1
```

# Différences finies (espace) Euler explicite (temps)

$$\left(\frac{U_i^{n+1} - U_i^n}{\Delta t}\right) = \epsilon \left(\frac{U_{i+1}^n - 2U_i^n + U_{i-1}^n}{(\Delta x)^2}\right)$$

En définissant  $b = \frac{\epsilon \Delta t}{(\Delta x)^2}$ ,

$$U_i^{n+1} = U_i^n + b(U_{i+1}^n + U_{i-1}^n - 2U_i^n)$$

C'est une itération pour un vecteur qui doit converger vers la solution de régime  
C'est quelque chose qu'on a déjà rencontré...

# On intègre un système linéaire...

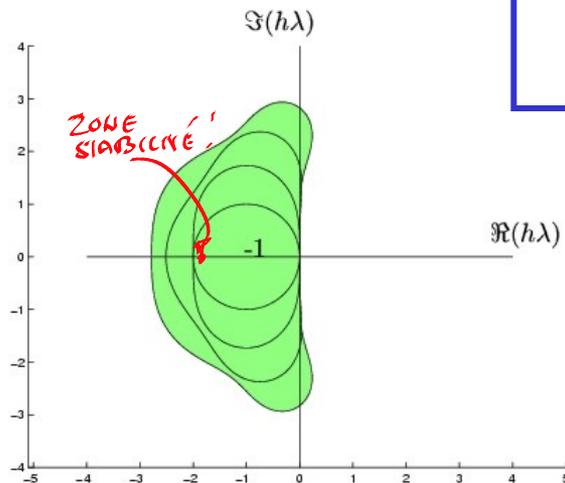
$$U_i^{n+1} = U_i^n + b(U_{i+1}^n + U_{i-1}^n - 2U_i^n)$$

En passant à une notation matricielle,

$$\begin{bmatrix} U_1^{n+1} \\ U_2^{n+1} \\ U_3^{n+1} \\ U_4^{n+1} \\ U_5^{n+1} \\ \vdots \\ U_m^{n+1} \end{bmatrix} = \begin{bmatrix} U_1^n \\ U_2^n \\ U_3^n \\ U_4^n \\ U_5^n \\ \vdots \\ U_m^n \end{bmatrix} + b \begin{bmatrix} -2 & 1 & & & & & & & \\ 1 & -2 & 1 & & & & & & \\ & 1 & -2 & 1 & & & & & \\ & & 1 & -2 & 1 & & & & \\ & & & 1 & -2 & 1 & & & \\ & & & & 1 & -2 & 1 & & \\ & & & & & & & 1 & -2 \\ & & & & & & & & & 1 & -2 \end{bmatrix} \begin{bmatrix} U_1^n \\ U_2^n \\ U_3^n \\ U_4^n \\ U_5^n \\ \vdots \\ U_m^n \end{bmatrix}$$

