

$$r^h = \nabla \cdot (a \nabla u^h) + f.$$

La technique de Galerkin
consiste à annuler en moyenne
le produit du résidu
avec les fonctions de forme

Et cette manière de procéder minimise
l'erreur dans la norme L2 : c'est une
formulation optimale en ce sens !



Galerkin 1871-1945

Les éléments finis
sont une méthode
de résidus pondérés

$$r^h \approx 0$$

$$\langle \tau_i r^h \rangle = 0,$$



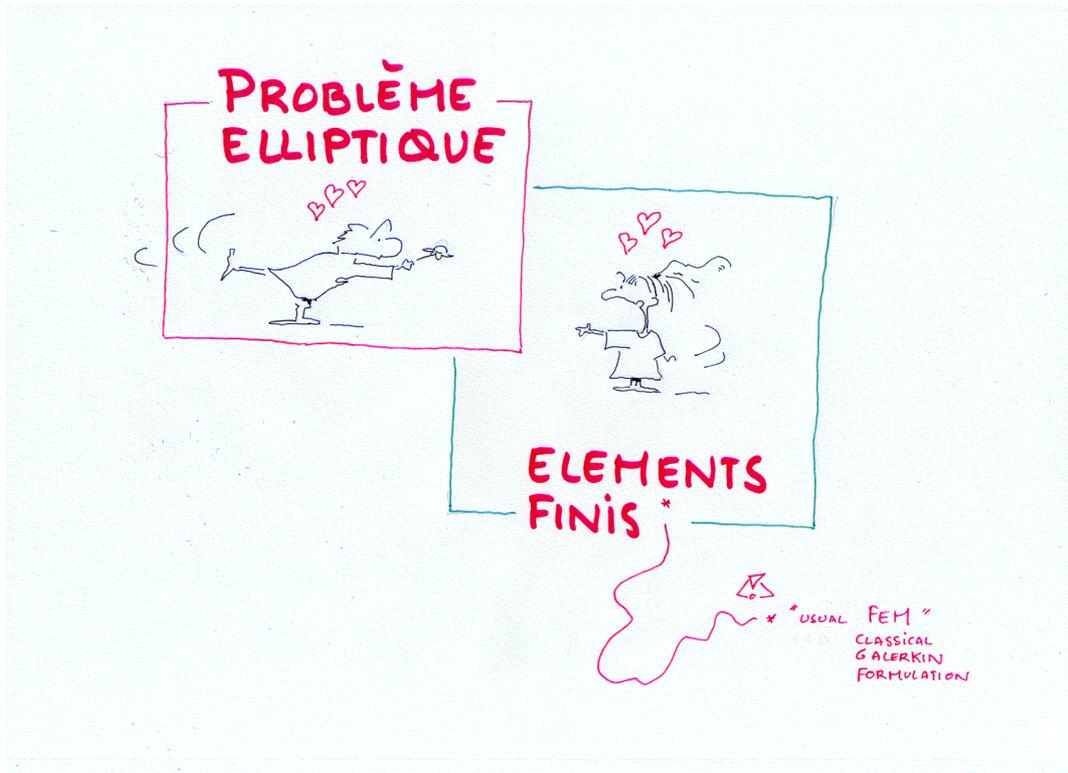
$$\langle \tau_i (\nabla \cdot (a \nabla u^h)) \rangle + \langle \tau_i f \rangle = 0,$$



$$\langle (\nabla \tau_i) \cdot (a \nabla u^h) \rangle = \langle \tau_i f \rangle,$$

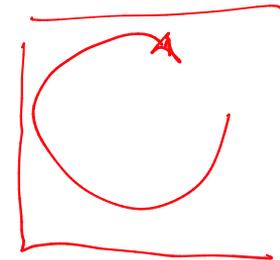
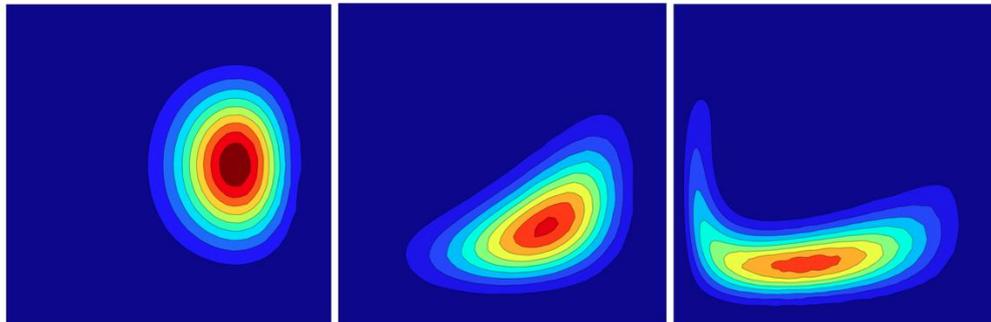
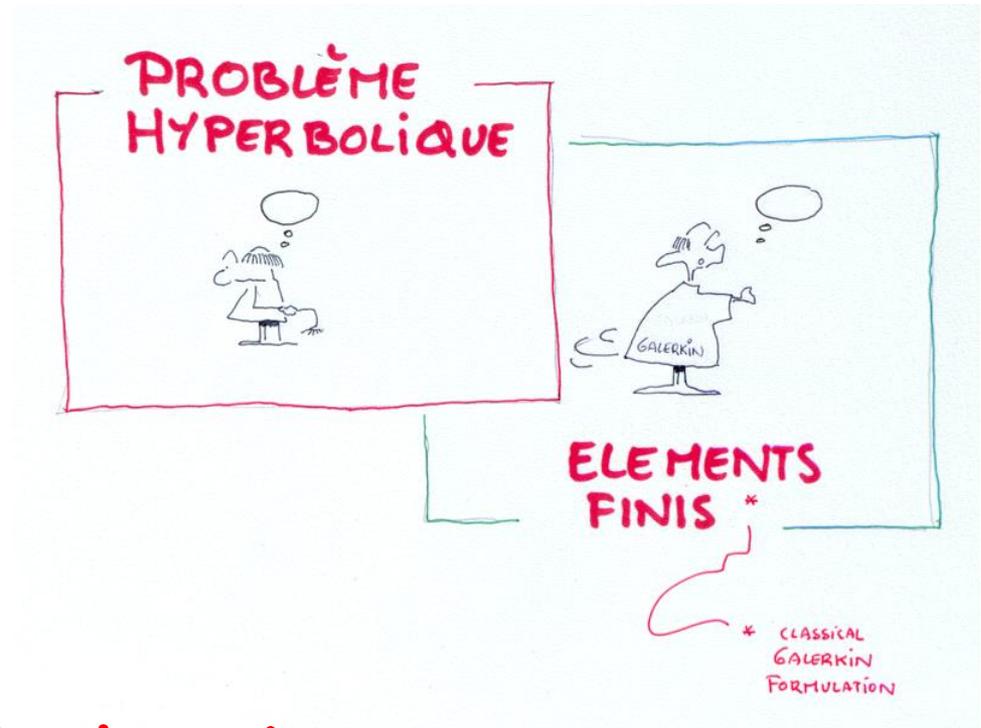


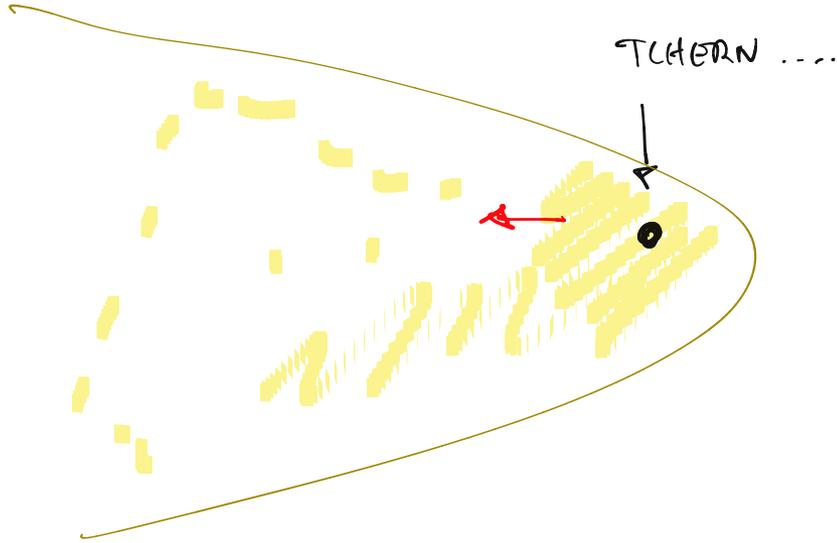
$$\sum_{j=1}^n \underbrace{\langle (\nabla \tau_i) \cdot (a \nabla \tau_j) \rangle}_{A_{ij}} U_j = \underbrace{\langle \tau_i f \rangle}_{B_i}$$



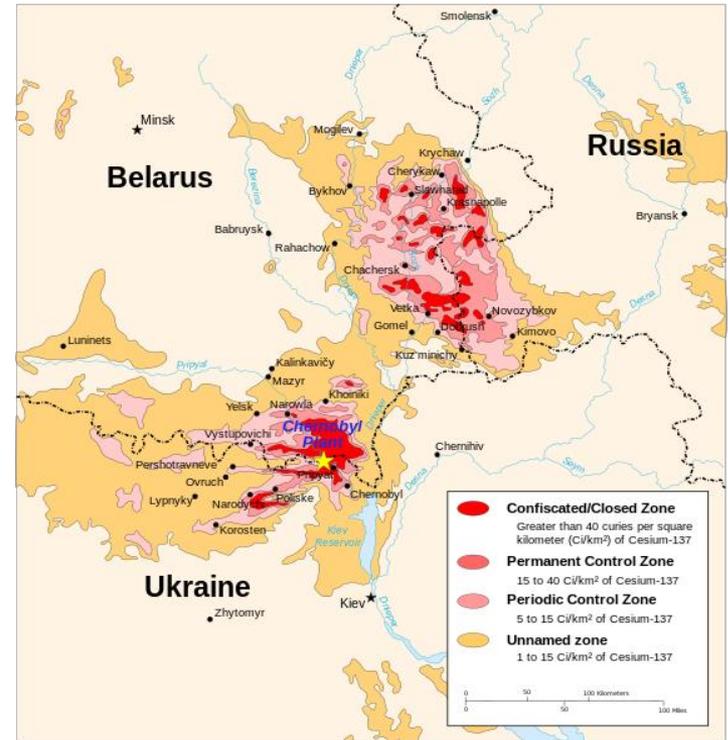
Galerkin, c'est donc optimal
pour des équations elliptiques

Mais,
plus pour des
équations
d'advection diffusion !

