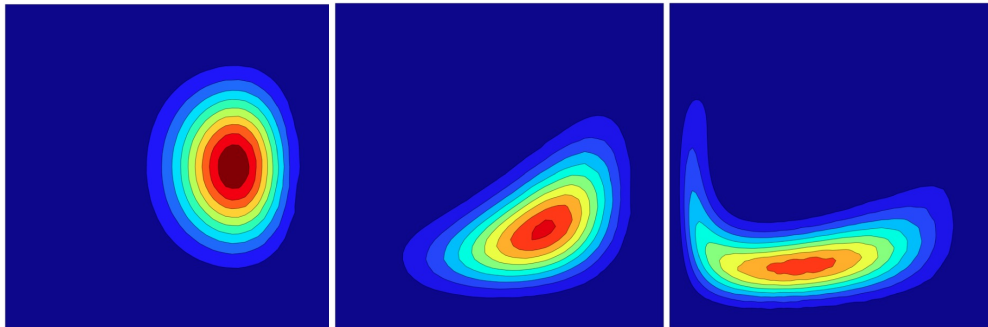
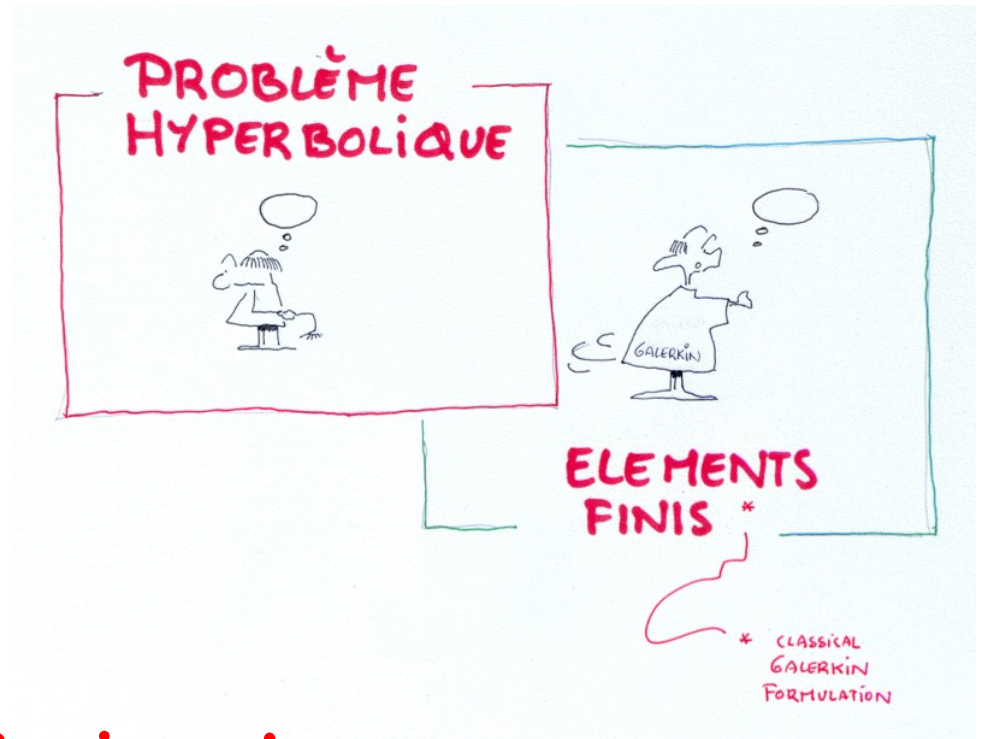
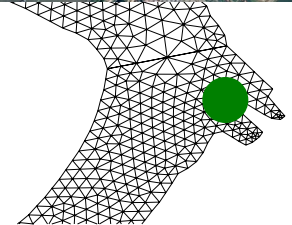
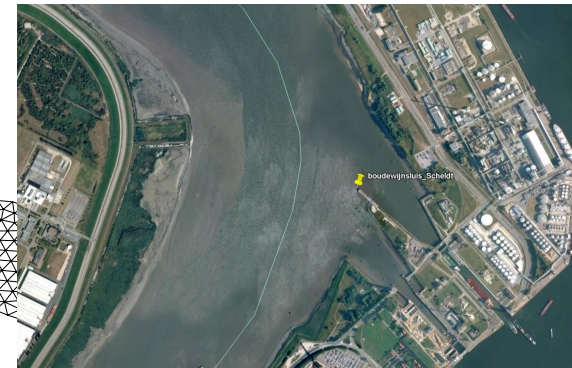
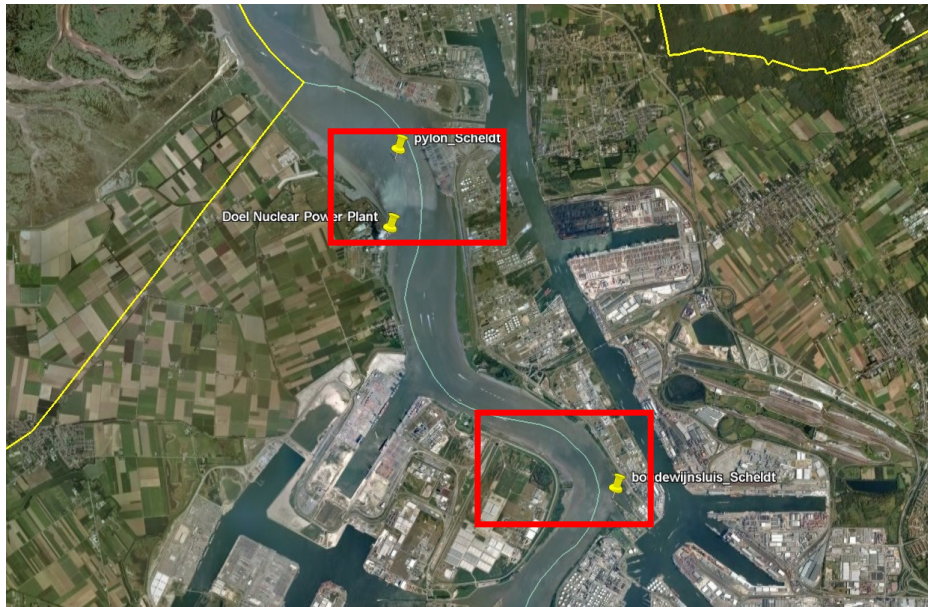
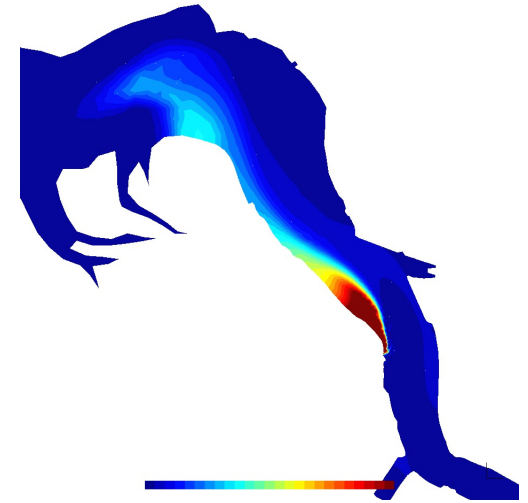
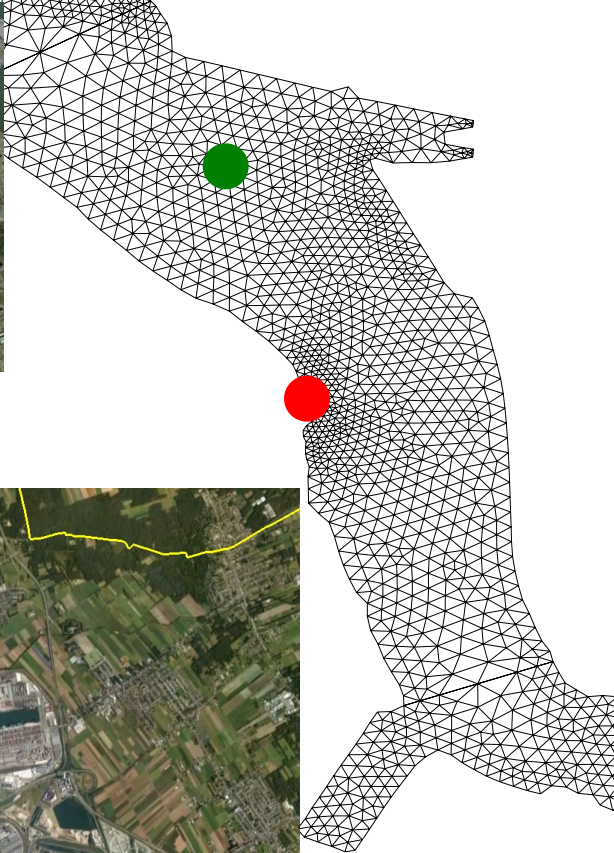