En définissant adéquatement  $u_n$  et  $A$ ,

$$\mathbf{u}_{n+1} = \mathbf{u}_n + b\mathbf{A}\mathbf{u}_n$$



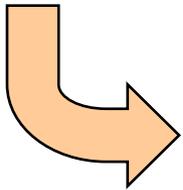
*On résout le système linéaire défini par :*

$$\mathbf{u}'(t) = \frac{\epsilon}{(\Delta x)^2} \mathbf{A}\mathbf{u}(t)$$

$$\Delta x = 0.1, \Delta t = 0.005$$

# Euler explicite

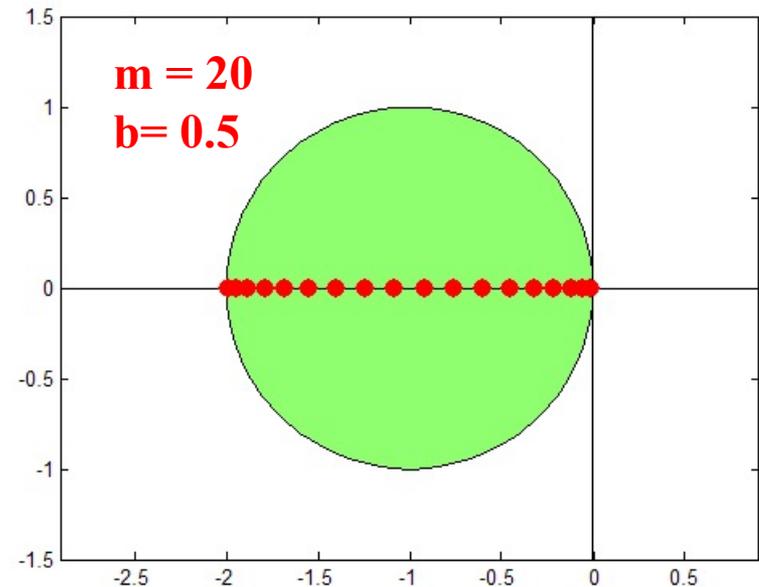
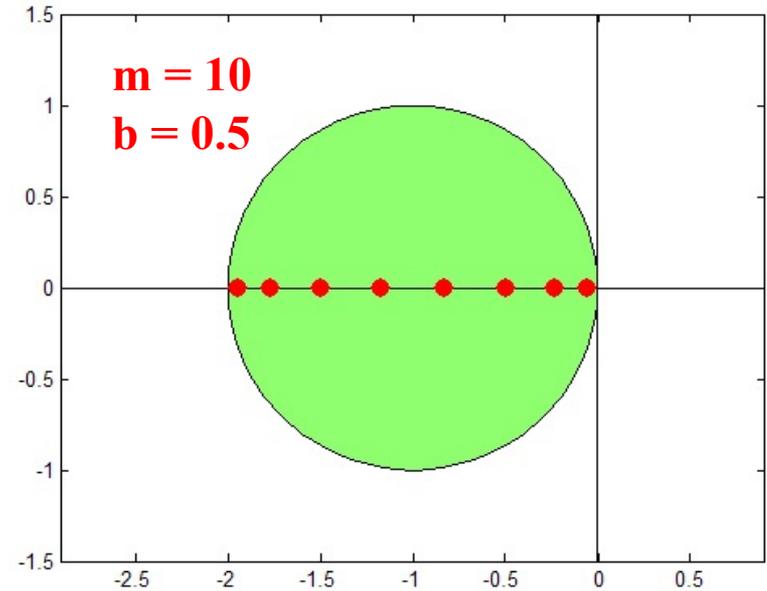
$$\mathbf{u}_{n+1} = \mathbf{u}_n + \underbrace{\frac{\epsilon \Delta t}{(\Delta x)^2}}_b \mathbf{A} \mathbf{u}_n$$



$$|1 + b\lambda_i| \leq 1$$

↑  
*Valeurs propres de*  
*A*

$$\Delta x = 0.05, \Delta t = 0.00125$$

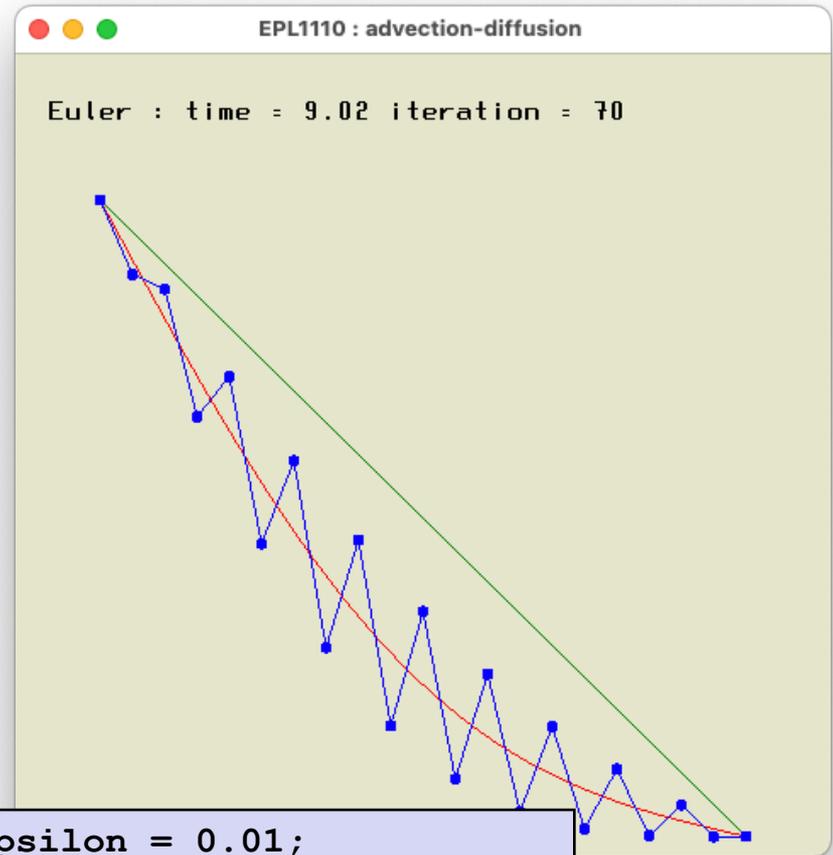


# Condition de stabilité pour la méthode d'Euler explicite....

$$\beta = \frac{\epsilon \Delta t}{(\Delta x)^2} \leq \frac{1}{2} \quad ( \sim )$$

$$\Delta t \leq \frac{(\Delta x)^2}{2\epsilon}$$

Courant, Friedrichs et Lewy (1928)



```
epsilon = 0.01;  
dt = h*h/(epsilon*1.94);
```