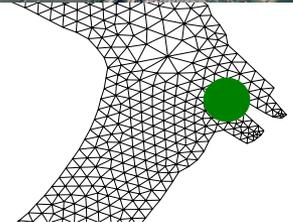
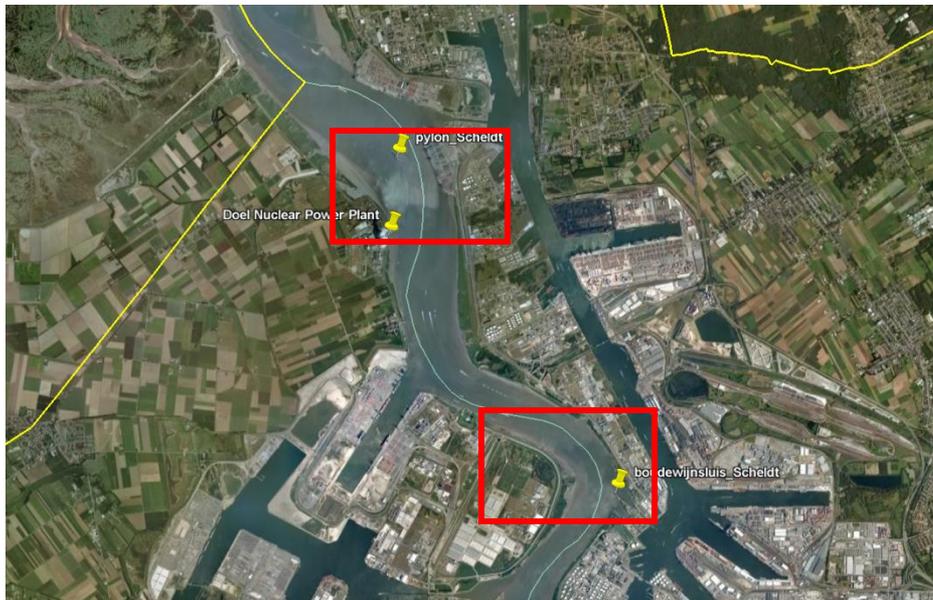
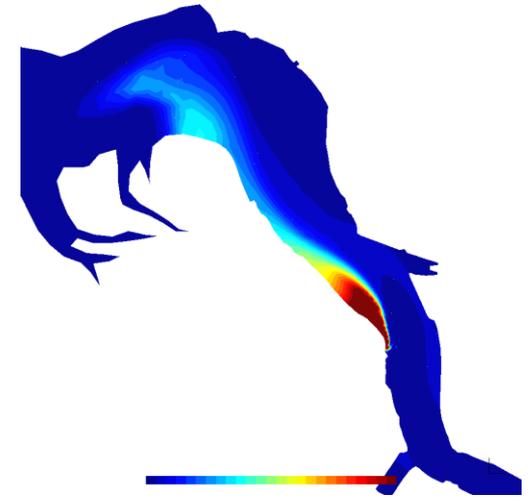
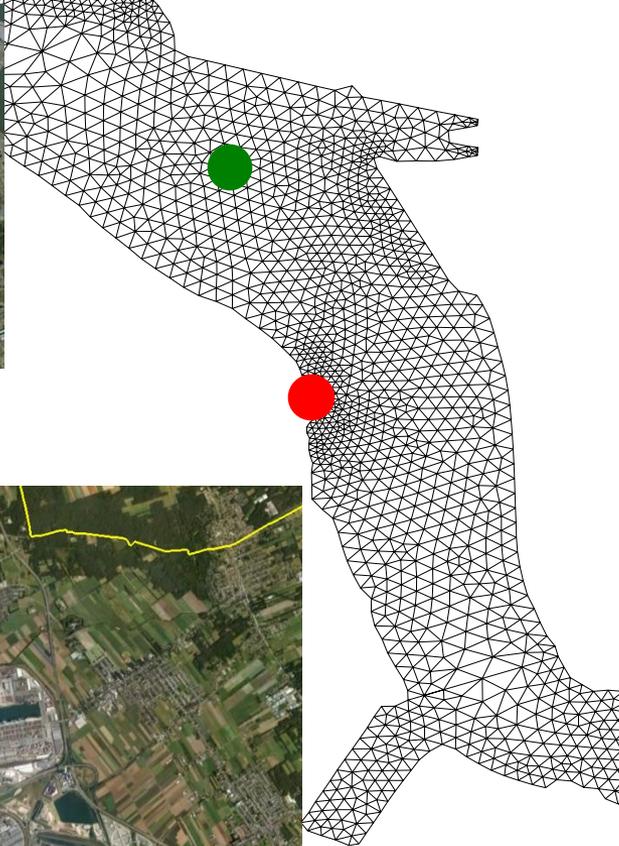




Tchernobyl...



Un petit exemple concret



Diffusion et transport d'un traceur passif

MOYENNE DE LA CONCENTRATION SUR LA PROFONDEUR

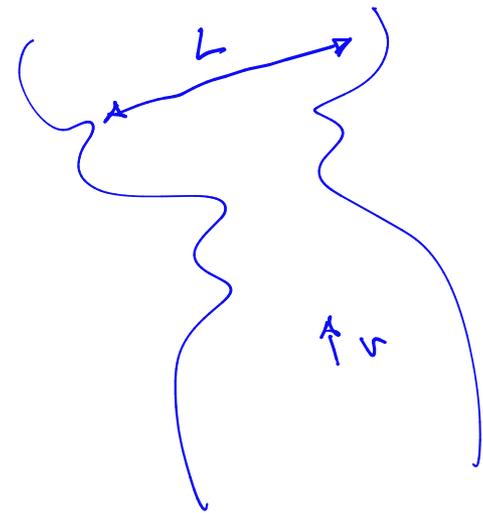
$$\frac{\partial c}{\partial t} + \underbrace{\vec{v} \cdot \nabla c}_{\text{TERME DE TRANSPORT}} + \underbrace{\nabla \cdot (D \nabla c)}_{\text{TERME DE DIFFUSION}} + S$$

\vec{v} VITESSE HORIZONTALE
 COEFFICIENT DE DIFFUSION

$$\frac{\partial c}{\partial t} + \boxed{u \frac{\partial c}{\partial x} + v \frac{\partial c}{\partial y}} = \boxed{k \left[\frac{\partial^2 c}{\partial x^2} + \frac{\partial^2 c}{\partial y^2} \right]}$$

$\frac{\partial(\frac{V \Delta c}{L})}{\partial t} = \frac{\partial(k \frac{\Delta c}{L^2})}{\partial t}$

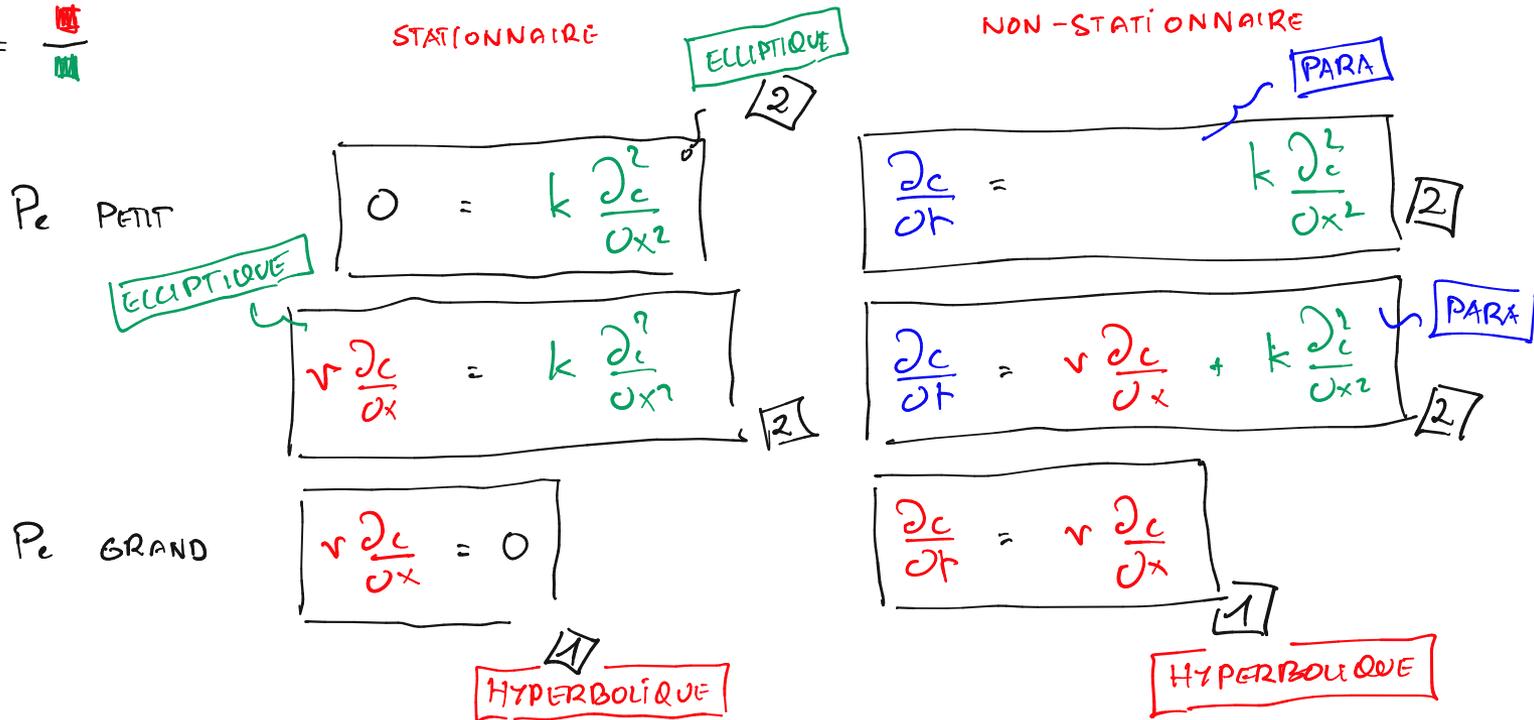
$$P_e = \frac{\cancel{V} \cancel{\Delta c}}{\cancel{L}} = \frac{V \cancel{\Delta c}}{L} \frac{L^2}{\cancel{k} \cancel{\Delta c}} = \frac{VL}{k}$$



Analysons les cas particuliers !

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2}$$

$$Pe = \frac{VL}{\kappa} = \frac{\text{ad}}{\text{diff}}$$



Le nombre de Péclet permet d'estimer l'importance du terme de transport par rapport à celui de la diffusion !