Galerkin, c'était donc optimal pour des équations elliptiques

Mais,
plus pour des
équations
d'advection diffusion !



Un petit exemple concret



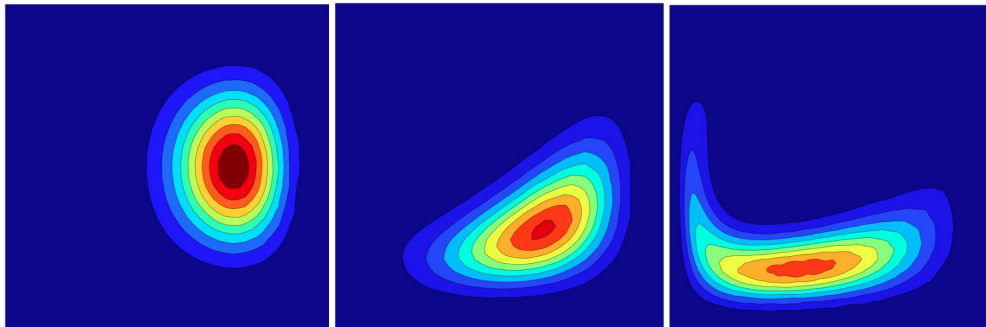
Diffusion et transport d'un traceur passif

MOYENNE DE LA CONCENTRATION SUR LA PROFONDEUR

COEFFICIENT DE DIFFUSION

$$\frac{\partial c}{\partial t} + \underbrace{\vec{u} \cdot \nabla c}_{\text{TERME DE TRANSPORT}} = \underbrace{\nabla \cdot (D \nabla c)}_{\text{TERME DE DIFFUSION}} + S$$

\vec{u} = VITESSE HORIZONTALE



C'est une équation parabolique du second ordre !

Ce n'est pas elliptique !

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2}$$

P_e PETIT

STATIONNAIRE

$$0 = k \frac{\partial^2 c}{\partial x^2}$$

ELL
2

$$v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2}$$

ELL
2

P_e GRAND

$$v \frac{\partial c}{\partial x} = 0$$

HYP
1

INSTATIONNAIRE

$$\frac{\partial c}{\partial t} = k \frac{\partial^2 c}{\partial x^2}$$

PARA
2

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = k \frac{\partial^2 c}{\partial x^2}$$

PARA
2

$$\frac{\partial c}{\partial t} + v \frac{\partial c}{\partial x} = 0$$

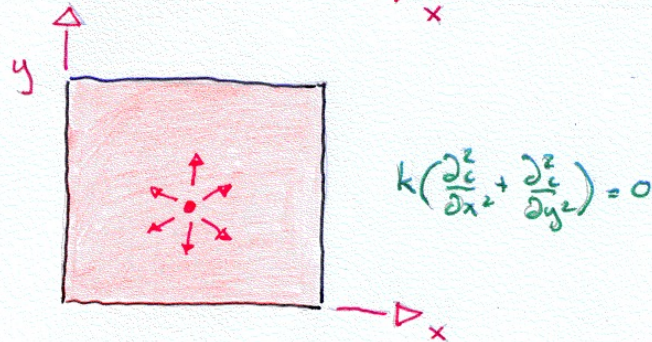
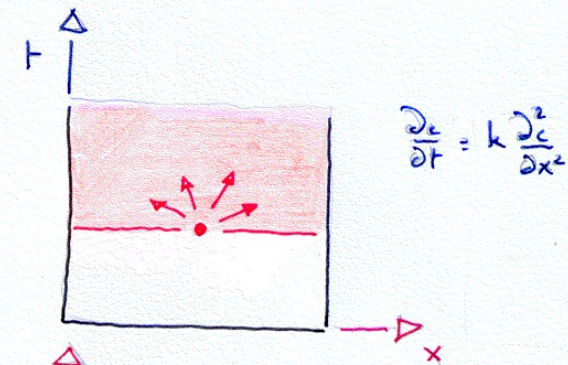
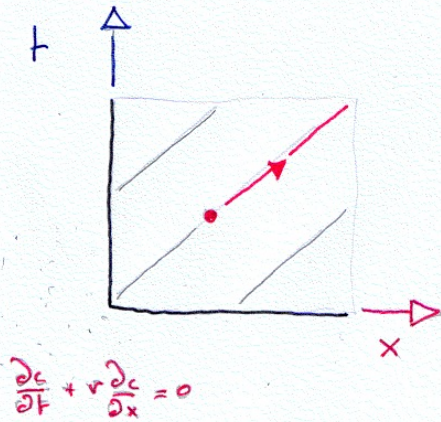
HYP
1

Le nombre de Péclet permet d'estimer l'importance du terme de transport par rapport à celui de la diffusion !