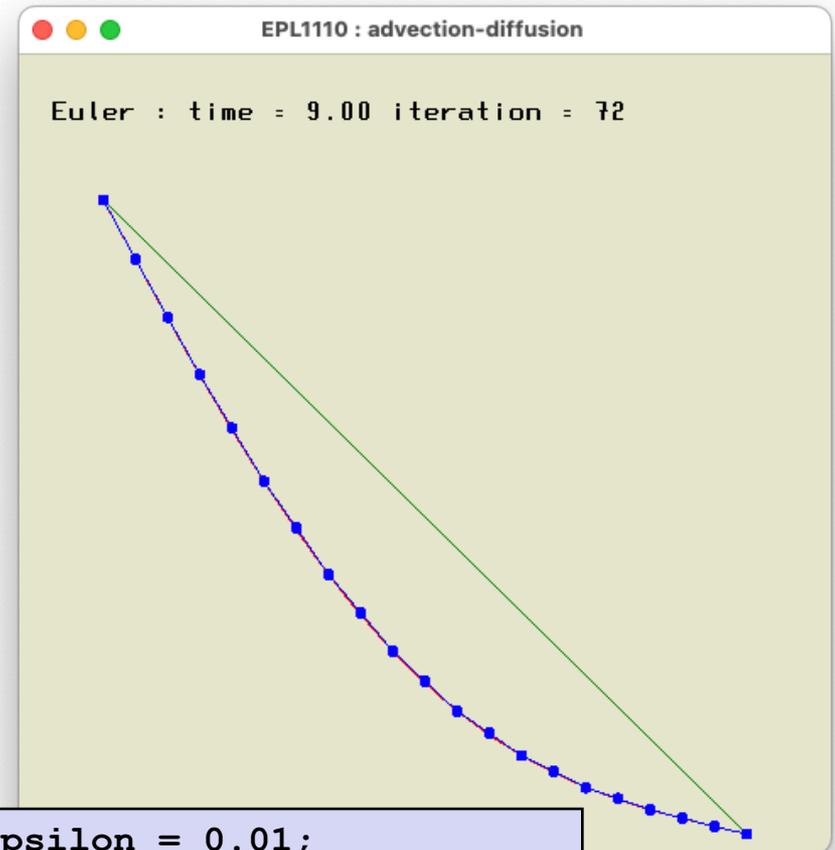
# Condition de stabilité pour la méthode d'Euler explicite....

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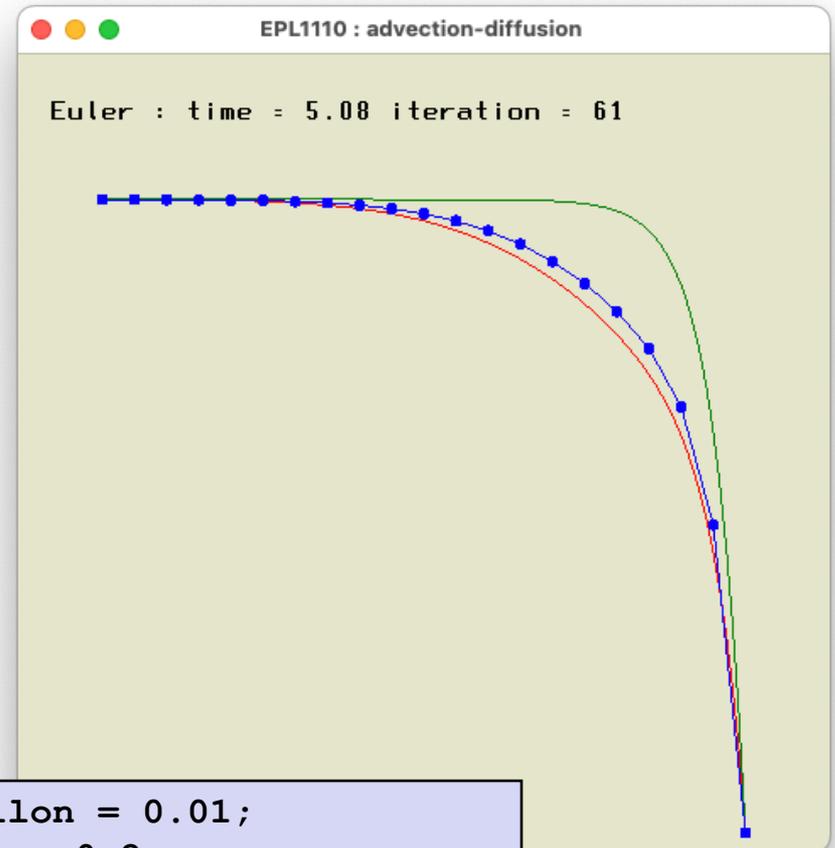
```
epsilon = 0.01;  
dt = h*h/(epsilon*2.0);
```

Et maintenant  
introduisons  