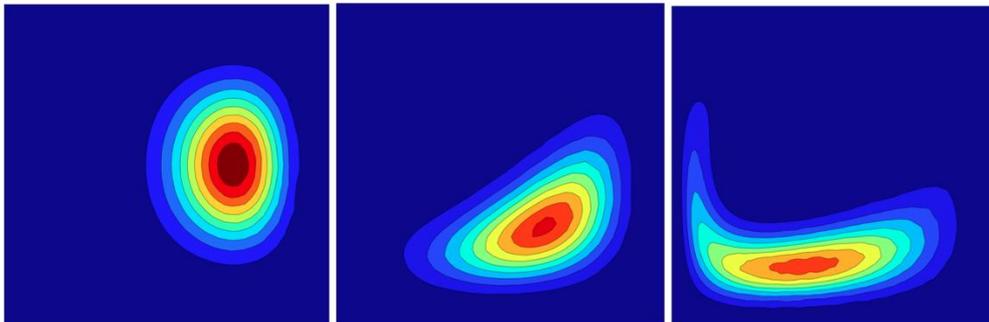
Diffusion et transport d'un traceur passif

MOYENNE DE LA CONCENTRATION SUR LA PROFONDEUR

COEFFICIENT DE DIFFUSION

$$\frac{\partial c}{\partial t} + \underbrace{\vec{u} \cdot \nabla c}_{\text{TERME DE TRANSPORT}} = \underbrace{\nabla \cdot (D \nabla c)}_{\text{TERME DE DIFFUSION}} + S$$

\vec{u} = VITESSE HORIZONTALE



C'est une équation parabolique du second ordre !

Ce n'est pas elliptique !

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2}$$

P_e PETIT

STATIONNAIRE

$$0 = k \frac{\partial^2 c}{\partial x^2}$$

ELL
2

$$v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2}$$

ELL
2

P_e GRAND

$$v \frac{\partial c}{\partial x} = 0$$

HYP
1

INSTATIONNAIRE

$$\frac{\partial c}{\partial t} = k \frac{\partial^2 c}{\partial x^2}$$

PARA
2

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2}$$

PARA
2

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = 0$$

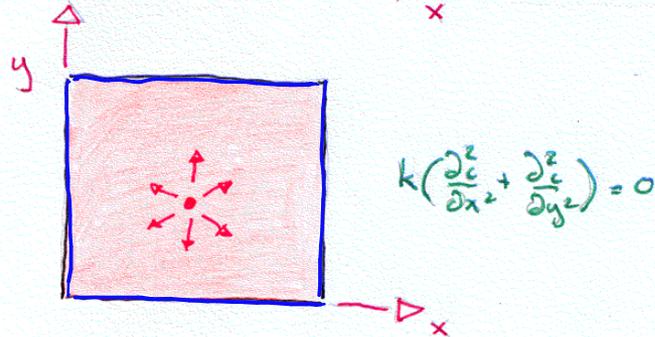
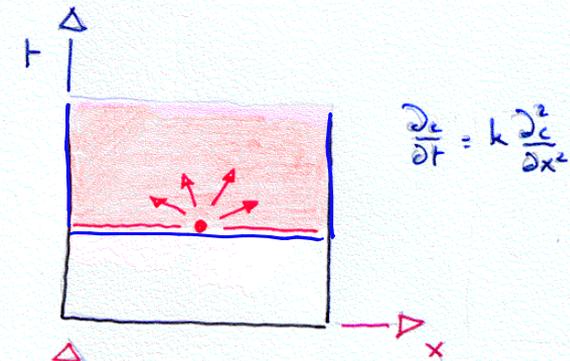
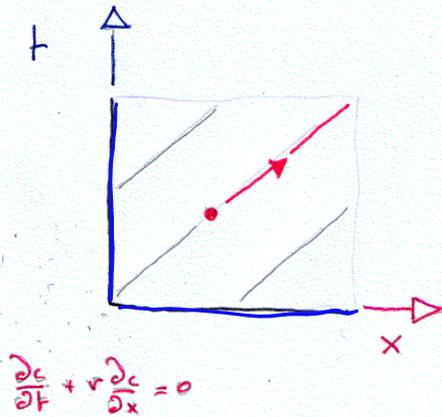
HYP
1

Le nombre de Péclet permet d'estimer l'importance du terme de transport par rapport à celui de la diffusion !

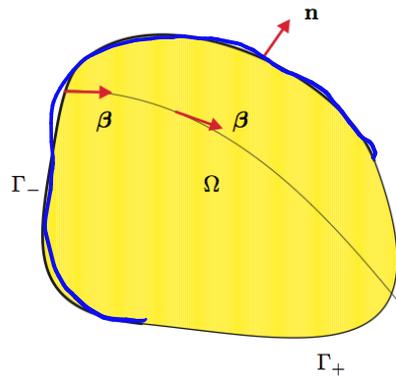
$$P_e = \frac{vL}{k}$$

PROBLEME BIEN POSE

→ CONDITIONS
AUX LIMITES



Advection pure



Trouver $u(\mathbf{x})$ tel que

$$\boldsymbol{\beta} \cdot \nabla u = f, \quad \forall \mathbf{x} \in \Omega,$$

$$u = 0, \quad \forall \mathbf{x} \in \Gamma_-$$

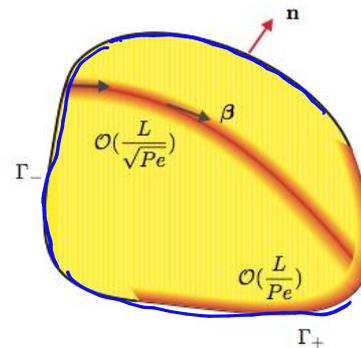
$$\frac{d\mathbf{x}}{ds}(s) = \boldsymbol{\beta}(\mathbf{x}, s)$$

Trouver $u(\mathbf{x}) \in \mathcal{U}_s$ tel que

$$\boldsymbol{\beta} \cdot \nabla u - \nabla \cdot (\epsilon \nabla u) = f, \quad \forall \mathbf{x} \in \Omega,$$

$$\mathbf{n} \cdot (\epsilon \nabla u) = g, \quad \forall \mathbf{x} \in \Gamma_N,$$

$$u = t, \quad \forall \mathbf{x} \in \Gamma_D,$$



$$\frac{d\mathbf{x}}{ds}(s) = \boldsymbol{\beta}(\mathbf{x}, s)$$

Advection-diffusion

Equation d'advection-diffusion

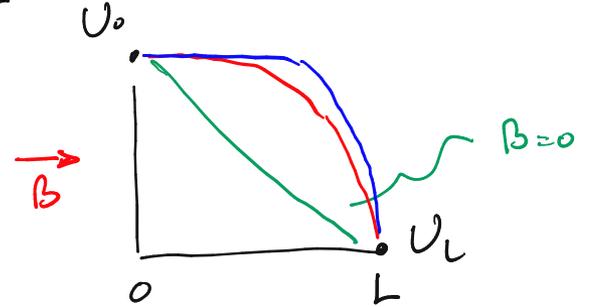
$$Pe = \frac{\beta L}{\epsilon}$$

$$\beta \frac{dv}{dx} - \epsilon \frac{d^2v}{dx^2} = 0$$

$$v(x) = C \exp \left[\frac{\beta x}{\epsilon} \right]$$

$$\epsilon v'' = \frac{\beta^2}{\epsilon^2} \epsilon \exp[\dots] C$$

$$\beta v' = \frac{\beta}{\epsilon} \beta \exp[\dots] C$$

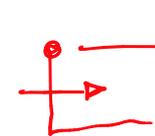


$$\epsilon \frac{d^2v}{dx^2} = 0$$



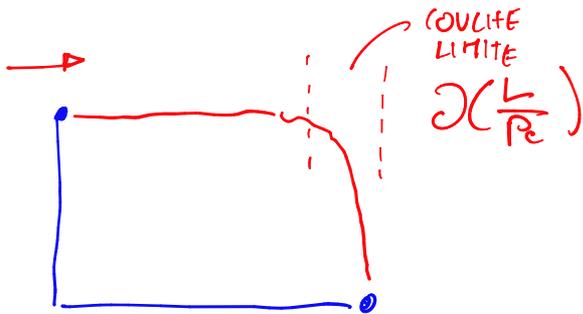
$$v(0) = U_0$$

$$v(L) = 0$$



$$\beta \frac{dv}{dx} = 0$$

$$v(0) = U_0$$



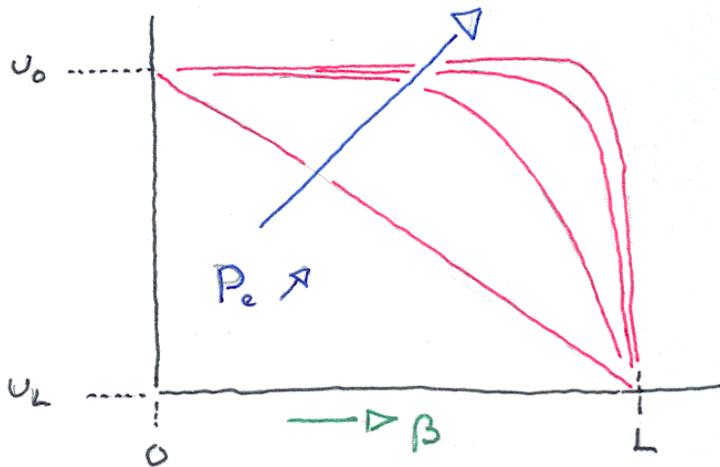
$$\frac{v(x) - U_0}{U_L - U_0} = \frac{\exp \left[\frac{\beta x}{\epsilon} \right] - 1}{\exp \left[\frac{\beta L}{\epsilon} \right] - 1}$$

EQUATION OF ADVECTION - DIFFUSION

$$\beta \frac{dv}{dx} - \epsilon \frac{d^2v}{dx^2} = 0$$

$$v(0) = v_0$$

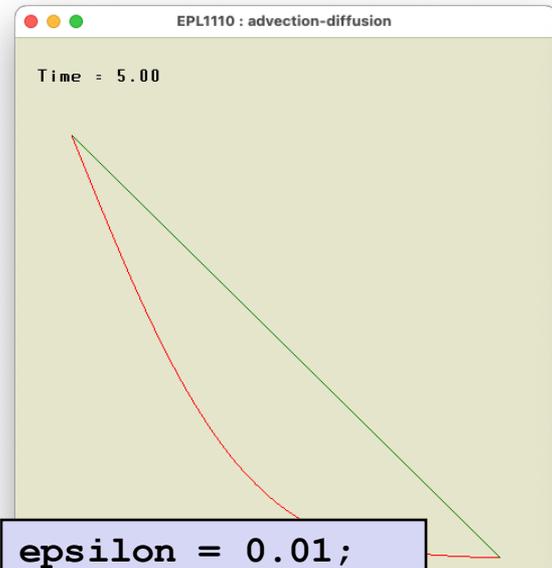
$$v(L) = v_L$$



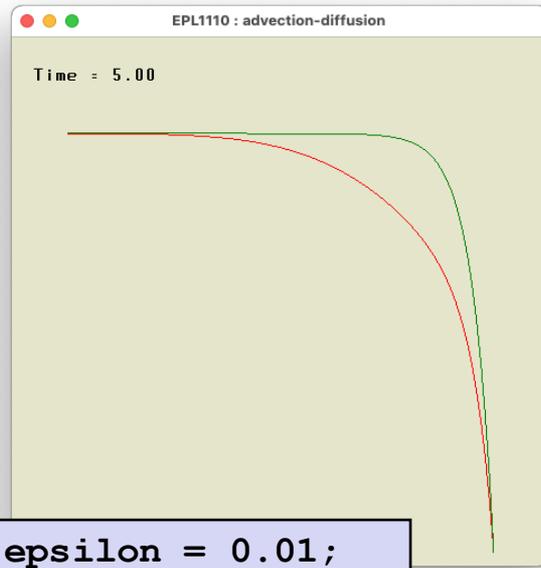
$$Pe = \frac{\beta L}{\epsilon}$$

$$\frac{v - v_0}{v_L - v_0} = \frac{\exp\left(\frac{\beta x}{\epsilon}\right) - 1}{\exp\left(\frac{\beta L}{\epsilon}\right) - 1}$$