$$P_e = \frac{vL}{k}$$

PROBLEME BIEN POSE

→ CONDITIONS
AUX LIMITES

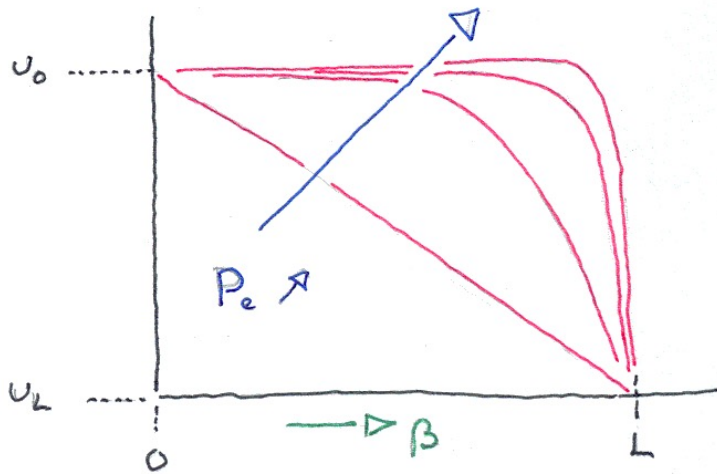


EQUATION D'ADVECTION - DIFFUSION

$$\beta \frac{du}{dx} - \epsilon \frac{d^2u}{dx^2} = 0$$

$$u(0) = u_0$$

$$u(L) = u_L$$

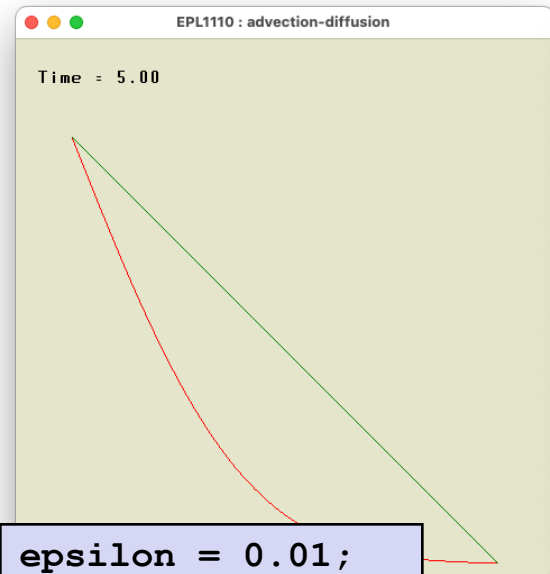


$$P_e = \frac{\beta L}{\epsilon}$$

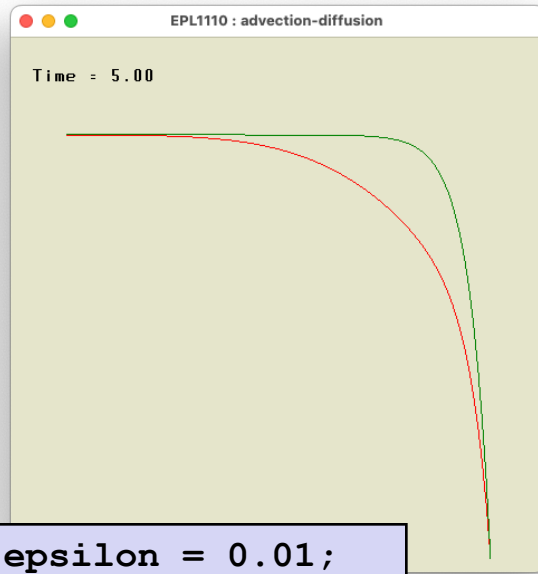
$$\frac{u - u_0}{u_L - u_0} = \frac{\exp\left(\frac{\beta x}{\epsilon}\right) - 1}{\exp\left(\frac{\beta L}{\epsilon}\right) - 1}$$

$P_e \times /L$

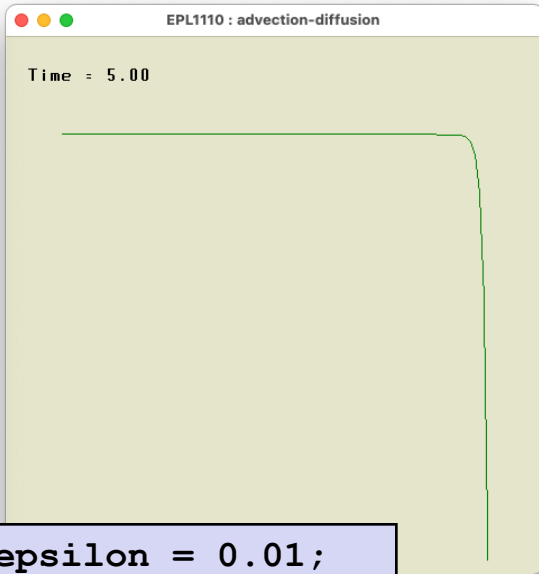
P_e



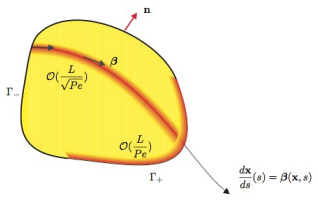
epsilon = 0.01;
beta = 0.0;



epsilon = 0.01;
beta = 0.2;



epsilon = 0.01;
beta = 1.0;



Trouver $u(\mathbf{x}) \in \mathcal{U}_s$ tel que

$$\beta \cdot \nabla u - \nabla \cdot (\epsilon \nabla u) = f, \quad \forall \mathbf{x} \in \Omega,$$

$$\mathbf{n} \cdot (\epsilon \nabla u) = g, \quad \forall \mathbf{x} \in \Gamma_N,$$


$$u = t, \quad \forall \mathbf{x} \in \Gamma_D,$$

Advection-diffusion

EQUATION DE TRANSPORT

$$\frac{du}{dx} = f$$

$$u(0) = u_0$$

$$u \approx u_h = \sum_i U_i \tau_i(x)$$


GALERKIN

? U_i TELS QUE

$$\langle \tau_i, \Gamma_h \rangle = 0$$

$$\sum_j \underbrace{\langle \tau_i, \tau_j, x \rangle}_{A_{ij}} U_j = \underbrace{\langle \tau_i, f \rangle}_{B_i}$$

≠ MATRICE DEFINIE POSITIVE !

$$\frac{du}{dx} = f$$

GALERKIN

$$\sum_j A_{ij} U_j = B_i$$

BUBNOV - GALERKIN

DIFFERENCES FINIES CENTREES

$$U_{j+1} - U_{j-1} = B_j \cdot 2\Delta x$$



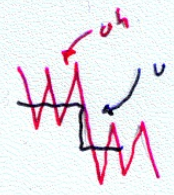
PROBLEME DE MINIMISATION

$$f(x) = \sin(x)$$

$$f(x) = \uparrow$$

OK

Bout



PETROV-GALERKIN

? U_j TELS QUE

$$\langle \tau_{j,x} |^h \rangle = 0$$

0 → INTEGRATION LE LONG DES CARACTERISTIQUES

DIFFERENCES FINIES AMONT

$$U_{j+1} - U_j = B_j \Delta x$$

$$\sum_j \underbrace{\langle \tau_{i,x} | \tau_{j,x} \rangle}_{A_{ij}} U_j = \underbrace{\langle \tau_{i,x} | f \rangle}_{B_i}$$

MATRICE DEFINIE POSITIVE

1 CONDITION AUX LIMITES !

$\frac{du}{dx} = f$

A ÉTÉ REMPLACÉ PAR $\frac{d^2 u}{dx^2} = \frac{df}{dx}$


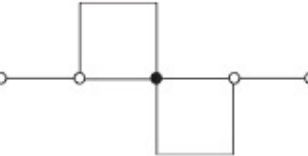

2 CONDITIONS AUX LIMITES !

HIC

En bref :-)

$$\frac{du}{dx} = f,$$

$$u(0) = 0,$$

<p>Galerkin $w_i = \tau_i$</p> 	<p><i>Différences finies centrées</i></p> <p>Simple et donc tentant... Oscillations numériques si f n'est pas lisse !</p> $\frac{U_{i+1} - U_{i-1}}{2h} = \frac{F_{i+1} + 4F_i + F_{i-1}}{6},$
<p>Petrov-Galerkin $w_i = \tau_{i,x}$</p> 	<p><i>Différences finies centrées d'ordre deux</i></p> <p>Mathématiquement, tentant Condition frontière parasite !</p> $\frac{U_{i+1} - 2U_i + U_{i-1}}{h^2} = \frac{F_{i+1} - F_{i-1}}{2h},$
<p>Petrov-Galerkin $w_i = \tau_{i-1}^{cst}$</p> 	<p><i>Différences finies amont</i></p> <p>Quasiment optimal... Correspond à une intégration le long de la caractéristique, Pas d'oscillation numérique</p> $\frac{U_i - U_{i-1}}{h} = \frac{F_{i+1} + F_{i-1}}{2},$

PETROV-GALERKIN

$$\langle (\tau_c + \zeta \tau_{c,x}) (u_x^h - \epsilon u_{xx}^h - f) \rangle = 0$$

Γ^h

$\hat{\tau}_c$

How TO SELECT ζ ?