l'advection...

$$\frac{\partial u}{\partial t} + \beta \frac{\partial u}{\partial x} = \epsilon \frac{\partial^2 u}{\partial x^2}$$

$$u(0) = 1$$

$$u(1) = 0$$

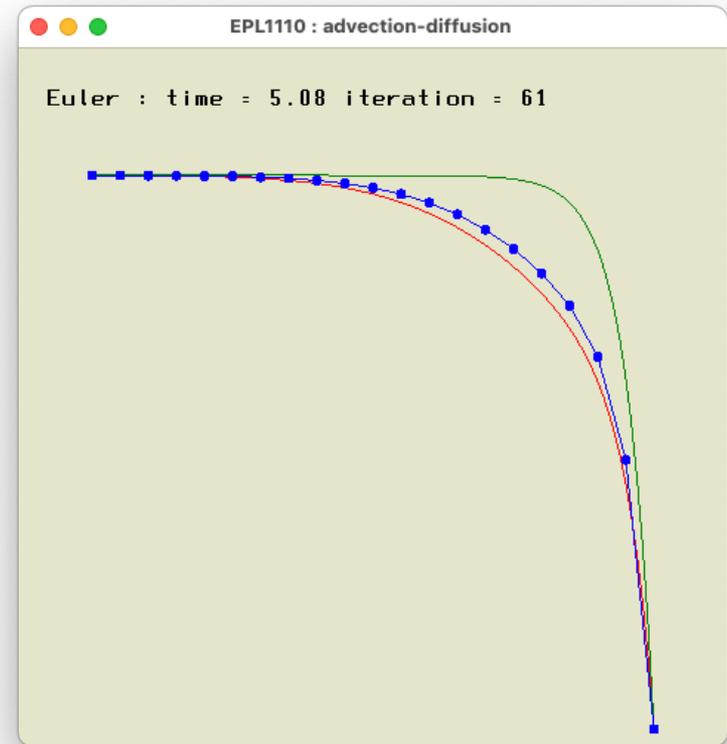


```
epsilon = 0.01;  
beta = 0.2;  
dt = h*h/(epsilon*3.0);
```