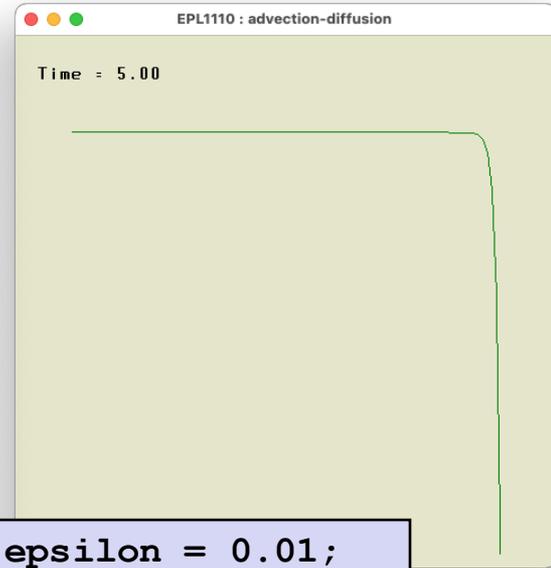
$Pe \times /L$
 Pe



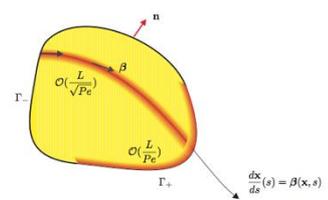
epsilon = 0.01;
beta = 0.0;



epsilon = 0.01;
beta = 0.2;



epsilon = 0.01;
beta = 1.0;



Trouver $u(\mathbf{x}) \in \mathcal{U}_s$ tel que

$$\beta \cdot \nabla u - \nabla \cdot (\epsilon \nabla u) = f, \quad \forall \mathbf{x} \in \Omega,$$

$$\mathbf{n} \cdot (\epsilon \nabla u) = g, \quad \forall \mathbf{x} \in \Gamma_N,$$

$$u = t, \quad \forall \mathbf{x} \in \Gamma_D,$$

Advection-diffusion

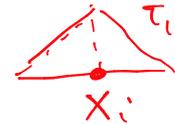
Equation de transport !

Advection pure !

$$\frac{du}{dx} = f$$

$$u(0) = U_0$$

$$v(x) \approx u^h(x) = \sum U_i \tau_i(x)$$



GALERKIN

$$\langle r^h, \tau_i \rangle = 0$$

$$\sum_j \underbrace{\langle \tau_i, \tau_j' \rangle}_{A_{ij}} U_j = \underbrace{\langle f, \tau_i \rangle}_{B_i}$$

$$\underbrace{\frac{du^h}{dx}}_{r^h} - f \approx 0$$

Appliquons la méthode de Galerkin à notre problème de transport

$$u' = f$$

$$\frac{du}{dx} = \kappa(x)$$

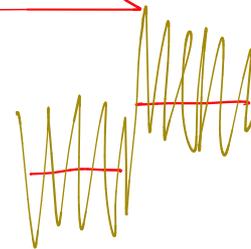


OK :-)

$$\frac{du}{dx} = \uparrow$$
$$u = \text{step}$$



KO



Bubnov-Galerkin !

Ce n'est plus un problème de minimisation

$$u \approx u_h = \sum U_i \tau_i$$

$$\langle r^h, \hat{\tau}_i \rangle = 0 \quad \forall i$$

$$\hat{\tau}_i = \tau_i$$

Petrov-Galerkin !

C'est plus le même problème !

$$\frac{dv}{dx} = f$$

$$v(0) = U_0$$

$$\sum_{U_j} \left\langle \left(\frac{dv^h}{dx} - f \right) \tau_i' \right\rangle = 0$$

r^h

$\sum U_j \tau_j'$

$$\hat{\tau}_i = \tau_i'$$

$$v' \geq 0$$

$$\sum U_j \underbrace{\langle \tau_i' \tau_j' \rangle}_{A_{ij}} = \underbrace{\langle f \tau_i' \rangle}_{- \langle f \tau_i \rangle + \ll \gg}$$

SYM
DEFINIE POSITIVE

$$\frac{d^2 v}{dx^2} = \frac{df}{dx} \quad v(0) = \dots$$

EQUATION DE TRANSPORT

$$\frac{du}{dx} = f$$

$$u(0) = u_0$$

$$u \approx u_h = \sum_i U_i \tau_i(x)$$


GALERKIN

? U_i TELS QUE

$$\langle \tau_i, \Gamma_h \rangle = 0$$

$$\sum_j \underbrace{\langle \tau_i, \tau_j, x \rangle}_{A_{ij}} U_j = \underbrace{\langle \tau_i, f \rangle}_{B_i}$$

≠ MATRICE DEFINIE POSITIVE !

$$\frac{du}{dx} = f$$

GALERKIN

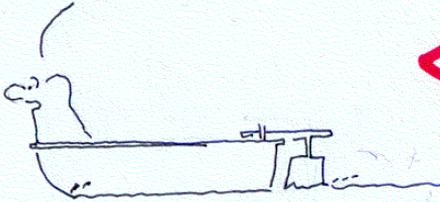
$$\sum_j A_{ij} U_j = B_i$$

BUBNOV - GALERKIN

DIFFERENCES FINIES CENTREES

$$U_{j+1} - U_{j-1} = B_j \cdot 2\Delta x$$

TERRA INCOGNITA ?



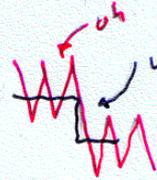
PROBLEME DE MINIMISATION

$$f(x) = \sin(x)$$

$$f(x) = \uparrow$$

OK

Bout



PETROV-GALERKIN

? U_j TELS QUE

$$\langle \tau_{j,x} | r^h \rangle = 0$$

0 → Δ
 INTEGRATION
 LE LONG DES
 CARACTERISTIQUES

Δ

DIFFERENCES
 FINIES
 AMONT

$$U_{j+1} - U_j = B_j \Delta x$$

$$\sum_j \underbrace{\langle \tau_{i,x} | \tau_{j,x} \rangle}_{A_{ij}} U_j = \underbrace{\langle \tau_{i,x} | f \rangle}_{B_i}$$

MATRICE
 DEFINIE
 POSITIVE

1 CONDITION
 AUX LIMTES !

$\frac{du}{dx} = f$

A ÉTÉ
 REMPLACÉ PAR

$\frac{d^2 u}{dx^2} = \frac{df}{dx}$

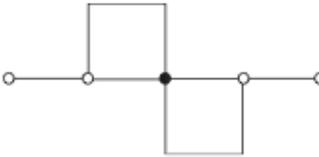
2 CONDITIONS
 AUX LIMTES !

HIC

En bref :-)

$$\frac{du}{dx} = f,$$

$$u(0) = 0,$$

<p>Galerkin $w_i = \tau_i$</p> 	<p><i>Différences finies centrées</i></p> <p>Simple et donc tentant... Oscillations numériques si f n'est pas lisse !</p> $\frac{U_{i+1} - U_{i-1}}{2h} = \frac{F_{i+1} + 4F_i + F_{i-1}}{6},$
<p>Petrov-Galerkin $w_i = \tau_{i,x}$</p> 	<p><i>Différences finies centrées d'ordre deux</i></p> <p>Mathématiquement, tentant Condition frontière parasite !</p> $\frac{U_{i+1} - 2U_i + U_{i-1}}{h^2} = \frac{F_{i+1} - F_{i-1}}{2h},$
<p>Petrov-Galerkin $w_i = \tau_{i-1}^{cst}$</p> 	<p><i>Différences finies amont</i></p> <p>Quasiment optimal... Correspond à une intégration le long de la caractéristique, Pas d'oscillation numérique</p> $\frac{U_i - U_{i-1}}{h} = \frac{F_{i+1} + F_{i-1}}{2},$

Petrov-Galerkin !

Comment sélectionner
le paramètre magique ?

$$u' - \epsilon u'' - f = 0$$

↙ τ' ↘ τ

$$\langle (\tau_i + \zeta \tau'_i) (u^h)' - \epsilon (u^h)'' - f \rangle = 0 \quad \forall i$$

$$\sum U_j \left[\begin{array}{cc} \zeta \langle \tau'_i \tau'_j \rangle & - \epsilon \zeta \langle \tau'_i \tau''_j \rangle \\ + \epsilon \langle \tau'_i \tau'_j \rangle & + \langle \tau_i \tau'_j \rangle \end{array} \right] = \dots$$

$$- \epsilon \langle \tau_i \tau''_j \rangle + \langle \dots \rangle$$



$\zeta \nearrow$

AUGMENTE
 MAIS
 AUGMENTE AUSSI
 SAUF SI $\tau''_j = 0$

PETROV-GALERKIN

$$\langle (\tau_c + \zeta \tau_{i,x}) (\underbrace{u_x^h - \epsilon u_{xx}^h - f}_{\Gamma^h}) \rangle = 0$$

↗ $\hat{\tau}_c$

How TO SELECT ζ ?