2D

$$\hat{\tau}_c = \tau_c + \zeta \beta \cdot \nabla \tau_c$$

STREAMLINE UPWINDING

$$\sum_j \left(\begin{array}{l} \zeta \langle \tau_{c,x} \tau_{j,x} \rangle \\ \epsilon \langle \tau_{c,x} \tau_{j,xx} \rangle \end{array} - \begin{array}{l} \epsilon \zeta \langle \tau_{c,x} \tau_{j,xx} \rangle \\ \langle \tau_c \tau_{j,x} \rangle \end{array} \right) U_j = \dots$$

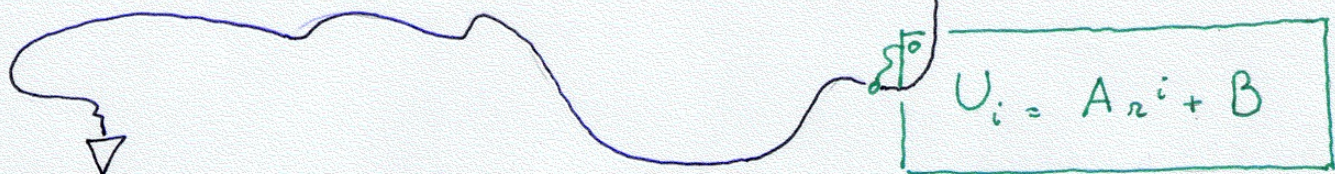


DIFF. CENTRÉES

$$\beta \frac{U_{i+1} - U_{i-1}}{2h} = \varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$U_0 = u_0$
 $U_N = u_L$

EQUATION AUX RECURRENCES !



$$\cancel{A} r^{i-1} \frac{\beta h}{2\varepsilon} (r^2 - 1) = \cancel{A} r^{i-1} (r^2 - 2r + 1)$$

$$0 = \left(\frac{1 - Pe^h/2}{2} \right) r^2 - r + \left(\frac{1 + Pe^h/2}{2} \right)$$

$$\Delta \frac{Pe^h}{2}$$

PECLET DE MAILLE

$$r = \frac{1 \pm \sqrt{1 - (1 + Pe^h/2)(1 - Pe^h/2)}}{(1 - Pe^h/2)}$$

$$r = \frac{1 + Pe^h/2}{1 - Pe^h/2}$$

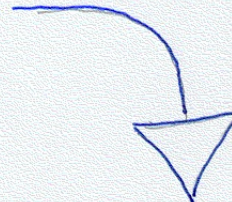
REJECT $r=1$ OF COURSE !

$$\frac{U_i - v_0}{v_h - v_0} = \frac{\left(\frac{1 + P_e h/2}{1 - P_e h/2} \right)^i - 1}{\left(\frac{1 + P_e h/2}{1 - P_e h/2} \right)^N - 1}$$

$$\approx \exp(P_e h) \cdot N$$

$$\approx \exp\left(\frac{\beta h N}{\epsilon}\right)$$

$$P_e$$



$\frac{P_e h}{2} < 1$
 TO AVOID
 OSCILLATORY
 BEHAVIOUR

[SCHAUM p 551]

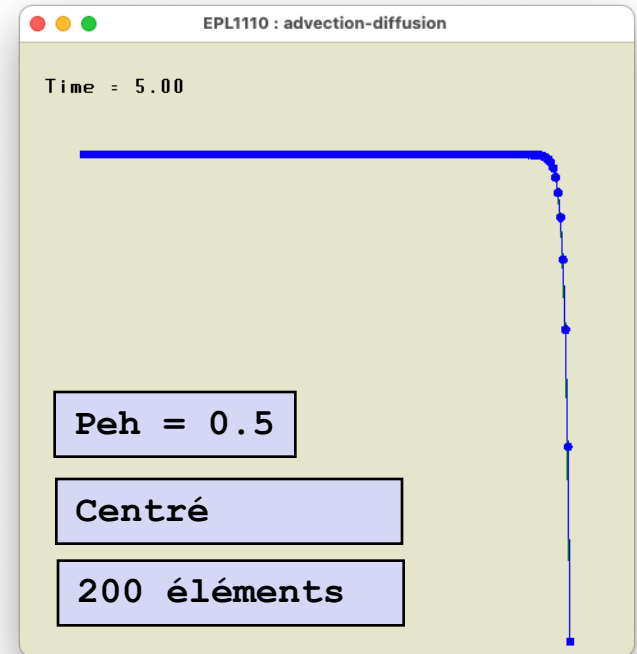
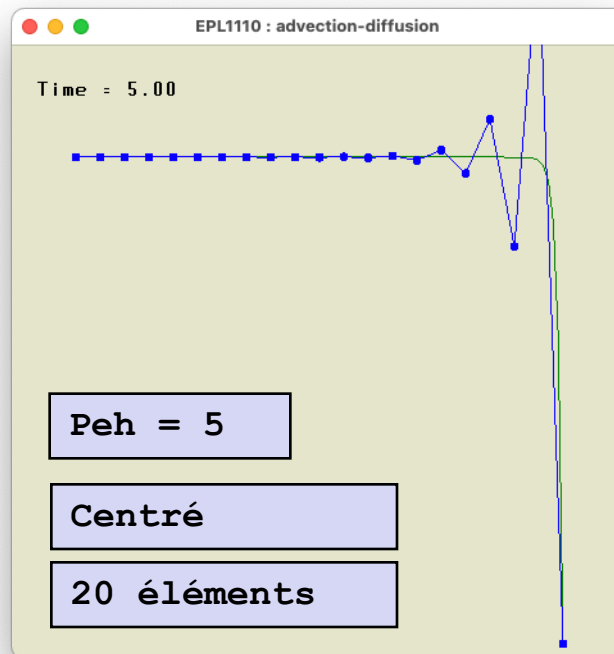
$$\frac{x}{e^x - 1} \approx 1 - \frac{x}{2}$$

$$\left(1 + \frac{x}{2}\right) = e^x \left(1 - \frac{x}{2}\right)$$

Galerkin converge si on raffine le maillage suffisamment !

`epsilon = 0.01;`
`beta = 1.0;`

L'équation d'advection-diffusion est formellement une équation elliptique et donc c'était prévisible par la théorie !



UPWIND DIFF.

$$\beta \frac{U_i - U_{i-1}}{h} = \varepsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$$U_0 = u_0$$

$$U_N = u_L$$

$\cancel{A} r^{i-1} \underbrace{\frac{\beta h}{\varepsilon}}_{\triangleq Pe^h} (\pi - 1) = \cancel{A} r^{i-1} (\pi^2 - 2\pi + 1)$

$$0 = \frac{\pi^2}{2} - (1 + Pe^h/2)\pi + \frac{(1 + Pe^h)}{2}$$

$$\pi = \frac{(1 + Pe^h/2) \pm \sqrt{(1 + Pe^h/2)^2 - (1 + Pe^h)}}{1}$$

$$= 1 + Pe^h$$

$$\frac{U_i - u_0}{u_L - u_0} = \frac{(1 + Pe^h)^i - 1}{(1 + Pe^h)^N - 1}$$

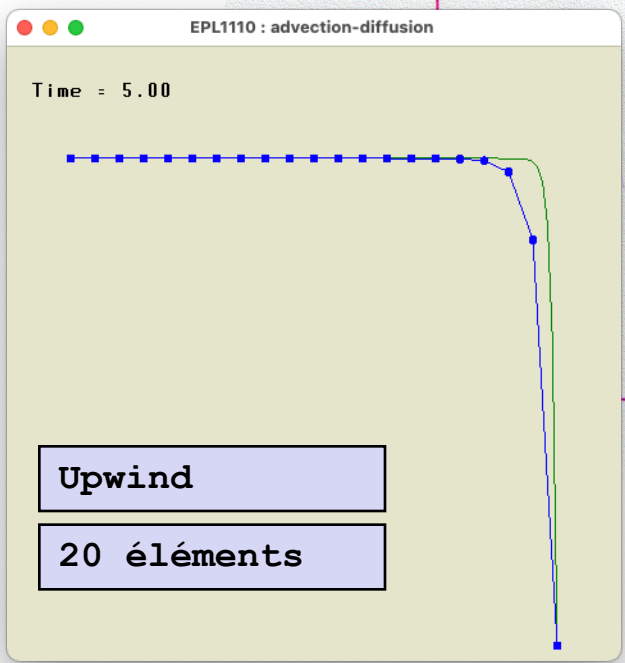
$(1 + Pe^h) > 0$
 $\forall h$
 NO OSCILLATIONS

BUT...