# Et comment déduire le pas de temps ?

$$U_j^n = U^n e^{ikX_j}$$

Considérons une perturbation quelconque...



$$\begin{aligned} U_j^{n+1} &= U_j^n + \Delta t \left( \overbrace{\left( (\zeta - 1) \frac{\beta}{2h} + \frac{\epsilon}{h^2} \right)}^a U_{j+1}^n + \overbrace{\left( -\zeta \frac{\beta}{h} - 2 \frac{\epsilon}{h^2} \right)}^b U_j^n + \overbrace{\left( (\zeta + 1) \frac{\beta}{2h} + \frac{\epsilon}{h^2} \right)}^c U_{j-1}^n \right) \\ &= U_j^n \left( 1 + \Delta t \left( a e^{ikh} + b + c e^{-ikh} \right) \right) \\ &= U_j^n \left( 1 + \Delta t \left( \underbrace{(a+c)}_{-b} \cos kh + b + i \underbrace{(a-c)}_{-\beta/h} \sin kh \right) \right) \end{aligned}$$

Il faut que le module  
du facteur  
d'amplification  
soit inférieur  
à l'unité :-)

$$U = \left( 1 + \Delta t \left( b - b \cos kh + b - i \frac{\beta}{h} \sin kh \right) \right)$$

$$\left| \left( 1 + \Delta t b - \Delta t b \cos(kh) \right) - i \Delta t \left( \frac{\beta}{h} \sin(kh) \right) \right| \leq 1$$



$$1 + \Delta t^2 b^2 (1 - \cos(kh))^2 + 2b\Delta t(1 - \cos(kh)) + \Delta t^2 \frac{\beta^2}{h^2} \sin^2(kh) \leq 1$$

$$\Delta t^2 b^2 (1 - \cos(kh))^2 + 2b\Delta t(1 - \cos(kh)) + \Delta t^2 \frac{\beta^2}{h^2} (1 - \cos(kh))^2 \leq 0$$

$$\Delta t b^2 (1 - \cos(kh)) + 2b + \Delta t \frac{\beta^2}{h^2} (1 + \cos(kh)) \leq 0$$

On déduit finalement :

$$\Delta t \leq \frac{-2b}{(1 - \cos(kh))b^2 + (1 + \cos(kh))\frac{\beta^2}{h^2}}$$

$$\Delta t \leq \frac{2(\zeta\beta h + 2\epsilon)h^2}{(\zeta h\beta + 2\epsilon)^2 + \beta^2 h^2 + \cos(kh)(\beta^2 h^2 - (\zeta h\beta + 2\epsilon)^2)}$$

On conclut donc :

$$\Delta t \leq \min\left(\frac{\zeta h\beta + 2\epsilon}{\beta^2}, \frac{h^2}{\zeta h\beta + 2\epsilon}\right)$$

Notons que l'on obtient les résultats habituels  $\Delta t \leq \frac{h}{\beta}$  pour  $\epsilon = 0, \zeta = 1$  et  $\Delta t \leq \frac{h^2}{2\epsilon}$  pour  $\beta = 0$ .

Pratiquement...