2D

$$\hat{\tau}_c = \tau_c + \zeta \beta \cdot \nabla \tau_c$$

STREAMLINE UPWINDING

$$\sum_j \left(\begin{array}{l} \zeta \langle \tau_{i,x} \tau_{j,x} \rangle \\ \epsilon \langle \tau_{i,x} \tau_{j,xx} \rangle \end{array} - \begin{array}{l} \epsilon \zeta \langle \tau_{i,x} \tau_{j,xx} \rangle \\ \langle \tau_c \tau_{j,x} \rangle \end{array} \right) U_j = \dots$$

☺

Différences finies centrées

On résout analytiquement

le problème discret...

$$\beta u' = \varepsilon u''$$

$$\beta \frac{U_{i+1} - U_{i-1}}{2h} = \varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$$U_i = A r^i + B$$

$$\cancel{A} r^{i-1} \left[\frac{\beta h}{2\varepsilon} \right] (r^2 - 1) = \cancel{A} r^{i-1} (r^2 - 2r + 1)$$

$\frac{\beta h}{2\varepsilon}$ PELLET DE MAILLE

$\frac{p_c h}{2}$

$\frac{p_c h}{2}$

$$0 = \underbrace{(1 - \zeta^2)}_{\alpha} r^2 - 2r + \underbrace{(1 + \zeta^2)}_c$$

$$\begin{aligned} r &= \frac{1 \pm \sqrt{1 - \alpha c}}{\alpha} \\ &= \frac{1 \pm \sqrt{\cancel{1} - \cancel{1} + (\zeta^2)^2}}{(1 - \zeta^2)} \\ &= \frac{1 + \zeta^2}{1 - \zeta^2} \end{aligned}$$

$$\frac{\beta h}{2\varepsilon} = \frac{p_c h}{2} < 1$$

DIFF. CENTRÉES

$$\beta \frac{U_{i+1} - U_{i-1}}{2h} = \varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$U_0 = u_0$
 $U_N = u_L$

EQUATION AUX RECURRENCES !

↙ ↘

$$U_i = A r^i + B$$

$$\cancel{A} r^{i-1} \frac{\beta h}{2\varepsilon} (r^2 - 1) = \cancel{A} r^{i-1} (r^2 - 2r + 1)$$

$$0 = \left(\frac{1 - Pe^h/2}{2} \right) r^2 - r + \left(\frac{1 + Pe^h/2}{2} \right)$$

$$\Delta = \frac{Pe^h}{2}$$

PECLET DE MAILLE

$$r = \frac{1 \pm \sqrt{1 - (1 + Pe^h/2)(1 - Pe^h/2)}}{(1 - Pe^h/2)}$$

$$r = \frac{1 + Pe^h/2}{1 - Pe^h/2}$$

REJECT $r=1$ OF COURSE !

$$\frac{U_i - v_0}{v_L - v_0} = \frac{\left(\frac{1 + P_e h/2}{1 - P_e h/2} \right)^i - 1}{\left(\frac{1 + P_e h/2}{1 - P_e h/2} \right)^N - 1}$$

$$\approx \exp. (P_e h)^N$$

$$\approx \exp. \left(\frac{\beta h N}{\epsilon} \right)$$

P_e

[SCHAUM p 551]

$$\frac{x}{e^x - 1} \approx 1 - \frac{x}{2}$$

$$\left(1 + \frac{x}{2} \right) = e^x \left(1 - \frac{x}{2} \right)$$

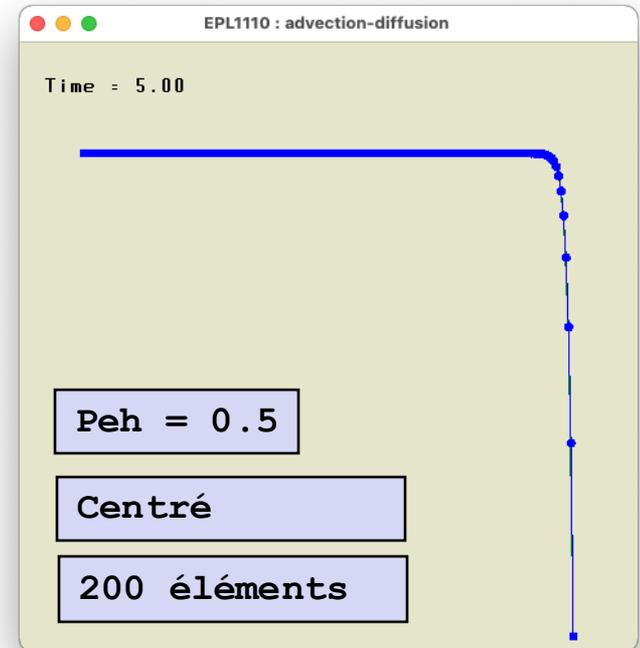
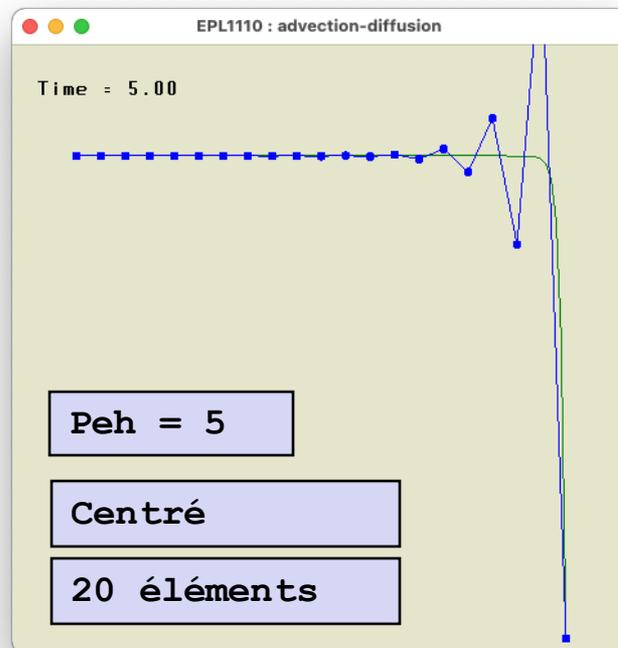
$$\frac{P_e h}{2} < 1$$

TO AVOID
OSCILLATORY
BEHAVIOUR

Galerkin converge si on raffine le maillage suffisamment !

epsilon = 0.01;
beta = 1.0;

L'équation d'advection-diffusion est formellement une équation elliptique et donc c'était prévisible par la théorie !



Différences finies décentrées.

On résout analytiquement

le problème discret...

$$\beta \frac{U_i - U_{i-1}}{h} = \varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$$\cancel{A} \cancel{\lambda}^{i-1} \left[\frac{\beta h}{2\varepsilon} (\lambda^2 - 1) \right] = \cancel{A} \cancel{\lambda}^{i-1} (\lambda^2 - 2\lambda + 1)$$

$$\underbrace{\frac{\beta h}{2}}_{\hat{\alpha}}$$

PELLET
DE MAILLE

$\hat{\alpha}$

$$\frac{\beta h}{\varepsilon} (\lambda - 1)$$

$$0 = \lambda^2 - 2\lambda(1 + \hat{\alpha}) - (1 - 2\hat{\alpha})$$

$$\lambda = (1 + \hat{\alpha}) \pm \sqrt{(1 + \hat{\alpha})^2 - (1 - 2\hat{\alpha})}$$

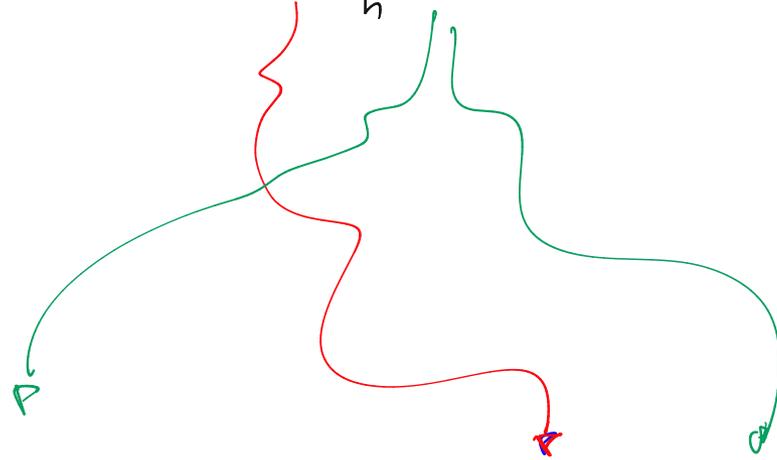
↓

$$= 1 + 2\hat{\alpha}$$

TOUJOURS > 0 !

$$\beta u' = \left(\varepsilon + \frac{\beta h}{2} \right) u''$$

$$\beta \frac{U_i - U_{i-1}}{h} = \varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$



$$\beta \left[\frac{U_{i+1}}{2h} - \frac{U_{i-1}}{2h} \right] = \left[\frac{U_{i+1}}{h^2} - \frac{2U_i}{h} + \frac{U_{i-1}}{h^2} \right] \left[\frac{\beta h}{2} \right]$$

... et on obtient la diffusion numérique !

UPWIND DIFF.

$$\beta \frac{U_i - U_{i-1}}{h} = \varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$$U_0 = u_0$$

$$U_N = u_L$$

$$\cancel{A} r^{i-1} \underbrace{\frac{\beta h}{\varepsilon}}_{\triangleq Pe^h} (\pi - 1) = \cancel{A} r^{i-1} (\pi^2 - 2\pi + 1)$$

$$0 = \frac{\pi^2}{2} - (1 + Pe^h/2)\pi + \frac{(1 + Pe^h)}{2}$$

$$\pi = \frac{(1 + Pe^h/2) \pm \sqrt{(1 + Pe^h/2)^2 - (1 + Pe^h)}}{1}$$

$$= 1 + Pe^h$$

$$\frac{U_i - u_0}{u_L - u_0} = \frac{(1 + Pe^h)^i - 1}{(1 + Pe^h)^N - 1}$$

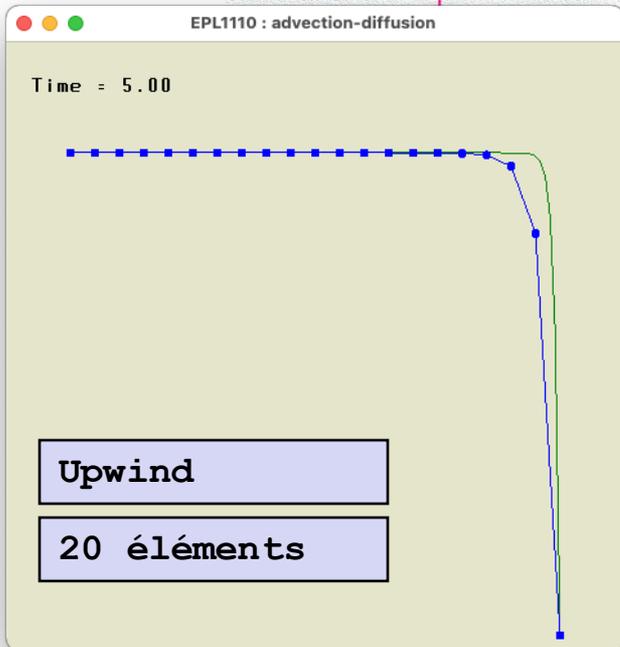
$(1 + Pe^h) > 0$
 \sqrt{h}
 NO
 OSCILLATIONS

BUT...