NUMERICAL DIFFUSION

$$\beta \frac{U_i - U_{i-1}}{h} = \epsilon \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$

$$\beta \frac{U_{i+1} - U_{i-1}}{2h} - \underbrace{\frac{\beta h}{2}}_{\text{NUMERICAL DIFFUSIVITY}} \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2}$$



HYBRID SCHEME

$$(1-\zeta)\beta \frac{U_{i+1}-U_{i-1}}{2h} + \zeta\beta \frac{U_i-U_{i-1}}{2h} = \varepsilon \frac{U_{i+1}-2U_i+U_{i-1}}{h^2}$$

$$0 = \left(1 - \frac{(1-\zeta)P_e h/2}{2}\right) \pi^2 - \left(1 + \zeta P_e h/2\right) \pi + \left(1 + \frac{(1-\zeta)P_e h/2}{2} + \zeta P_e h/2\right)$$

$$\pi = \frac{(1 + \zeta P_e h/2) \pm \sqrt{\begin{matrix} (1 + \zeta P_e h/2)^2 \\ - (1 - (1-\zeta)P_e h/2) \\ (1 + (1-\zeta)P_e h/2) \end{matrix}}}{(1 - (1-\zeta)P_e h/2)}$$

} = $P_e h/2$

$$\pi = \frac{1 + (1 + \zeta) P_e h/2}{1 - (1 - \zeta) P_e h/2}$$

HOW TO
SELECT ζ ?

$$U_i = u(ih)$$

$$\left(\frac{1 + (1 + \zeta) P_e h/2}{1 - (1 - \zeta) P_e h/2} \right)^i = \exp\left(\frac{\beta h}{\varepsilon} i\right)$$

$$\left(\exp(P_e h) \right)^i$$

$$\left(1 + P_e h/2\right) - \zeta P_e h/2 = \exp(P_e) \left(\left(1 - P_e h/2\right) + \zeta P_e h/2 \right)$$

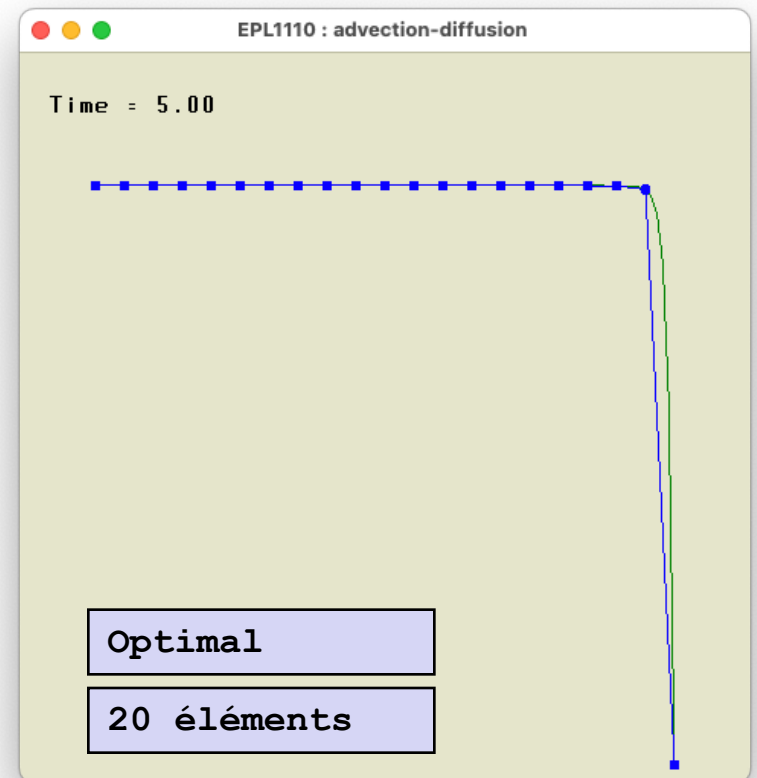
$$\begin{aligned}
 \zeta \frac{P_e h}{2} (1 - \exp(-P_e)) &= \exp(P_e^h) \left(1 - \frac{P_e^h}{2}\right) - \left(1 + \frac{P_e^h}{2}\right) \\
 &\downarrow \\
 \zeta &= \frac{\exp(P_e^h) \left(\frac{2}{P_e^h} - 1\right) - \left(\frac{2}{P_e^h} + 1\right)}{(1 - \exp(P_e^h))} \\
 &\downarrow \\
 &= \underbrace{-\frac{(1 + \exp(P_e^h))}{(1 - \exp(P_e^h))}}_{\coth(P_e^h/2)} - \frac{2}{P_e^h}
 \end{aligned}$$

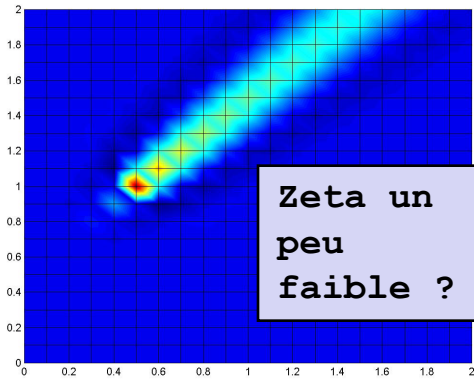
$$\boxed{\zeta = \coth\left(\frac{P_e^h}{2}\right) - \frac{2}{P_e^h}} \quad \square$$

On a trouvé
la méthode parfaite
pour des équations
unidimensionnelles !

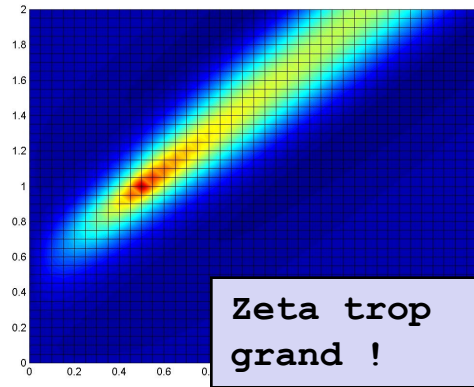
$$\zeta = \coth\left(\frac{Pe^h}{2}\right) - \frac{2}{Pe^h}$$

$$\begin{aligned}\beta \frac{du}{dx} - \epsilon \frac{d^2u}{dx^2} &= 0, \\ u(0) &= u_0, \\ u(L) &= u_L,\end{aligned}$$

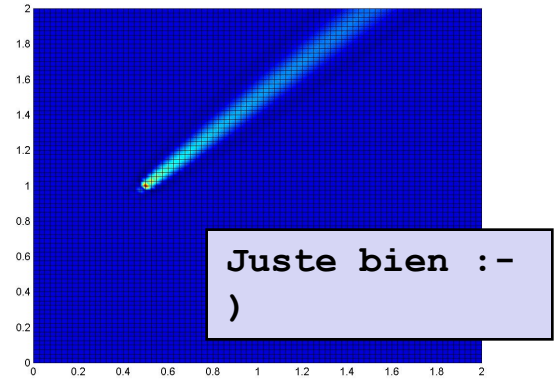




Zeta un peu faible ?