NUMERICAL
DIFFUSION

$$\beta \frac{U_i - U_{i-1}}{h} = \epsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$$\beta \frac{U_{i+1} - U_{i-1}}{2h} - \underbrace{\frac{\beta h}{2}}_{\text{NUMERICAL DIFFUSIVITY}} \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$



On fait le meilleur compromis !
On résout analytiquement
le problème discret...

$$\beta(1-\zeta) \frac{U_{i+1} - U_{i-1}}{2h} + \zeta\beta \frac{U_i - U_{i-1}}{h} = \varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

HYBRID SCHEME

$$(1-\zeta)\beta \frac{U_{i+1}-U_{i-1}}{2h} + \zeta\beta \frac{U_i-U_{i-1}}{2h} = \varepsilon \frac{U_{i+1}-2U_i+U_{i-1}}{h^2}$$

$$0 = \left(1 - \frac{(1-\zeta)P_e h/2}{2}\right) \pi^2 - \left(1 + \zeta P_e h/2\right) \pi + \left(1 + \frac{(1-\zeta)P_e h/2}{2} + \zeta P_e h/2\right)$$

$$\pi = \frac{(1 + \zeta P_e h/2) \pm \sqrt{\begin{matrix} (1 + \zeta P_e h/2)^2 \\ - (1 - (1-\zeta)P_e h/2) \\ (1 + (1-\zeta)P_e h/2) \end{matrix}}}{(1 - (1-\zeta)P_e h/2)}$$

} = $P_e h/2$

$$\pi = \frac{1 + (1 + \zeta) P_e h/2}{1 - (1 - \zeta) P_e h/2}$$

HOW TO
SELECT ζ ?

$$U_i = u(ih)$$

$$\left(\frac{1 + (1 + \zeta) P_e h/2}{1 - (1 - \zeta) P_e h/2} \right)^i = \exp\left(\frac{\beta h}{\varepsilon} i\right)$$

$$\left(\exp(P_e h) \right)^i$$

$$(1 + P_e h/2) - \zeta P_e h/2 = \exp(P_e) \left((1 - P_e h/2) + \zeta P_e h/2 \right)$$

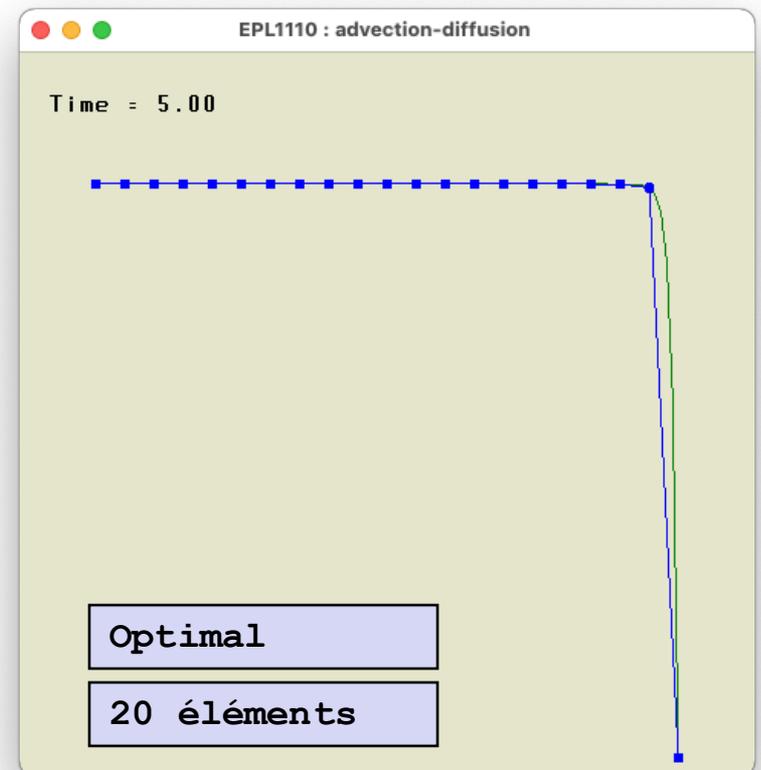
$$\begin{aligned}
 \zeta \frac{P_e h}{2} (1 - \exp(-P_e h)) &= \exp(P_e h) \left(1 - \frac{P_e h}{2}\right) - \left(1 + \frac{P_e h}{2}\right) \\
 &\downarrow \\
 \zeta &= \frac{\exp(P_e h) \left(\frac{2}{P_e h} - 1\right) - \left(\frac{2}{P_e h} + 1\right)}{(1 - \exp(-P_e h))} \\
 &\downarrow \\
 &= \underbrace{-\frac{(1 + \exp(P_e h))}{(1 - \exp(P_e h))}}_{\coth(P_e h/2)} - \frac{2}{P_e h}
 \end{aligned}$$

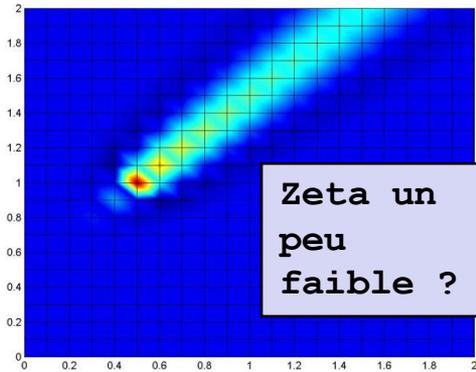
$$\boxed{\zeta = \coth\left(\frac{P_e h}{2}\right) - \frac{2}{P_e h}} \quad \square$$

On a trouvé
la méthode parfaite
pour des équations
unidimensionnelles !

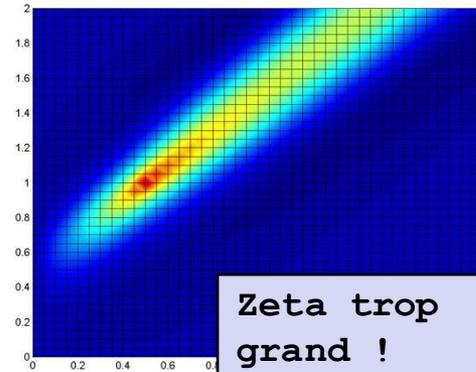
$$\zeta = \coth\left(\frac{Pe^h}{2}\right) - \frac{2}{Pe^h}$$

$$\begin{aligned}\beta \frac{du}{dx} - \epsilon \frac{d^2u}{dx^2} &= 0, \\ u(0) &= u_0, \\ u(L) &= u_L,\end{aligned}$$

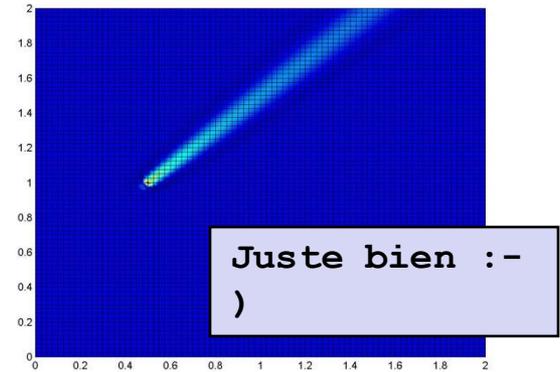




Zeta un peu faible ?



Zeta trop grand !



Juste bien :-)
)

En extrapolant
aux dimensions
supérieures...

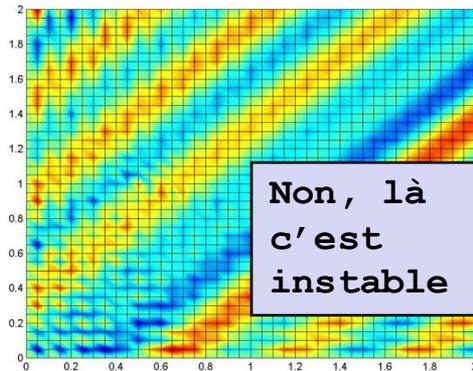
$$w_i = \tau_i + \zeta \beta \cdot \nabla \tau_i$$



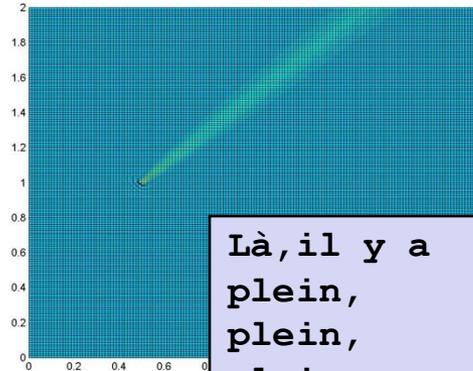
Facteur de stabilisation
Trop grand : diffusion numérique !
Trop petit : instable !

Trouver $U_j \in \mathbb{R}^n$ tel que

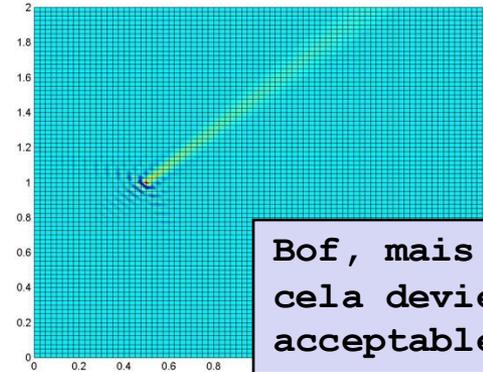
$$\sum_{j=1}^n \underbrace{\langle w_i \beta \cdot \nabla \tau_j + \epsilon \nabla w_i \cdot \nabla \tau_j \rangle}_{A_{ij}} U_j = \underbrace{\langle w_i f \rangle + \ll w_i g \gg_N}_{B_i}, \quad i = 1, \dots, n,$$



Non, là
c'est
instable



Là, il y a
plein,
plein,
plein
d'éléments



Bof, mais
cela devient
acceptable !

Et en payant le prix,
Galerkin fonctionne !

$$w_i = \tau_i + \zeta \beta \cdot \nabla \tau_i$$

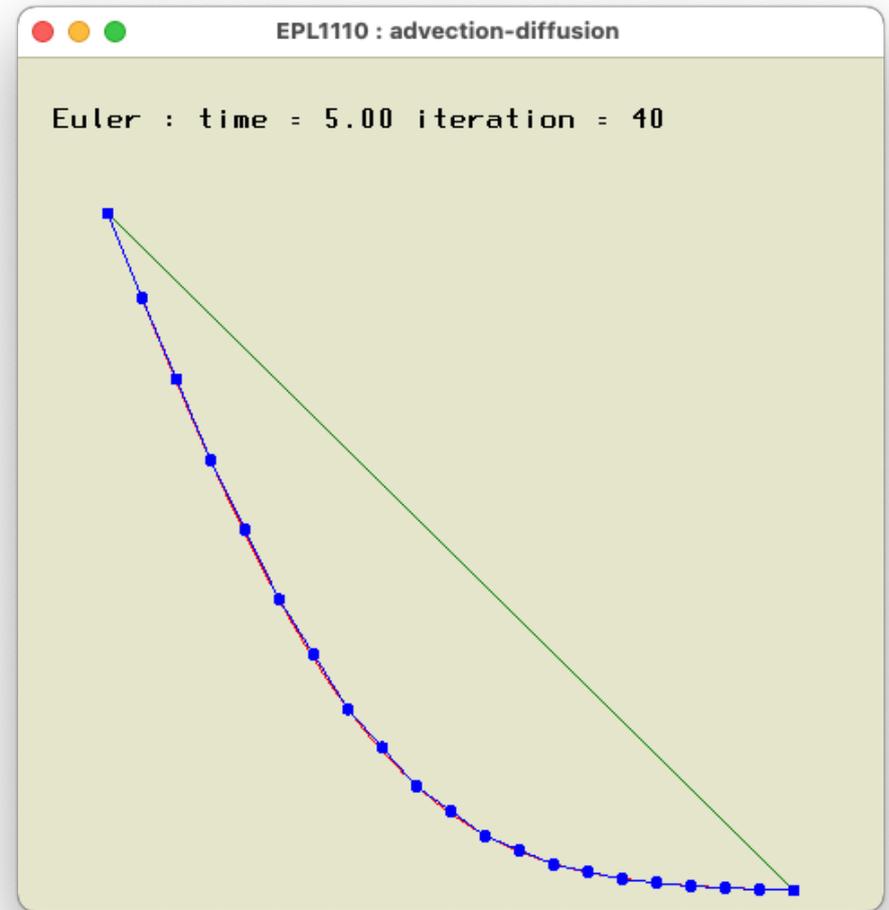
↑
Pas de stabilisation !
Zeta = 0 !

Trouver $U_j \in \mathbb{R}^n$ tel que

$$\sum_{j=1}^n \underbrace{\langle w_i \beta \cdot \nabla \tau_j + \epsilon \nabla w_i \cdot \nabla \tau_j \rangle}_{A_{ij}} U_j = \underbrace{\langle w_i f \rangle + \ll w_i g \gg_N}_{B_i}, \quad i = 1, \dots, n,$$

Et maintenant
introduisons
le temps...

$$\frac{\partial u}{\partial t} = \epsilon \frac{\partial^2 u}{\partial x^2}$$
$$u(0) = 1$$
$$u(1) = 0$$



```
epsilon = 0.01;  
L = 1
```

Différences finies (espace) Euler explicite (temps)

$$\left(\frac{U_i^{n+1} - U_i^n}{\Delta t}\right) = \epsilon \left(\frac{U_{i+1}^n - 2U_i^n + U_{i-1}^n}{(\Delta x)^2}\right)$$

En définissant $b = \frac{\epsilon \Delta t}{(\Delta x)^2}$,

$$U_i^{n+1} = U_i^n + b(U_{i+1}^n + U_{i-1}^n - 2U_i^n)$$

C'est une itération pour un vecteur qui doit converger vers la solution de régime
C'est quelque chose qu'on a déjà rencontré...

On intègre un système linéaire...

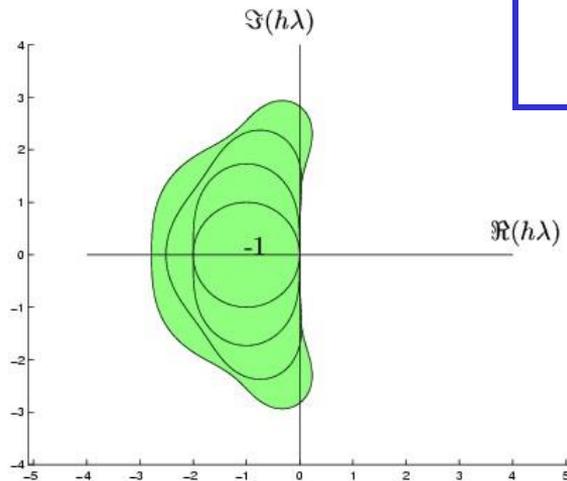
$$U_i^{n+1} = U_i^n + b(U_{i+1}^n + U_{i-1}^n - 2U_i^n)$$

En passant à une notation matricielle,

$$\begin{bmatrix} U_1^{n+1} \\ U_2^{n+1} \\ U_3^{n+1} \\ U_4^{n+1} \\ U_5^{n+1} \\ \vdots \\ U_m^{n+1} \end{bmatrix} = \begin{bmatrix} U_1^n \\ U_2^n \\ U_3^n \\ U_4^n \\ U_5^n \\ \vdots \\ U_m^n \end{bmatrix} + b \begin{bmatrix} -2 & 1 & & & & & & & \\ 1 & -2 & 1 & & & & & & \\ & & 1 & -2 & 1 & & & & \\ & & & & 1 & -2 & 1 & & \\ & & & & & & 1 & -2 & 1 \\ & & & & & & & & & 1 & -2 \end{bmatrix} \begin{bmatrix} U_1^n \\ U_2^n \\ U_3^n \\ U_4^n \\ U_5^n \\ \vdots \\ U_m^n \end{bmatrix}$$

En définissant adéquatement u_n et A ,

$$\mathbf{u}_{n+1} = \mathbf{u}_n + b\mathbf{A}\mathbf{u}_n$$



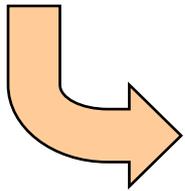
On résout le système linéaire défini par :

$$\mathbf{u}'(t) = \frac{\epsilon}{(\Delta x)^2} \mathbf{A}\mathbf{u}(t)$$

$$\Delta x = 0.1, \Delta t = 0.005$$

Euler explicite

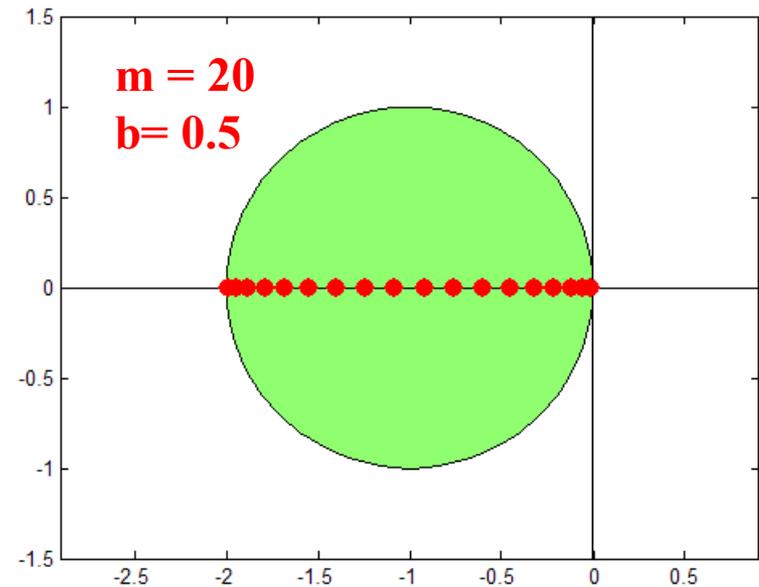
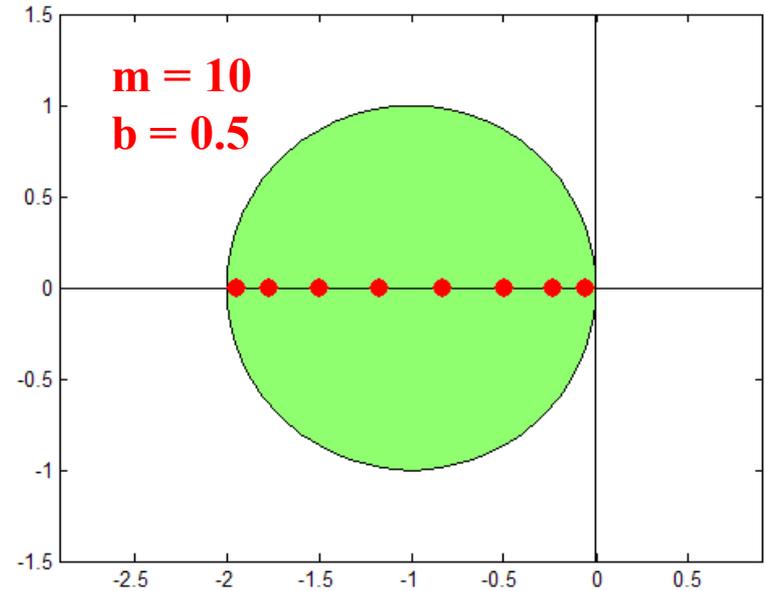
$$\mathbf{u}_{n+1} = \mathbf{u}_n + \underbrace{\frac{\epsilon \Delta t}{(\Delta x)^2}}_b \mathbf{A} \mathbf{u}_n$$



$$|1 + b\lambda_i| \leq 1$$

↑
Valeurs propres de
A

$$\Delta x = 0.05, \Delta t = 0.00125$$



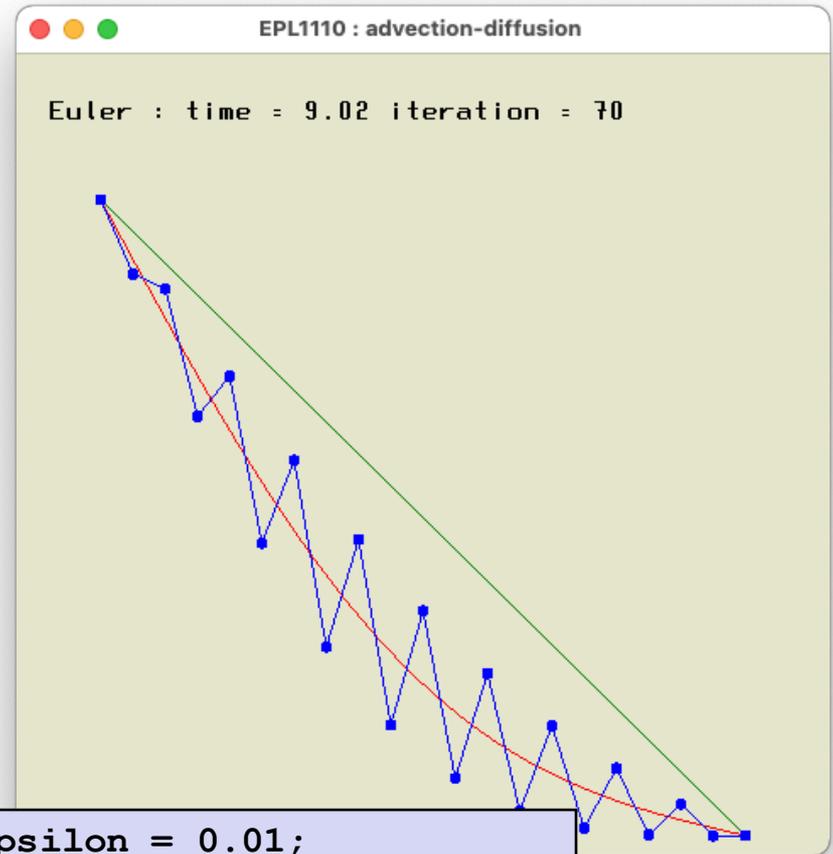
Condition de stabilité pour la méthode d'Euler explicite....