Zeta trop grand !



Juste bien :-)
)

En extrapolant
aux dimensions
supérieures...

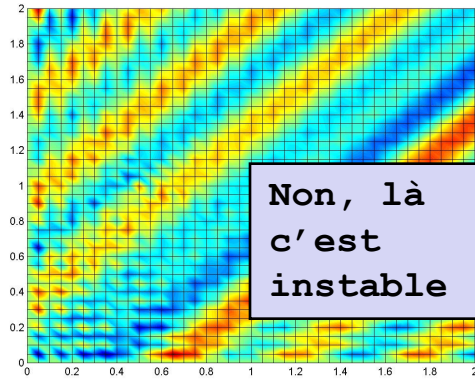
$$w_i = \tau_i + \zeta \beta \cdot \nabla \tau_i$$



Facteur de stabilisation
Trop grand : diffusion numérique !
Trop petit : instable !

Trouver $U_j \in \mathbb{R}^n$ tel que

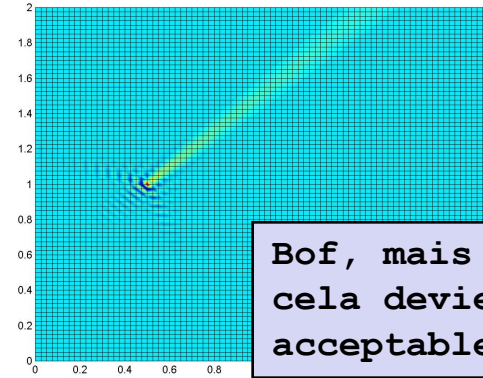
$$\sum_{j=1}^n \underbrace{\langle w_i \beta \cdot \nabla \tau_j + \epsilon \nabla w_i \cdot \nabla \tau_j \rangle}_{A_{ij}} U_j = \underbrace{\langle w_i f \rangle + \ll w_i g \gg_N}_{B_i}, \quad i = 1, \dots, n,$$



Non, là
c'est
instable



Là, il y a
plein,
plein,
plein
d'éléments



Bof, mais
cela devient
acceptable !

Et en payant le prix,
Galerkin fonctionne !

$$w_i = \tau_i + \zeta \beta \cdot \nabla \tau_i$$



*Pas de stabilisation !
Zeta = 0 !*

Trouver $U_j \in \mathbb{R}^n$ tel que

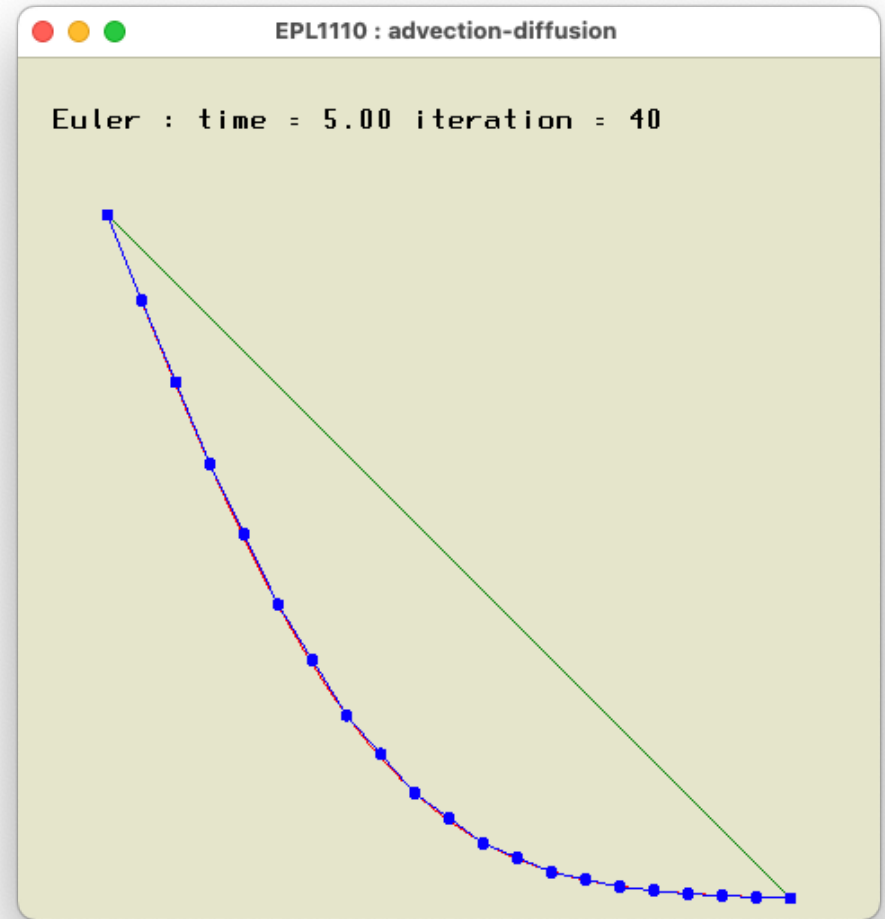
$$\sum_{j=1}^n \underbrace{\langle w_i \beta \cdot \nabla \tau_j + \epsilon \nabla w_i \cdot \nabla \tau_j \rangle}_{A_{ij}} U_j = \underbrace{\langle w_i f \rangle + \ll w_i g \gg_N}_{B_i}, \quad i = 1, \dots, n,$$

Et maintenant
introduisons
le temps...

$$\frac{\partial u}{\partial t} = \epsilon \frac{\partial^2 u}{\partial x^2}$$

$$u(0) = 1$$

$$u(1) = 0$$



```
epsilon = 0.01;  
L = 1
```

Différences finies (espace) Euler explicite (temps)

$$\left(\frac{U_i^{n+1} - U_i^n}{\Delta t}\right) = \epsilon \left(\frac{U_{i+1}^n - 2U_i^n + U_{i-1}^n}{(\Delta x)^2}\right)$$

En définissant $b = \frac{\epsilon \Delta t}{(\Delta x)^2}$,

$$U_i^{n+1} = U_i^n + b(U_{i+1}^n + U_{i-1}^n - 2U_i^n)$$

C'est une itération pour un vecteur qui doit converger vers la solution de régime
C'est quelque chose qu'on a déjà rencontré...

On intègre un système linéaire...

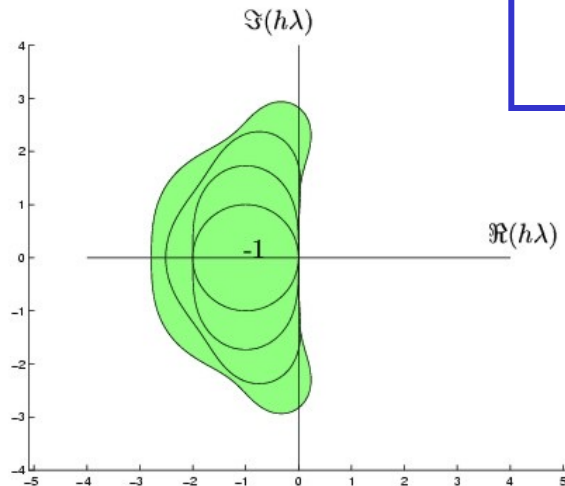
$$U_i^{n+1} = U_i^n + b(U_{i+1}^n + U_{i-1}^n - 2U_i^n)$$