$$\beta = \frac{\epsilon \Delta t}{(\Delta x)^2} \leq \frac{1}{2}$$



$$\Delta t \leq \frac{(\Delta x)^2}{2\epsilon}$$

Courant, Friedrichs et Lewy (1928)



```
epsilon = 0.01;  
dt = h*h/(epsilon*1.94);
```

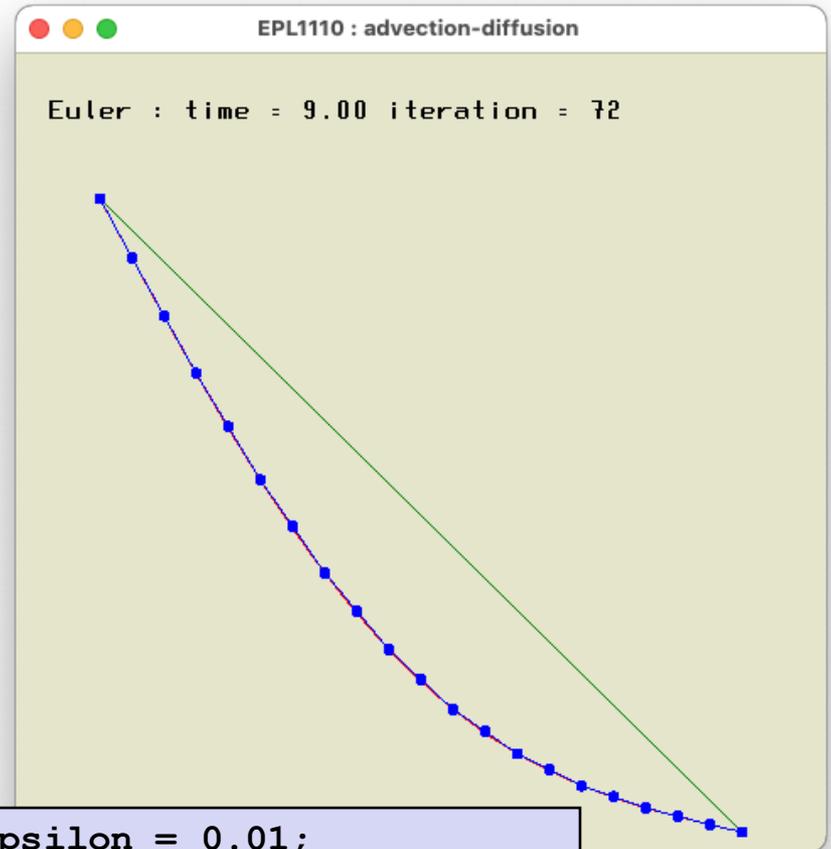
Condition de stabilité pour la méthode d'Euler explicite....

$$\beta = \frac{\epsilon \Delta t}{(\Delta x)^2} \leq \frac{1}{2}$$



$$\Delta t \leq \frac{(\Delta x)^2}{2\epsilon}$$

Courant, Friedrichs et Lewy (1928)



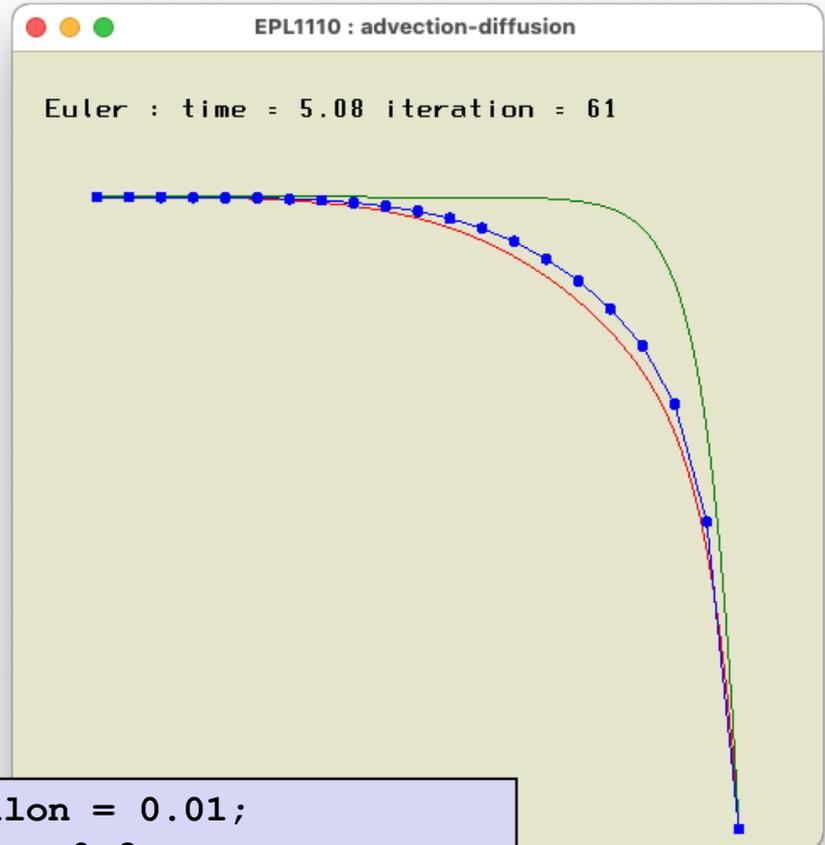
```
epsilon = 0.01;  
dt = h*h/(epsilon*2.0);
```

Et maintenant
introduisons
l'advection...

$$\frac{\partial u}{\partial t} + \beta \frac{\partial u}{\partial x} = \epsilon \frac{\partial^2 u}{\partial x^2}$$

$$u(0) = 1$$

$$u(1) = 0$$

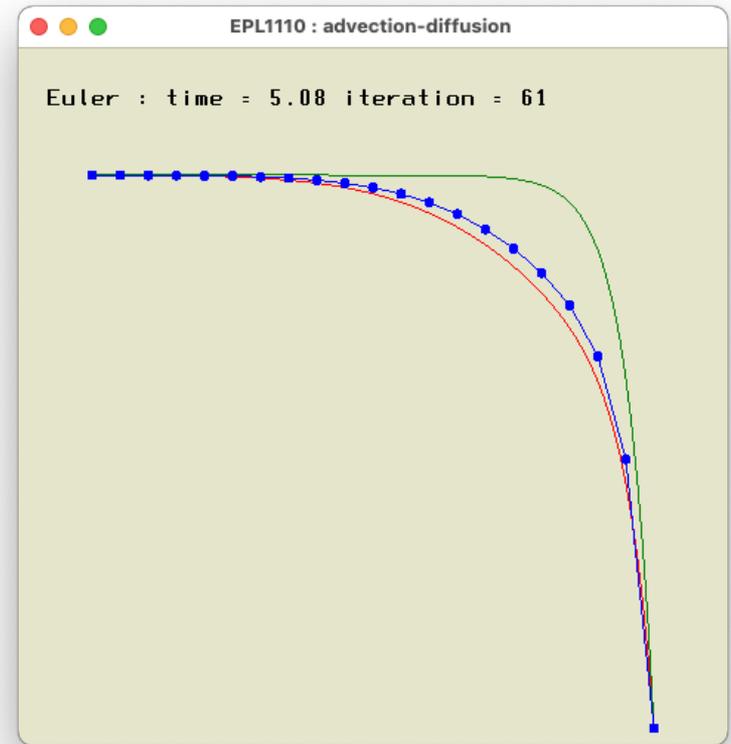


```
epsilon = 0.01;  
beta = 0.2;  
dt = h*h/(epsilon*3.0);
```

Et comment déduire le pas de temps ?

$$U_j^n = U^n e^{ikX_j}$$

Considérons une perturbation quelconque...



$$\begin{aligned} U_j^{n+1} &= U_j^n + \Delta t \left(\overbrace{\left((\zeta - 1) \frac{\beta}{2h} + \frac{\epsilon}{h^2} \right)}^a U_{j+1}^n + \overbrace{\left(-\zeta \frac{\beta}{h} - 2 \frac{\epsilon}{h^2} \right)}^b U_j^n + \overbrace{\left((\zeta + 1) \frac{\beta}{2h} + \frac{\epsilon}{h^2} \right)}^c U_{j-1}^n \right) \\ &= U_j^n \left(1 + \Delta t \left(a e^{ikh} + b + c e^{-ikh} \right) \right) \\ &= U_j^n \left(1 + \Delta t \left(\underbrace{(a+c)}_{-b} \cos kh + b + i \underbrace{(a-c)}_{-\beta/h} \sin kh \right) \right) \end{aligned}$$

Il faut que le module
 du facteur
 d'amplification
 soit inférieur
 à l'unité :-)

$$U = \left(1 + \Delta t \left(b - b \cos kh + b - i \frac{\beta}{h} \sin kh \right) \right)$$

$$\left| \left(1 + \Delta t b - \Delta t b \cos(kh) \right) - i \Delta t \left(\frac{\beta}{h} \sin(kh) \right) \right| \leq 1$$



$$1 + \Delta t^2 b^2 (1 - \cos(kh))^2 + 2b \Delta t (1 - \cos(kh)) + \Delta t^2 \frac{\beta^2}{h^2} \sin^2(kh) \leq 1$$

$$\Delta t^2 b^2 (1 - \cos(kh))^2 + 2b \Delta t (1 - \cos(kh)) + \Delta t^2 \frac{\beta^2}{h^2} (1 - \cos(kh))^2 \leq 0$$

$$\Delta t b^2 (1 - \cos(kh)) + 2b + \Delta t \frac{\beta^2}{h^2} (1 + \cos(kh)) \leq 0$$

On déduit finalement :

$$\Delta t \leq \frac{-2b}{(1 - \cos(kh))b^2 + (1 + \cos(kh))\frac{\beta^2}{h^2}}$$

$$\Delta t \leq \frac{2(\zeta\beta h + 2\epsilon)h^2}{(\zeta h\beta + 2\epsilon)^2 + \beta^2 h^2 + \cos(kh)(\beta^2 h^2 - (\zeta h\beta + 2\epsilon)^2)}$$

On conclut donc :

$$\Delta t \leq \min\left(\frac{\zeta h\beta + 2\epsilon}{\beta^2}, \frac{h^2}{\zeta h\beta + 2\epsilon}\right)$$

Notons que l'on obtient les résultats habituels $\Delta t \leq \frac{h}{\beta}$ pour $\epsilon = 0, \zeta = 1$ et $\Delta t \leq \frac{h^2}{2\epsilon}$ pour $\beta = 0$.

Pratiquement...