En passant à une notation matricielle,

$$\begin{bmatrix} U_1^{n+1} \\ U_2^{n+1} \\ U_3^{n+1} \\ U_4^{n+1} \\ U_5^{n+1} \\ \vdots \\ U_m^{n+1} \end{bmatrix} = \begin{bmatrix} U_1^n \\ U_2^n \\ U_3^n \\ U_4^n \\ U_5^n \\ \vdots \\ U_m^n \end{bmatrix} + b \begin{bmatrix} -2 & 1 & & & & & & & \\ 1 & -2 & 1 & & & & & & \\ & 1 & -2 & 1 & & & & & \\ & & 1 & -2 & 1 & & & & \\ & & & 1 & -2 & 1 & & & \\ & & & & 1 & -2 & 1 & & \\ & & & & & & & 1 & -2 \\ & & & & & & & & & 1 & -2 \end{bmatrix} \begin{bmatrix} U_1^n \\ U_2^n \\ U_3^n \\ U_4^n \\ U_5^n \\ \vdots \\ U_m^n \end{bmatrix}$$

En définissant adéquatement u_n et A ,

$$\mathbf{u}_{n+1} = \mathbf{u}_n + b\mathbf{A}\mathbf{u}_n$$



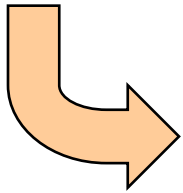
On résout le système linéaire défini par :

$$\mathbf{u}'(t) = \frac{\epsilon}{(\Delta x)^2} \mathbf{A}\mathbf{u}(t)$$

$$\Delta x = 0.1, \Delta t = 0.005$$

Euler explicite

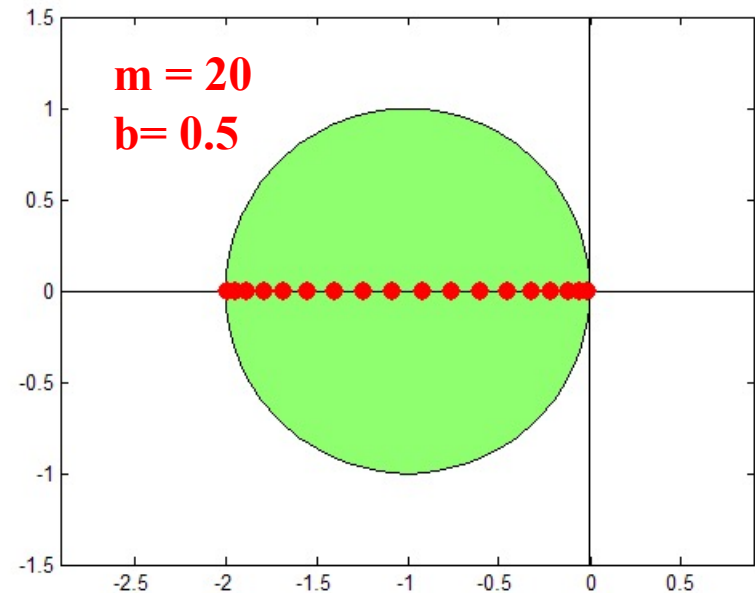
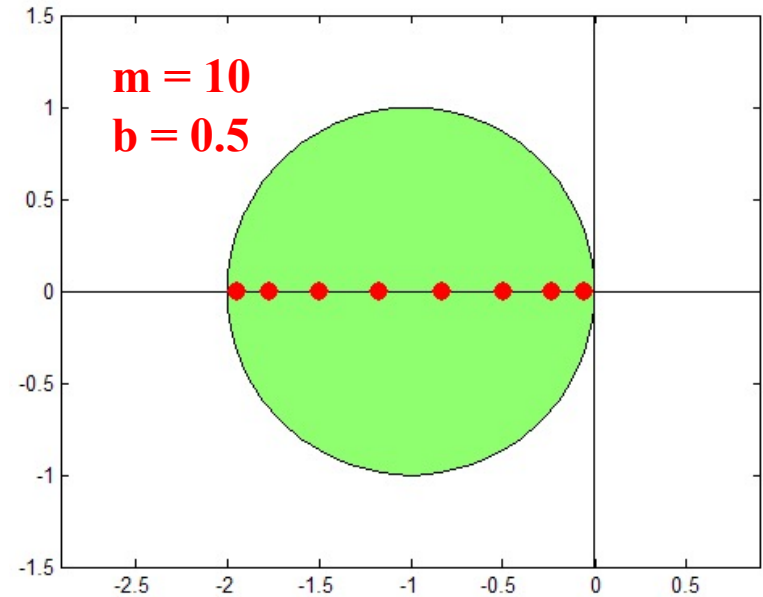
$$\mathbf{u}_{n+1} = \mathbf{u}_n + \underbrace{\frac{\epsilon \Delta t}{(\Delta x)^2}}_b \mathbf{A} \mathbf{u}_n$$



$$|1 + b\lambda_i| \leq 1$$

↑
Valeurs propres de
A

$$\Delta x = 0.05, \Delta t = 0.00125$$



Condition de stabilité pour la méthode d'Euler explicite....

$$\beta = \frac{\epsilon \Delta t}{(\Delta x)^2} \leq \frac{1}{2}$$

$$\Delta t \leq \frac{(\Delta x)^2}{2\epsilon}$$

Courant, Friedrichs et Lewy (1928)



```
epsilon = 0.01;  
dt = h*h/(epsilon*1.94);
```

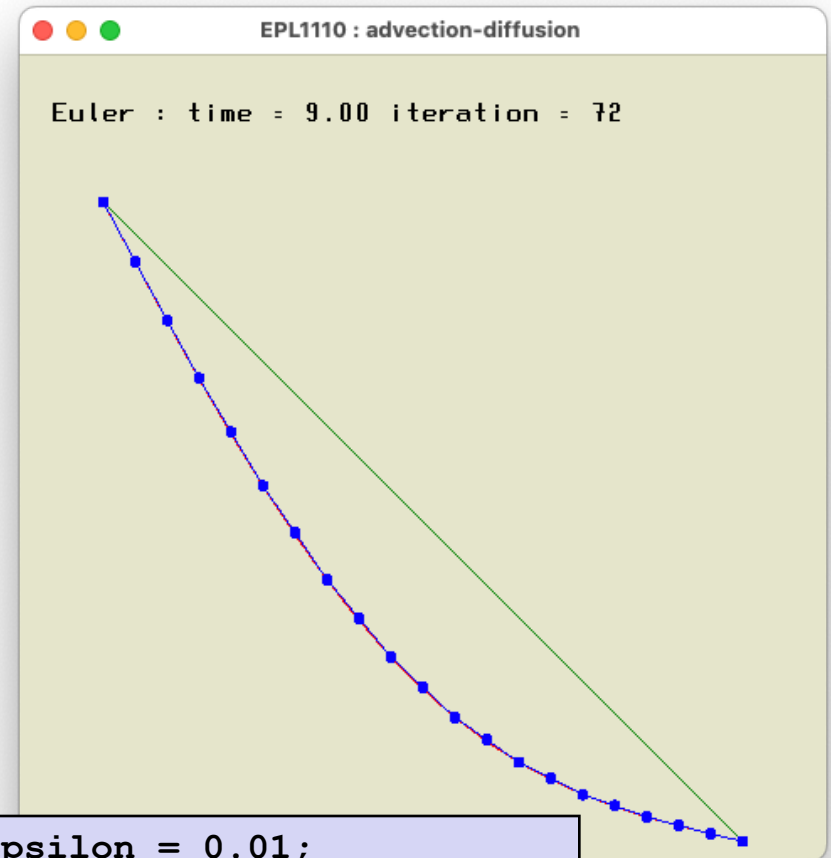
Condition de stabilité pour la méthode d'Euler explicite....

$$\beta = \frac{\epsilon \Delta t}{(\Delta x)^2} \leq \frac{1}{2}$$



$$\Delta t \leq \frac{(\Delta x)^2}{2\epsilon}$$

Courant, Friedrichs et Lewy (1928)



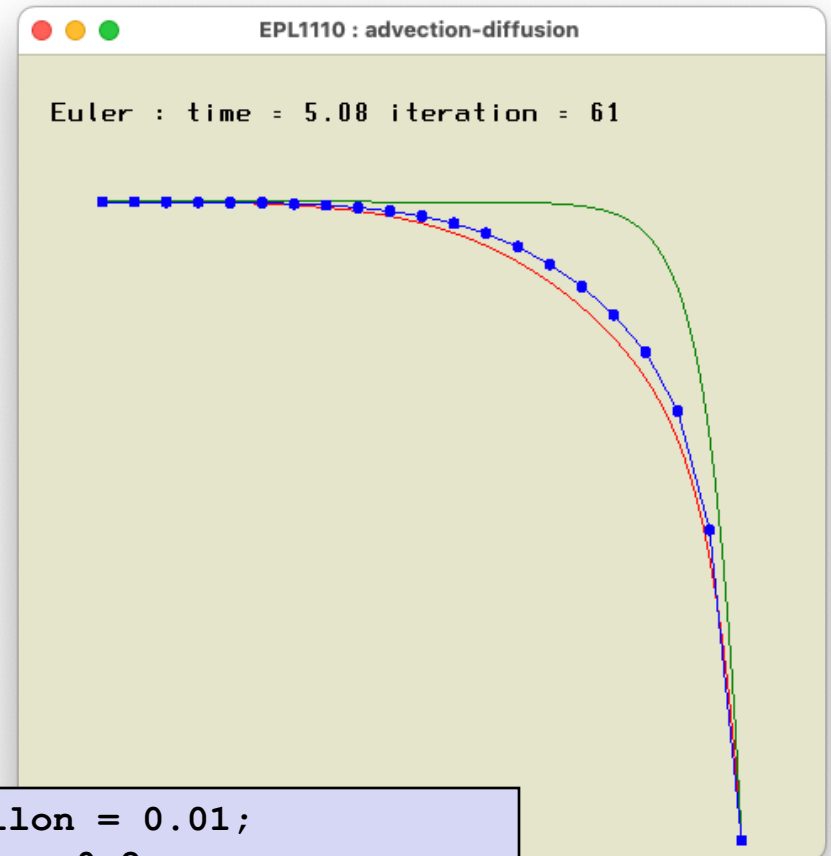
```
epsilon = 0.01;  
dt = h*h/(epsilon*2.0);
```

Et maintenant
introduisons
l'advection...

$$\frac{\partial u}{\partial t} + \beta \frac{\partial u}{\partial x} = \epsilon \frac{\partial^2 u}{\partial x^2}$$

$$u(0) = 1$$

$$u(1) = 0$$

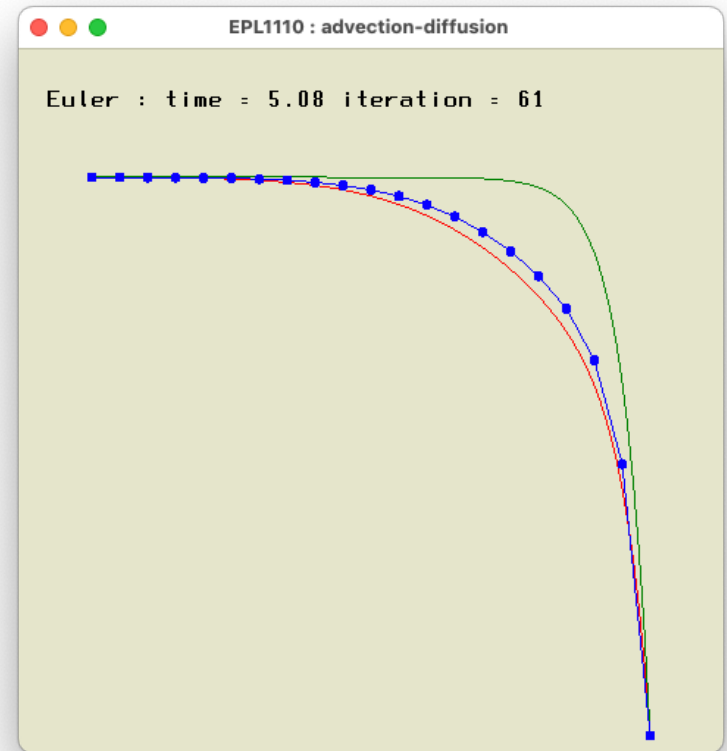


```
epsilon = 0.01;  
beta = 0.2;  
dt = h*h/(epsilon*3.0);
```


Et comment déduire le pas de temps ?

$$U_j^n = U^n e^{ikX_j}$$

Considérons une perturbation quelconque...



$$\begin{aligned} U_j^{n+1} &= U_j^n + \Delta t \left(\overbrace{\left((\zeta - 1) \frac{\beta}{2h} + \frac{\epsilon}{h^2} \right)}^a U_{j+1}^n + \overbrace{\left(-\zeta \frac{\beta}{h} - 2 \frac{\epsilon}{h^2} \right)}^b U_j^n + \overbrace{\left((\zeta + 1) \frac{\beta}{2h} + \frac{\epsilon}{h^2} \right)}^c U_{j-1}^n \right) \\ &= U_j^n \left(1 + \Delta t \left(a e^{ikh} + b + c e^{-ikh} \right) \right) \\ &= U_j^n \left(1 + \Delta t \left(\underbrace{(a+c)}_{-b} \cos kh + b + i \underbrace{(a-c)}_{-\beta/h} \sin kh \right) \right) \end{aligned}$$

Il faut que le module
du facteur
d'amplification
soit inférieur
à l'unité :-)

$$U = \left(1 + \Delta t \left(b - b \cos kh + b - i \frac{\beta}{h} \sin kh \right) \right)$$

$$\left| \left(1 + \Delta t b - \Delta t b \cos(kh) \right) - i \Delta t \left(\frac{\beta}{h} \sin(kh) \right) \right| \leq 1$$



$$1 + \Delta t^2 b^2 (1 - \cos(kh))^2 + 2b\Delta t(1 - \cos(kh)) + \Delta t^2 \frac{\beta^2}{h^2} \sin^2(kh) \leq 1$$

$$\Delta t^2 b^2 (1 - \cos(kh))^2 + 2b\Delta t(1 - \cos(kh)) + \Delta t^2 \frac{\beta^2}{h^2} (1 - \cos(kh))^2 \leq 0$$

$$\Delta t b^2 (1 - \cos(kh)) + 2b + \Delta t \frac{\beta^2}{h^2} (1 + \cos(kh)) \leq 0$$

On déduit finalement :

$$\Delta t \leq \frac{-2b}{(1 - \cos(kh))b^2 + (1 + \cos(kh))\frac{\beta^2}{h^2}}$$

$$\Delta t \leq \frac{2(\zeta\beta h + 2\epsilon)h^2}{(\zeta h\beta + 2\epsilon)^2 + \beta^2 h^2 + \cos(kh)(\beta^2 h^2 - (\zeta h\beta + 2\epsilon)^2)}$$

On conclut donc :

$$\Delta t \leq \min\left(\frac{\zeta h\beta + 2\epsilon}{\beta^2}, \frac{h^2}{\zeta h\beta + 2\epsilon}\right)$$

Notons que l'on obtient les résultats habituels $\Delta t \leq \frac{h}{\beta}$ pour $\epsilon = 0, \zeta = 1$ et $\Delta t \leq \frac{h^2}{2\epsilon}$ pour $\beta = 0$.

Pratiquement...